

# To Adapt or Not To Adapt

## The Power and Limits of Adaptive Sensing

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# Compressive Sensing

$y = Ax + z$

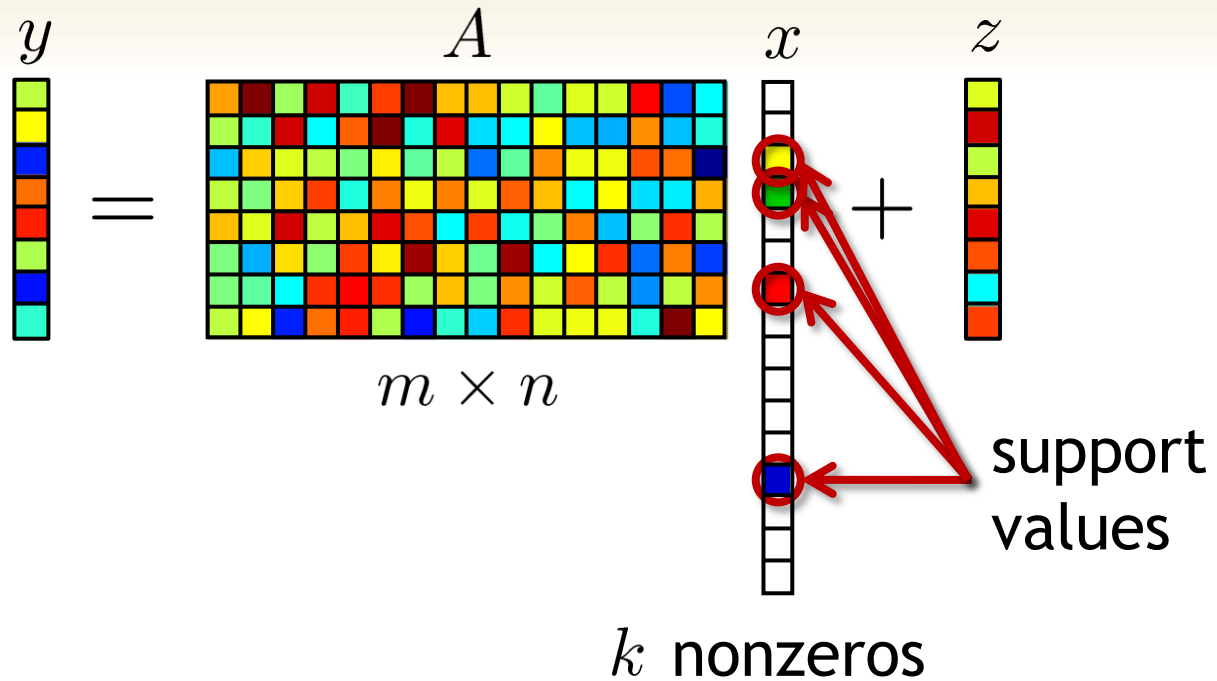
$m \times n$   
 $m \ll n$

$n \times 1$   
 $k$ -sparse

When (and how well) can we estimate  $x$  from the measurements  $y$ ?

# **Review of Nonadaptive Compressive Sensing**

# Compressive Sensing



- How should we design  $A$  to ensure that  $y$  contains as much information about  $x$  as possible?
- What algorithms do we have for recovering  $x$  from  $y$ ?

# How To Design $A$ ?

Prototypical sensing model:

$$y = Ax + z \quad z \sim \mathcal{N}(0, \sigma^2 I)$$

- Constrain  $A$  to have unit-norm rows
- Pick  $A$  at *random!*
  - i.i.d. Gaussian entries (with variance  $1/n$ )
  - random rows from a unitary matrix
- As long as  $m = O(k \log(n/k))$ , with high probability a random  $A$  will satisfy the *restricted isometry property*
- Deep connections with *Johnson-Lindenstrauss Lemma*
  - see Baraniuk, Davenport, DeVore, and Wakin (2008)

# How To Recover $x$ ?

- Lots and lots of algorithms
  - $\ell_1$ -minimization
  - greedy algorithms (matching pursuit, CoSaMP, IHT)

If  $A$  satisfies the RIP,  $\|x\|_0 \leq k$ , and  $y = Ax + z$  with  $z \sim \mathcal{N}(0, \sigma^2 I)$ , then

$$\hat{x} = \arg \min_{x' \in \mathbb{R}^n} \|x'\|_1$$

$$\text{s.t. } \|A^*(y - Ax')\|_\infty \leq c\sqrt{\log n}\sigma$$

satisfies

$$\mathbb{E} \|\hat{x} - x\|_2^2 \leq C \frac{n}{m} k \sigma^2 \log n.$$

[Candès and Tao - 2005]

# Room For Improvement?

There exists matrices  $A$  such that for *any* (sparse)  $x$  we have

$$\mathbb{E} \|\hat{x} - x\|_2^2 \leq C \frac{n}{m} k \sigma^2 \log n.$$

$$y_i = \langle a_i, x \rangle + z_i$$



$a_i$  and  $x$  are almost orthogonal

- We are using most of our “sensing power” to sense entries that aren’t even there!
- Tremendous loss in signal-to-noise ratio (SNR)
- It’s hard to imagine any way to avoid this...

# Can We Do Better?

## Theorem

For *any* matrix  $A$  (with unit-norm rows) and *any* recovery procedure  $\hat{x}$ , there exists an  $x$  with  $\|x\|_0 \leq k$  such that if  $y = Ax + z$  with  $z \sim \mathcal{N}(0, \sigma^2 I)$ , then

$$\mathbb{E} \|\hat{x}(y) - x\|_2^2 \geq C' \frac{n}{m} k \sigma^2 \log(n/k).$$

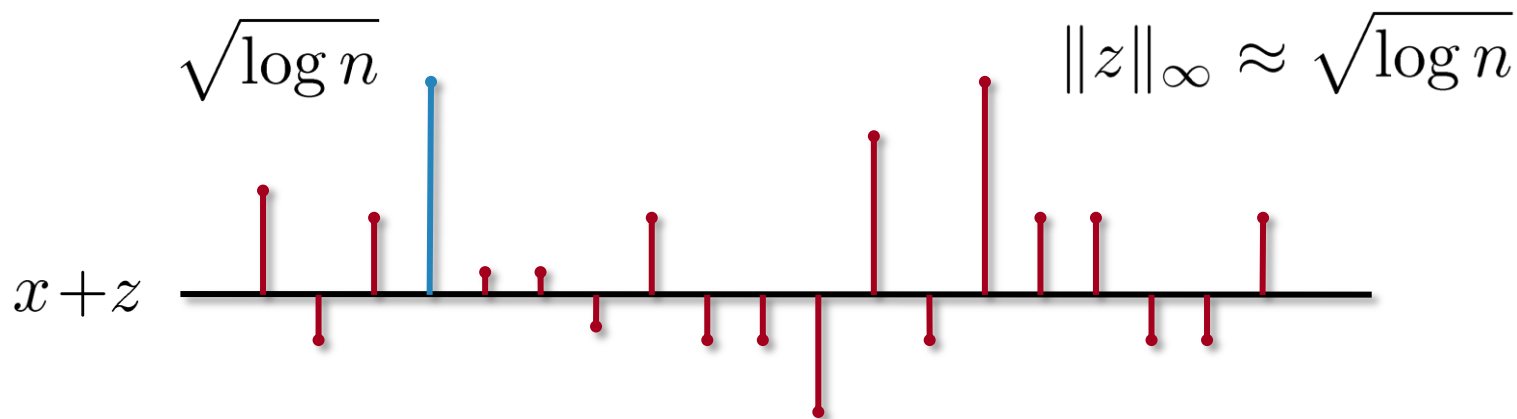
Compressive sensing is already operating at the limit



# Intuition

Suppose that  $y = x + z$  with  $z \sim \mathcal{N}(0, I)$  and that  $k = 1$

$$\mathbb{E} \|\hat{x}(y) - x\|_2^2 \geq C' \log n$$



# Proof Recipe

## Ingredients (Makes $\sigma^2 = 1$ servings)

- Lemma 1: There exists a set  $\mathcal{X}$  of  $k$ -sparse vectors such that
  - $|\mathcal{X}| = (n/k)^{k/4}$
  - $\|x_i - x_j\|_2 \geq \frac{1}{2}$  for all  $x_i, x_j \in \mathcal{X}$
  - $\left\| \frac{1}{|\mathcal{X}|} \sum_i x_i x_i^* - \frac{1}{n} I \right\| \leq \frac{\beta}{n}$  for some  $\beta > 0$
- Lemma 2: Define  $R_{\text{mm}}^*(A) = \inf_{\hat{x}} \sup_{\|x\|_0 \leq k} \mathbb{E} [\|\hat{x}(Ax + z) - x\|_2^2]$ .  
Suppose  $\mathcal{X}$  is a set of  $k$ -sparse vectors such that  $\|x_i - x_j\|_2^2 \geq 8nR_{\text{mm}}^*(A)$  for all  $x_i, x_j \in \mathcal{X}$ .  
Then  $\frac{1}{2} \log |\mathcal{X}| - 1 \leq \frac{1}{2|\mathcal{X}|^2} \sum_{i,j} \|Ax_i - Ax_j\|_2^2$ .


## Instructions

Combine ingredients and add a dash of linear algebra.

# The Details

$$\mu = \frac{1}{|\mathcal{X}|} \sum_i x_i \quad Q = \frac{1}{|\mathcal{X}|} \sum_i x_i x_i^*$$

$$\begin{aligned} \frac{k}{4} \log(n/k) - 2 &\leq \frac{1}{|\mathcal{X}|^2} \sum_{i,j} \|Ax_i - Ax_j\|_2^2 \\ &= \text{Tr} \left( A^* A \left( \frac{1}{|\mathcal{X}|^2} \sum_{i,j} (x_i - x_j)(x_i - x_j)^* \right) \right) \\ &= \text{Tr} (A^* A (2(Q - \mu\mu^*))) \\ &\leq 2\text{Tr} (A^* A Q) \\ &\leq 2\text{Tr} (A^* A) \|Q\| \\ &\leq 2\|A\|_F^2 \cdot 16R_{\text{mm}}^*(A)(1 + \beta) \end{aligned}$$


$$R_{\text{mm}}^*(A) \geq \frac{k \log(n/k)}{128(1 + \beta)\|A\|_F^2}$$

# Lemma 1

Lemma 1: There exists a set  $\mathcal{X}$  of  $k$ -sparse points such that

- $|\mathcal{X}| = (n/k)^{k/4}$
- $\|x_i - x_j\|_2 \geq \frac{1}{2}$  for all  $x_i, x_j \in \mathcal{X}$
- $\left\| \frac{1}{|\mathcal{X}|} \sum_i x_i x_i^* - \frac{1}{n} I \right\| \leq \frac{\beta}{n}$  for some  $\beta > 0$

## Strategy

Construct  $\mathcal{X}$  by sampling (with replacement) from

$$\mathcal{U} = \left\{ x \in \{0, \sqrt{1/k}, -\sqrt{1/k}\}^n : \|x\|_0 \leq k \right\}$$

Repeat for  $|\mathcal{X}| = (n/k)^{k/4}$  iterations.

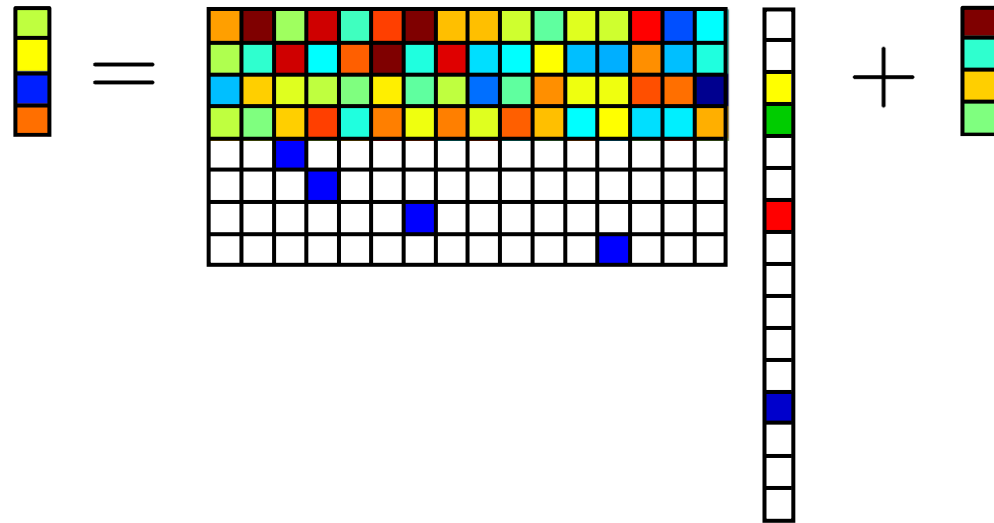
With probability  $> 0$ , the remaining properties are satisfied.

**Key: Matrix Bernstein Inequality** [Ahlsvede and Winter, 2002]

# **Adaptive Sensing**

# Adaptive Sensing

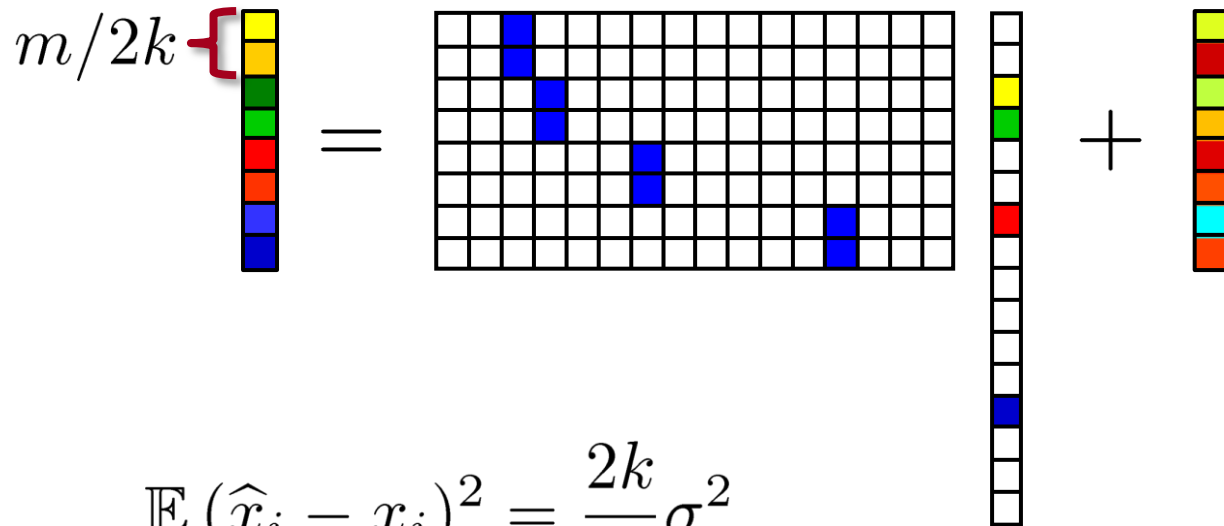
Think of sensing as a game of 20 questions



Simple strategy: Use  $m/2$  measurements to find the support, and the remainder to estimate the values.

# Thought Experiment

Suppose that after  $m/2$  measurements we have perfectly estimated the support.



$$\mathbb{E} (\hat{x}_i - x_i)^2 = \frac{2k}{m} \sigma^2$$

$$\mathbb{E} \|\hat{x} - x\|_2^2 = \frac{2k}{m} k \sigma^2 \ll \frac{n}{m} k \sigma^2 \log n$$

# Does Adaptivity *Really* Help?

Sometimes...

- Noise-free measurements, but non-sparse signal
  - adaptivity doesn't help if you want a uniform guarantee
  - probabilistic adaptive algorithms can reduce the required number of measurements from  $O(k \log(n/k))$  to  $O(k \log \log(n/k))$  [Indyk et al. - 2011]
- Noisy setting
  - distilled sensing [Haupt et al. - 2007, 2010]
  - adaptivity can reduce the estimation error to

$$\mathbb{E} \|\hat{x} - x\|_2^2 = \frac{n}{m} k \sigma^2$$

$$\mathbb{E} \|\hat{x} - x\|_2^2 = \frac{k}{m} k \sigma^2$$

*Which is it?*





# Which Is It?

Suppose we have a budget of  $m$  measurements of the form  $y_i = \langle a_i, x \rangle + z_i$  where  $\|a_i\|_2 = 1$  and  $z_i \sim \mathcal{N}(0, \sigma^2)$

The vector  $a_i$  can have an arbitrary dependence on the measurement history, i.e.,  $(a_1, y_1), \dots, (a_{i-1}, y_{i-1})$

## Theorem

There exist  $x$  with  $\|x\|_0 \leq k$  such that for **any** adaptive measurement strategy and **any** recovery procedure  $\hat{x}$ ,

$$\mathbb{E} \|\hat{x}(y) - x\|_2^2 \geq C \frac{n}{m} k \sigma^2.$$

Thus, in general, adaptivity does **not** significantly help!

# Proof Strategy

- Step 1:** Consider a prior on sparse signals with nonzeros of amplitude  $\mu \approx \sigma \sqrt{n/m}$
- Step 2:** Show that if given a budget of  $m$  measurements, you cannot detect the support very well
- Step 3:** Immediately translate this into a lower bound on the MSE

To make things simpler, we will consider a Bernoulli prior  $\pi(x)$  instead of a uniform  $k$ -sparse prior:

$$x_j = \begin{cases} 0 & \text{with probability } 1 - k/n \\ \mu > 0 & \text{with probability } k/n \end{cases}$$


# Proof of Main Result

Let  $S = \{j : x_j \neq 0\}$  and set  $\sigma^2 = 1$

For any estimator  $\hat{x}$ , define  $\hat{S} := \{j : |\hat{x}_j| \geq \mu/2\}$

Whenever  $j \in S \setminus \hat{S}$  or  $j \in \hat{S} \setminus S$ ,  $|\hat{x}_j - x_j| \geq \mu/2$

$$\|\hat{x} - x\|_2^2 \geq \frac{\mu^2}{4} |S \setminus \hat{S}| + \frac{\mu^2}{4} |\hat{S} \setminus S| = \frac{\mu^2}{4} |\hat{S} \Delta S|$$


$$\mathbb{E} \|\hat{x} - x\|_2^2 \geq \frac{\mu^2}{4} \mathbb{E} |\hat{S} \Delta S|$$

# Proof of Main Result

## Lemma

Under the Bernoulli prior, *any* estimate  $\hat{S}$  satisfies

$$\mathbb{E} |\hat{S} \Delta S| \geq k \left( 1 - \frac{\mu}{2} \sqrt{\frac{m}{n}} \right).$$

Thus, 
$$\begin{aligned} \mathbb{E} \|\hat{x} - x\|_2^2 &\geq \frac{\mu^2}{4} \mathbb{E} |\hat{S} \Delta S| \\ &\geq k \cdot \frac{\mu^2}{4} \left( 1 - \frac{\mu}{2} \sqrt{\frac{m}{n}} \right) \end{aligned}$$

Plug in  $\mu = \frac{8}{3} \sqrt{\frac{n}{m}}$  and this reduces to

$$\mathbb{E} \|\hat{x} - x\|_2^2 \geq \frac{4}{27} \cdot \frac{kn}{m} \geq \frac{1}{7} \cdot \frac{kn}{m}$$

# Key Ideas in Proof of Lemma

$$\mathbb{P}_{0,j}(y_1, \dots, y_m) = \mathbb{P}(y_1, \dots, y_m | x_j = 0)$$

$$\mathbb{P}_{1,j}(y_1, \dots, y_m) = \mathbb{P}(y_1, \dots, y_m | x_j = \mu)$$

$$\begin{aligned} \mathbb{E} |\widehat{S} \Delta S| &\geq \frac{k}{n} \sum_j (1 - \|\mathbb{P}_{1,j} - \mathbb{P}_{0,j}\|_{\text{TV}}) \\ &\geq k - \frac{k}{\sqrt{n}} \sqrt{\sum_j \|\mathbb{P}_{1,j} - \mathbb{P}_{0,j}\|_{\text{TV}}^2} \end{aligned}$$


$$\sum_j \|\mathbb{P}_{1,j} - \mathbb{P}_{0,j}\|_{\text{TV}}^2 \leq \frac{\mu^2}{4} m \quad \longrightarrow \quad \mathbb{E} |\widehat{S} \Delta S| \geq k \left( 1 - \frac{\mu}{2} \sqrt{\frac{m}{n}} \right)$$

# Key Ideas in Proof of Lemma

## Pinsker's Inequality

$$\|\mathbb{P} - \mathbb{Q}\|_{\text{TV}} \leq \sqrt{K(\mathbb{P}, \mathbb{Q})/2}$$

$$\begin{aligned} \|\mathbb{P}_{1,j} - \mathbb{P}_{0,j}\|_{\text{TV}}^2 &\leq \frac{\pi_0}{2} K(\mathbb{P}_{0,j}, \mathbb{P}_{1,j}) + \frac{\pi_1}{2} K(\mathbb{P}_{1,j}, \mathbb{P}_{0,j}) \\ &\leq \frac{\mu^2}{4} \sum_i \mathbb{E} a_{i,j}^2 \end{aligned}$$


$$\sum_j \|\mathbb{P}_{1,j} - \mathbb{P}_{0,j}\|_{\text{TV}}^2 \leq \frac{\mu^2}{4} \sum_{i,j} \mathbb{E} a_{i,j}^2 = \frac{\mu^2}{4} m$$

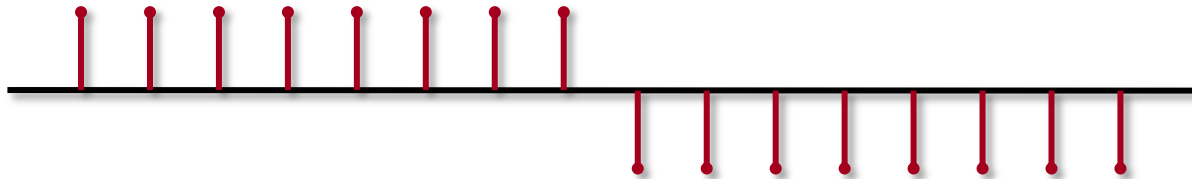
# **Adaptivity in Practice**

# Adaptivity In Practice

Suppose that  $k = 1$  and that  $x_{j^*} = \mu$

Binary Search [Iwen and Tewfik - 2011, Davenport and Arias-Castro - 2012]

- split measurements into  $\log n$  stages
- in each stage, use measurements to decide if the nonzero is in the left or right half of the “active set”
- after subdividing  $\log n$  times, return support



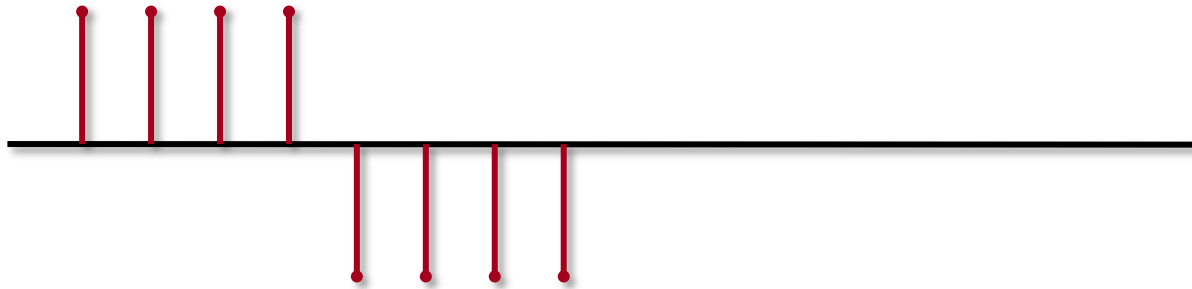


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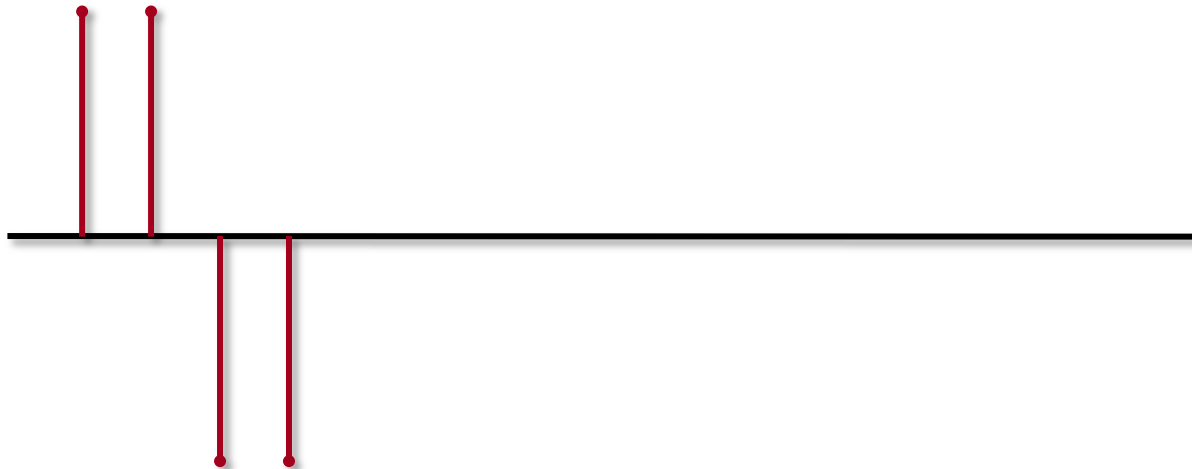


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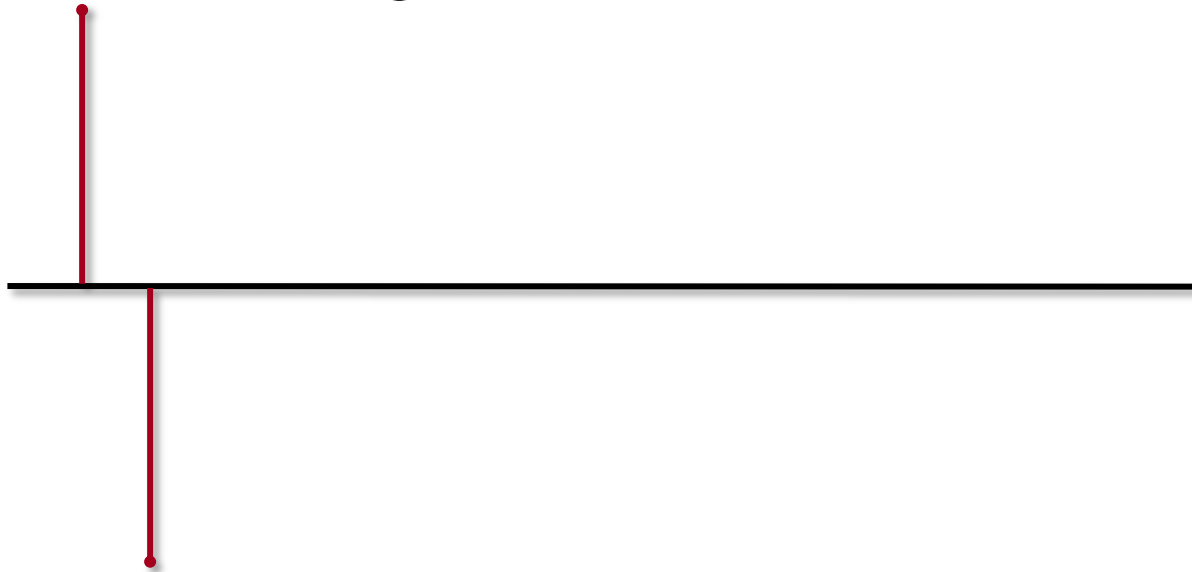


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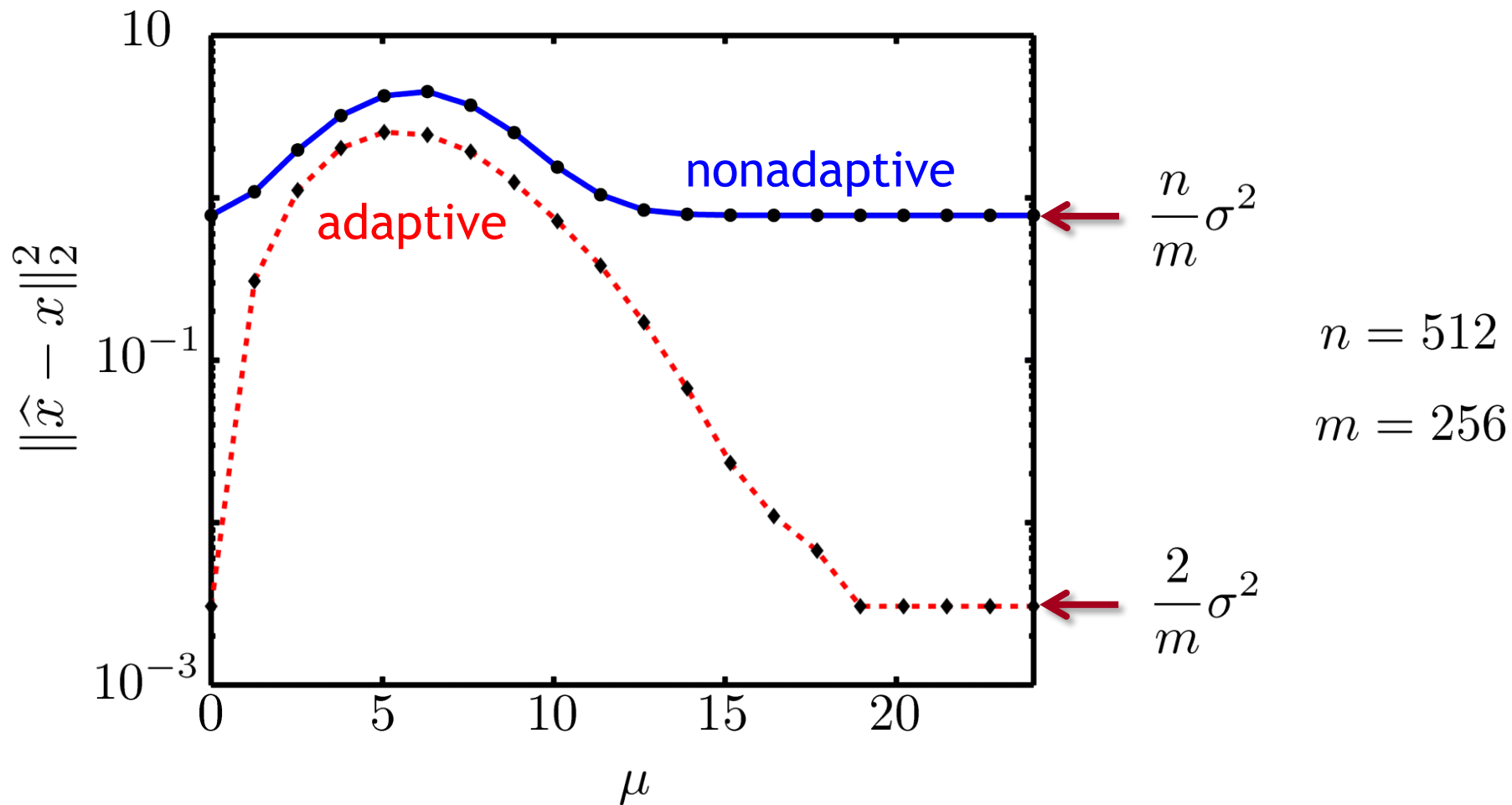
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- in each stage, use measurements to decide if the nonzero is in the left or right half of the “active set”
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# Experimental Results



# Open Questions

- No method can succeed when  $\frac{\mu}{\sigma} \approx \sqrt{\frac{n}{m}}$ , but the binary search approach succeeds as long as  $\frac{\mu}{\sigma} \geq C \sqrt{\frac{n}{m} \log \log n}$   
[Davenport and Arias-Castro - 2012]
- Practical algorithms that work well for all values of  $\mu$
- Practical algorithms for  $k > 1$
- New theory for restricted adaptive measurements
  - single-pixel camera: 0/1 measurements
  - magnetic resonance imaging (MRI): Fourier measurements
  - analog-to-digital converters: linear filter measurements
- New sensors and architectures that can actually acquire adaptive measurements

# More Information

<http://stat.stanford.edu/~markad>

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