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## **Collection of Solved Feedback Amplifier Problems**

This document contains a collection of solved feedback amplifier problems involving one or more active devices. The solutions make use of a graphical tool for solving simultaneous equations that is called the Mason Flow Graph (also called the Signal Flow Graph). When set up properly, the graph can be used to obtain by inspection the gain of a feedback amplifier, its input resistance, and its output resistance without solving simultaneous equations. Some background on how the equations are written and how the flow graph is used to solve them can be found at

http://users.ece.gatech.edu/~mleach/ece3050/notes/feedback/fdbkamps.pdf

The gain of a feedback amplifier is usually written in the form  $A \div (1 + bA)$ , where A is the gain with feedback removed and b is the feedback factor. In order for this equation to apply to the four types of feedback amplifiers, the input and output variables must be chosen correctly. For amplifiers that employ series summing at the input (alson called voltage summing), the input variable must be a voltage. In this case, the source is modeled as a Thévenin equivalent circuit. For amplifiers that employ shunt summing at the input (also called current summing), the input variable must be a current. In this case, the source is modeled as a Norton equivalent circuit. When the output sampling is in shunt with the load (also called voltage sampling), the output variable must be a current. These conventions are followed in the following examples.

The quantity Ab is called the loop gain. For the feedback to be negative, the algebraic sign of Ab must be positive. If Ab is negative the feedback is positive and the amplifier is unstable. Thus if A is positive, bmust also be positive. If A is negative, b must be negative. The quantity (1 + Ab) is called the amount of feedback. It is often expressed in dB with the relation  $20 \log (1 + Ab)$ .

For series summing at the input, the expression for the input resistance is of the form  $R_{IN} \times (1 + bA)$ , where  $R_{IN}$  is the input resistance without feedback. For shunt summing at the input, the expression for the input resistance is of the form  $R_{IN} \div (1 + bA)$ . For shunt sampling at the output, the expression for the output resistance is of the form  $R_O \div (1 + bA)$ , where  $R_O$  is the output resistance without feedback. To calculate this in the examples, a test current source is added in shunt with the load. For series sampling at the output, the expression for the output resistance is of the form  $R_O \times (1 + bA)$ . To calculate this in the examples, a test voltage source is added in series with the load.

Most texts neglect the feedforward gain through the feedback network in calculating the forward gain A. When the flow graph is used for the analysis, this feedforward gain can easily be included in the analysis without complicating the solution. This is done in all of the examples here.

The dc bias sources in the examples are not shown. It is assumed that the solutions for the dc voltages and currents in the circuits are known. In addition, it is assumed that any dc coupling capacitors in the circuits are ac short circuits for the small-signal analysis.

## Series-Shunt Example 1

Figure 1(a) shows the ac signal circuit of a series-shunt feedback amplifier. The input variable is  $v_1$  and the output variable is  $v_2$ . The input signal is applied to the gate of  $M_1$  and the feedback signal is applied to the source of  $M_1$ . Fig. 1(b) shows the circuit with feedback removed. A test current source  $i_t$  is added in shunt with the output to calculate the output resistance  $R_B$ . The feedback at the source of  $M_1$  is modeled by a Thévenin equivalent circuit. The feedback factor or feedback ratio b is the coefficient of  $v_2$  in this source, i.e.  $b = R_1/(R_1 + R_3)$ . The circuit values are  $g_m = 0.001 \,\text{S}$ ,  $r_s = g_m^{-1} = 1 \,\text{k}\Omega$ ,  $r_0 = \infty$ ,  $R_1 = 1 \,\text{k}\Omega$ ,  $R_2 = 10 \,\text{k}\Omega$ ,  $R_3 = 9 \,\text{k}\Omega$ ,  $R_4 = 1 \,\text{k}\Omega$ , and  $R_5 = 100 \,\text{k}\Omega$ .

The following equations can be written for the circuit with feedback removed:

$$i_{d1} = G_{m1}v_a \qquad G_{m1} = \frac{1}{r_{s1} + R_1 \|R_3} \qquad v_a = v_1 - v_{ts1} \qquad v_{ts1} = \frac{R_1}{R_1 + R_3}v_2 \qquad i_{d2} = -g_m v_{tg2}$$



Figure 1: (a) Amplifier circuit. (b) Circuit with feedback removed.

$$v_{tg2} = -i_{d1}R_2 \qquad v_2 = i_{d2}R_C + i_tR_C + i_{d1}R_D \qquad R_C = R_4 \| (R_1 + R_3) \qquad R_D = \frac{R_1R_4}{R_1 + R_3 + R_4}$$

The voltage  $v_a$  is the error voltage. The negative feedback tends to reduce  $v_a$ , making  $|v_a| \to 0$  as the amount of feedback becomes infinite. When this is the case, setting  $v_a = 0$  yields the voltage gain  $v_2/v_1 = b^{-1} = 1 + R_3/R_1$ . Although the equations can be solved algebraically, the signal-flow graph simplifies the solution.

Figure 2 shows the signal-flow graph for the equations. The determinant of the graph is given by

$$\Delta = 1 - G_{m1} \times [-R_2 \times (-g_{m2}) \times R_C + R_D] \times \frac{R_1}{R_1 + R_3} \times (-1)$$

Figure 2: Signal-flow graph for the equations.

The voltage gain  $v_2/v_1$  is calculated with  $i_t = 0$ . It is given by

$$\frac{v_2}{v_1} = \frac{G_{m1} \times [-R_2 \times (-g_{m2}) \times R_C + R_D]}{\Delta}$$
$$= \frac{\frac{1}{r_{s1} + R_1 \| R_3} \times (R_2 \times g_{m2} \times R_C + R_D)}{1 + \frac{1}{r_{s1} + R_1 \| R_3} \times (R_2 \times g_{m2} \times R_C + R_D) \times \frac{R_1}{R_1 + R_3}}$$

This is of the form

$$\frac{v_2}{v_1} = \frac{A}{1+Al}$$

where

$$A = \frac{1}{r_{s1} + R_1 ||R_3|} \times (R_2 \times g_{m2} \times R_C + R_D) = 4.83$$
$$b = \frac{R_1}{R_1 + R_3} = 0.1$$

Note that Ab is dimensionless. Numerical evaluation yields

$$\frac{v_2}{v_1} = \frac{4.83}{1+0.483} = 3.26$$

The output resistance  $R_B$  is calculated with  $v_1 = 0$ . It is given by

$$R_B = \frac{v_2}{i_t} = \frac{R_C}{\Delta} = \frac{R_C}{1+Ab} = 613\,\Omega$$

Note that the feedback tends to decrease  $R_B$ . Because the gate current of  $M_1$  is zero, the input resistance is  $R_A = R_5 = 100 \text{ k}\Omega$ .

# Series-Shunt Example 2

A series-shunt feedback BJT amplifier is shown in Fig. 3(a). A test current source is added to the output to solve for the output resistance. Solve for the voltage gain  $v_2/v_1$ , the input resistance  $R_A$ , and the output resistance  $R_B$ . Assume  $\beta = 100$ ,  $r_{\pi} = 10 \,\mathrm{k\Omega}$ ,  $\alpha = \beta/(1+\beta)$ ,  $g_m = \beta/r_{\pi}$ ,  $r_e = \alpha/g_m$ ,  $r_0 = \infty$ ,  $r_x = 0$ ,  $R_1 = 1 \,\mathrm{k\Omega}$ ,  $R_2 = 1 \,\mathrm{k\Omega}$ ,  $R_3 = 2 \,\mathrm{k\Omega}$ ,  $R_4 = 4 \,\mathrm{k\Omega}$ , and  $R_5 = 10 \,\mathrm{k\Omega}$ . The circuit with feedback removed is shown in Fig. 3(b). The circuit seen looking out of the emitter of  $Q_1$  is replaced with a Thévenin equivalent circuit made with respect to  $v_2$ . A test current source  $i_t$  is added to the output to solve for the output resistance.



Figure 3: (a) Amplifier circuit. (b) Circuit with feedback removed.

For the circuit with feedback removed, we can write

$$i_{e1} = G_1 v_a \qquad v_a = v_1 - v_2 \frac{R_3}{R_3 + R_4} \qquad G_1 = \frac{1}{r'_{e1} + R_3 \| R_4} \qquad r'_{e1} = \frac{R_1}{1 + \beta} + r_e \qquad i_{c1} = \alpha i_{e1}$$
$$i_{b1} = \frac{i_{c1}}{\beta} \qquad v_{tb2} = -i_{c1} R_2 \qquad i_{e2} = -G_2 v_{tb2} \qquad G_2 = \frac{1}{r'_{e2}} \qquad r'_{e2} = \frac{R_2}{1 + \beta} + r_e$$

$$i_{c2} = \alpha i_{e2} \qquad v_2 = i_{c2}R_a + i_tR_a + i_{e1}R_b \qquad R_a = R_5 \| (R_3 + R_4) \qquad R_b = \frac{R_3R_5}{R_3 + R_4 + R_5}$$

The equations can be solved algebraically or by a flow graph. The flow graph for the equations is shown in Fig. 4. The determinant is

$$\Delta = 1 - G_1 \times [\alpha \times -R_2 \times -G_2 \times \alpha \times R_a + R_b] \times \frac{-R_3}{R_3 + R_4}$$
$$= 1 + G_1 \times [\alpha \times R_2 \times G_2 \times \alpha \times R_a + R_b] \times \frac{R_3}{R_3 + R_4}$$
$$= 9.09$$



Figure 4: Signal-flow graph for the equations.

The voltage gain is

$$\begin{array}{ll} \displaystyle \frac{v_2}{v_1} &=& \displaystyle \frac{G_1 \times \left[\alpha \times -R_2 \times -G_2 \times \alpha \times R_a + R_b\right]}{\Delta} \\ &=& \displaystyle \frac{G_1 \times \left[\alpha \times R_2 \times G_2 \times \alpha \times R_a + R_b\right]}{1 + G_1 \times \left[\alpha \times R_2 \times G_2 \times \alpha \times R_a + R_b\right] \times \displaystyle \frac{R_3}{R_3 + R_4} } \end{array}$$

This is of the form

where

$$\frac{v_2}{i_1} = \frac{A}{1+Ab}$$

$$A = G_1 \times [\alpha \times R_2 \times G_2 \times \alpha \times R_a + R_b]$$
  
=  $\frac{1}{r'_{e1} + R_3 \| R_4} \left[ \alpha \times R_2 \times \frac{1}{r'_{e2}} \times \alpha \times R_5 \| (R_3 + R_4) + \frac{R_3 R_5}{R_3 + R_4 + R_5} \right]$   
= 24.27  
$$b = \frac{R_3}{R_3 + R_4} = 0.333$$

Notice that the product Ab is positive. This must be true for the feedback to be negative. Numerical evaluation of the voltage gain yields

$$\frac{v_2}{v_1} = \frac{A}{\Delta} = 2.67$$

The resistances  $R_A$  and  $R_B$  are given by

$$R_A = \left(\frac{i_{b1}}{v_1}\right)^{-1} = \left(\frac{G_1 \alpha/\beta}{\Delta}\right)^{-1} = \Delta \times \frac{\beta r'_{e1}}{\alpha} = \Delta \times \frac{\beta}{\alpha} \left(r'_{e1} + R_3 \| R_4 \right) = 1.32 \,\mathrm{M}\Omega$$
$$R_B = \frac{v_2}{i_t} = \frac{R_a}{\Delta} = \frac{R_5 \| \left(R_3 + R_4\right)}{\Delta} = 412.5 \,\Omega$$

# Series-Shunt Example 3

A series-shunt feedback BJT amplifier is shown in Fig. 5(a). Solve for the voltage gain  $v_2/v_1$ , the input resistance  $R_A$ , and the output resistance  $R_B$ . For  $J_1$ , assume  $g_{m1} = 0.003$  S, and  $r_{01} = \infty$ . For  $Q_2$ , assume  $\beta_2 = 100$ ,  $r_{\pi 2} = 2.5 \text{ k}\Omega$ ,  $\alpha_2 = \beta_2/(1 + \beta_2)$ ,  $g_{m2} = \beta_2/r_{\pi 2}$ ,  $r_{e2} = \alpha_2/g_{m2}$ ,  $r_{02} = \infty$ ,  $r_{x2} = 0$ . The circuit elements are  $R_1 = 1 \text{ M}\Omega$ .  $R_2 = 10 \text{ k}\Omega$ ,  $R_3 = 1 \text{ k}\Omega$ ,  $R_4 = 20 \text{ k}\Omega$ , and  $R_5 = 10 \text{ k}\Omega$ . The circuit with feedback removed is shown in Fig. 5(b). The circuit seen looking out of the source of  $J_1$  is replaced with a Thévenin equivalent circuit made with respect to  $v_2$ . A test current source  $i_t$  is added in shunt with the output to solve for the output resistance.



Figure 5: (a) Amplifier circuit. (b) Circuit with feedback removed.

For the circuit with feedback removed, we can write

$$\begin{aligned} v_a &= v_1 - v_2 \frac{R_3}{R_3 + R_4} \qquad i_{d1} = G_1 v_a \qquad G_1 = \frac{1}{r_{s1} + R_3 \| R_4} \\ v_{tb2} &= -i_{d1} R_2 \qquad i_{e2} = -G_2 v_{tb2} \qquad G_2 = \frac{1}{r'_{e2}} \qquad r'_{e2} = \frac{R_2}{1 + \beta_2} + r_{e2} \\ i_{c2} &= \alpha_2 i_{e2} \qquad v_2 = i_{c2} R_a + i_t R_a + i_{d1} R_b \qquad R_a = R_5 \| (R_3 + R_4) \qquad R_b = \frac{R_3 R_5}{R_3 + R_4 + R_5} \end{aligned}$$

The equations can be solved algebraically or by a flow graph. The flow graph for the equations is shown in Fig. 6. The determinant is

$$\Delta = 1 - G_1 \times \left[-R_2 \times -G_2 \times \alpha \times R_a + R_b\right] \times \frac{-R_3}{R_3 + R_4}$$
$$= 1 + G_1 \times \left[R_3 \times G_2 \times \alpha \times R_a + R_b\right] \times \frac{R_3}{R_3 + R_4}$$
$$= 21.08$$

The voltage gain is

$$\frac{v_2}{v_1} = \frac{G_1 \times [-R_2 \times -G_2 \times \alpha_2 \times R_a + R_b]}{\Delta}$$
$$= \frac{G_1 \times [R_2 \times G_2 \times \alpha_2 \times R_a + R_b]}{1 + G_1 \times [R_3 \times G_2 \times \alpha \times R_a + R_b] \times \frac{R_3}{R_3 + R_4}}$$



Figure 6: Signal-flow graph for the equations.

This is of the form

$$\frac{v_2}{i_1} = \frac{A}{\Delta} = \frac{A}{1+Ab}$$

where

$$A = G_1 \times [R_2 \times G_2 \times \alpha_2 \times R_a + R_b]$$
  
=  $\frac{1}{r_{s1} + R_3 \| R_4} \left[ R_2 \times \frac{1}{r'_{e1}} \times \alpha_1 \times R_5 \| (R_3 + R_4) + \frac{R_3 R_4}{R_3 + R_4 + R_5} \right]$   
= 421.8  
 $b = \frac{R_3}{R_3 + R_4} = 0.0467$ 

Notice that the product Ab is positive. This must be true for the feedback to be negative.

Numerical evaluation of the voltage gain yields

$$\frac{v_2}{v_1} = \frac{421.8}{1 + 421.8 \times 0.0476} = 20$$

The resistances  $R_A$  and  $R_B$  are given by

$$R_A = R_1 = 1 \operatorname{M}\Omega$$
$$R_B = \frac{v_2}{i_t} = \frac{R_a}{\Delta} = \frac{R_5 \| (R_3 + R_4)}{\Delta} = 321.3 \,\Omega$$

## Series-Shunt Example 4

A series-shunt feedback BJT amplifier is shown in Fig. 7(a). A test current source is added to the output to solve for the output resistance. Solve for the voltage gain  $v_2/v_1$ , the input resistance  $R_A$ , and the output resistance  $R_B$ . Assume  $\beta = 50$ ,  $r_{\pi} = 2.5 \text{ k}\Omega$ ,  $\alpha = \beta/(1+\beta)$ ,  $g_m = \beta/r_{\pi}$ ,  $r_e = \alpha/g_m$ ,  $r_0 = \infty$ ,  $r_x = 0$ ,  $R_1 = 1 \text{ k}\Omega$ ,  $R_2 = 100 \Omega$ ,  $R_3 = 9.9 \text{ k}\Omega$ ,  $R_4 = 10 \text{ k}\Omega$ , and  $R_5 = 10 \text{ k}\Omega$ . The circuit with feedback removed is shown in Fig. 8. The circuit seen looking out of the base of  $Q_2$  is a Thévenin equivalent circuit made with respect to the voltage  $v_2$ . A test current source  $i_t$  is added in shunt with the output to solve for the output resistance.

The emitter eQuivalent circuit for calculating  $i_{e1}$  and  $i_{e2}$  is shown in Fig. 7(b). For this circuit and the circuit with feedback removed, we can write

$$\begin{aligned} i_{e1} &= G_1 v_e \qquad v_e = v_1 - v_2 \frac{R_2}{R_2 + R_3} \qquad G_1 = \frac{1}{r_{e1} + r'_{e2}} \qquad r'_{e2} = \frac{R_2 ||R_3}{1 + \beta} + r_e \qquad i_{c1} = \alpha i_{e1} \\ i_{b1} &= \frac{i_{c1}}{\beta} \qquad v_{tb3} = -i_{c1} R_1 \qquad i_{e3} = -G_2 v_{tb3} \qquad G_2 = \frac{1}{r'_{e3}} \qquad r'_{e3} = \frac{R_1}{1 + \beta} + r_e \\ i_{c3} &= \alpha i_{e3} \qquad v_2 = i_{c3} R_a + i_t R_a - i_{b2} R_b \qquad R_a = R_4 || (R_2 + R_3) \qquad R_b = \frac{R_2 R_4}{R_2 + R_3 + R_4} \end{aligned}$$



Figure 7: (a) Amplifier circuit. (b) Emitter equivalent circuit for calculating  $i_{e1}$  and  $i_{e2}$ .



Figure 8: Circuit with feedback removed.

The equations can be solved algebraically or by a flow graph. The flow graph for the equations is shown in Fig. 9. The determinant is

Figure 9: Flow graph for the equations.

The voltage gain is

$$\frac{v_2}{v_1} = \frac{G_1 \times \left(\alpha \times -R_1 \times -G_2 \times \alpha \times R_a - \frac{R_b}{1+\beta}\right)}{\Delta}$$
$$= \frac{G_1 \times \left(\alpha \times R_1 \times G_2 \times \alpha \times R_a - \frac{R_b}{1+\beta}\right)}{1+G_1 \times \left(\alpha \times R_1 \times G_2 \times \alpha \times R_a - \frac{R_b}{1+\beta}\right) \times \frac{R_2}{R_2+R_3}}$$

This is of the form

$$\frac{v_2}{i_1} = \frac{A}{1+Ab}$$

where

$$A = G_{1} \times \left( \alpha \times R_{1} \times G_{2} \times \alpha \times R_{a} - \frac{R_{b}}{1+\beta} \right)$$
  
$$\frac{1}{r_{e1} + r'_{e2}} \left[ \alpha \times R_{1} \times \frac{1}{r'_{e3}} \times \alpha \times R_{4} \| (R_{2} + R_{3}) - \frac{1}{1+\beta} \frac{R_{2}R_{4}}{R_{2} + R_{3} + R_{4}} \right]$$
  
$$= 700.4$$
  
$$b = \frac{R_{2}}{R_{2} + R_{3}} = 0.01$$

Notice that the product Ab is positive. This must be true for the feedback to be negative.

Numerical evaluation of the voltage gain yields

$$\frac{v_2}{v_1} = \frac{A}{\Delta} = 87.51$$

The resistances  $R_A$  and  $R_B$  are given by

$$R_{A} = R_{5} \left\| \left( \frac{i_{b1}}{v_{1}} \right)^{-1} = R_{5} \left\| \left( \frac{G_{1} \alpha / \beta}{\Delta} \right)^{-1} = R_{5} \right\| \left[ \Delta \times (1 + \beta) \times (r_{e1} + r'_{e2}) \right] = 8.032 \,\mathrm{k\Omega}$$
$$R_{B} = \frac{v_{2}}{i_{t}} = \frac{R_{a}}{\Delta} = \frac{R_{4} \left\| (R_{2} + R_{3}) - R_{2} \right\|}{\Delta} = 624.7 \,\mathrm{\Omega}$$

## Shunt-Shunt Example 1

Figure 10(a) shows the ac signal circuit of a shunt-series feedback amplifier. The input variable is  $v_1$  and the output variable is  $v_2$ . The input signal and the feedback signal are applied to the base of  $Q_1$ . A test current source  $i_t$  is added in shunt with the output to calculate the output resistance  $R_B$ . For the analysis to follow convention, the input source consisting of  $v_1$  in series with  $R_1$  must be converted into a Norton equivalent. This circuit is the current  $i_1 = v_1/R_1$  in parallel with the resistor  $R_1$ . Fig. 10(b) shows the circuit with feedback removed and the source replaced with the Norton equivalent. The feedback at the base of  $Q_1$  is modeled by a Norton equivalent circuit  $v_2/R_4$  in parallel with the resistor  $R_4$ . The feedback factor or feedback ratio b is the negative of the coefficient of  $v_2$  in this source, i.e.  $b = -R_4^{-1}$ . The circuit values are  $\beta_1 = 100$ ,  $g_{m1} = 0.05$  S,  $r_{x1} = 0$ ,  $r_{ib1} = \beta_1/g_{m1} = 2$  k $\Omega$ ,  $r_{01} = \infty$ ,  $g_{m2} = 0.001$  S,  $r_{s2} = g_{m2}^{-1} = 1$  k $\Omega$ ,  $r_{02} = \infty$ ,  $R_1 = 1$  k $\Omega$ ,  $R_2 = 1$  k $\Omega$ ,  $R_3 = 10$  k $\Omega$ , and  $R_4 = 10$  k $\Omega$ .



Figure 10: (a) Amplifier circuit. (b) Circuit with feedback removed.

The following equations can be written for the circuit with feedback removed:

$$v_{b1} = i_a R_b \qquad i_a = i_1 + \frac{v_2}{R_4} \qquad R_b = R_1 ||R_4||r_{ib1} \qquad i_{c1} = g_{m1} v_{b1}$$
$$i_{d1} = -i_{c1} \frac{R_2}{r_{s1} + R_2} \qquad v_2 = i_{d1} R_c + i_t R_c + v_{b1} \frac{R_3}{R_3 + R_4} \qquad R_c = R_3 ||R_4|$$

The current  $i_a$  is the error current. The negative feedback tends to reduce  $i_a$ , making  $|i_a| \rightarrow 0$  as the amount of feedback becomes infinite. When this is the case, setting  $i_a = 0$  yields the current gain  $v_2/i_1 = -R_4$ .

Although the equations can be solved algebraically, the signal-flow graph simplifies the solution. Figure 11 shows the flow graph for the equations. The determinant of the graph is given by

$$\Delta = 1 - R_b \times \left[ g_{m1} \times \frac{-R_2}{r_{s1} + R_2} \times R_c + \frac{R_3}{R_3 + R_4} \right] \times \frac{1}{R_4}$$

The transresistance gain is calculated with  $i_t = 0$ . It is given by

$$\frac{v_2}{i_1} = \frac{R_b \times \left(g_{m1} \times \frac{-R_2}{r_{s2} + R_2} \times R_c + \frac{R_3}{R_3 + R_4}\right)}{\Delta}$$
$$= -\frac{\left(R_1 \| R_4 \| r_{ib1}\right) \times \left[g_{m1} \times \frac{-R_2}{r_{s2} + R_2} \times \left(R_3 \| R_4\right) + \frac{R_3}{R_3 + R_4}\right]}{1 + \left[\left(R_1 \| R_4 \| r_{ib1}\right) \times g_{m1} \times \frac{-R_2}{r_{s2} + R_2} \times \left(R_3 \| R_4\right) + \frac{R_3}{R_3 + R_4}\right] \times \frac{-1}{R_4}}$$

Figure 11: Signal-flow graph for the equations.

This is of the form

$$\frac{v_2}{i_1} = \frac{A}{1+Ab}$$

where

$$A = (R_1 || R_4 || r_{ib1}) \times \left[ g_{m1} \times \frac{-R_2}{r_{s2} + R_2} \times (R_3 || R_4) + \frac{R_3}{R_3 + R_4} \right] = -77.81 \,\mathrm{k\Omega}$$
$$b = -\frac{1}{R_4} = -10^{-4} \,\mathrm{S}$$

Note that Ab is dimensionless and positive. Numerical evaluation yields

$$\frac{v_2}{i_1} = \frac{-77.81 \times 10^3}{1 + (-77.81 \times 10^3) \times (-10^{-4})} = -8.861 \,\mathrm{k\Omega}$$

The voltage gain is given by

$$\frac{v_2}{v_1} = \frac{v_2}{i_1} \times \frac{i_1}{v_1} = \frac{v_2}{i_1} \times \frac{1}{R_1} = -8.861$$

The resistance  $R_a$  is calculated with  $i_t = 0$ . It is given by

$$R_a = \frac{v_{b1}}{i_1} = \frac{R_b}{\Delta} = \frac{R_1 ||R_4|| r_{ib1}}{1 + Ab} = 71.17\,\Omega$$

Note that the feedback tends to decrease  $R_a$ . The resistance  $R_A$  is calculated as follows:

$$R_A = R_1 + \left(R_a^{-1} - R_1^{-1}\right)^{-1} = 1.077 \,\mathrm{k}\Omega$$

The resistance  $R_B$  is calculated with  $i_1 = 0$ . It is given by

$$R_B = \frac{v_2}{i_t} = \frac{R_c}{\Delta} = \frac{R_3 || R_4}{1 + Ab} = 569.4 \,\Omega$$

### Shunt-Shunt Example 2

A shunt-shunt feedback JFET amplifier is shown in Fig. 12(a). Solve for the voltage gain  $v_2/v_1$ , the input resistance  $R_A$ , and the output resistance  $R_B$ . Assume  $g_m = 0.005 \text{ S}$ ,  $r_s = g_m^{-1} = 200 \Omega$ ,  $r_0 = \infty$ ,  $R_1 = 3 \text{ k}\Omega$ ,  $R_2 = 7 \text{ k}\Omega$ ,  $R_3 = 1 \text{ k}\Omega$ ,  $R_4 = 10 \text{ k}\Omega$ . The circuit with feedback removed is shown in Fig. 12(b) In this circuit, the source is replaced by a Norton equivalent circuit consisting of a current  $i_1 = v_1/R_1$  in parallel with the resistor  $R_1$ . This is necessary for the feedback analysis to conform to convention for shunt-shunt feedback. The circuit seen looking up into  $R_2$  is replaced with a Norton equivalent circuit made with respect to  $v_2$ . A test current source  $i_t$  is added in shunt with the output to solve for the output resistance.



Figure 12: (a) Amplifier circuit. (b) Circuit with feedback removed.

For the circuit with feedback removed, we can write

$$v_{g} = i_{1}R_{b} + \frac{v_{2}}{R_{2}}R_{b} \qquad R_{b} = R_{1}||R_{2} \qquad i_{d} = G_{m}v_{g} \qquad G_{m} = \frac{1}{r_{s} + R_{3}}$$
$$v_{2} = -i_{d}R_{c} + i_{t}R_{c} + v_{g}\frac{R_{4}}{R_{2} + R_{4}} \qquad R_{c} = R_{2}||R_{4}$$

The equations can be solved algebraically or by a flow graph. The flow graph for the equations is shown in Fig. 13. The determinant is

$$\Delta = 1 - R_b \times \left[ G_m \times -R_c + \frac{R_4}{R_2 + R_4} \right] \times \frac{1}{R_2}$$
$$= 1 + R_b \times \left[ G_m \times R_c - \frac{R_4}{R_2 + R_4} \right] \times \frac{1}{R_2}$$
$$= 1.853 \,\Omega$$



Figure 13: Signal-flow graph for the equations.

The transresistance gain is

$$\frac{v_2}{i_1} = \frac{R_b \times \left[G_m \times -R_c + \frac{R_4}{R_2 + R_4}\right]}{\Delta}$$
$$= \frac{-R_b \times \left[G_m \times R_c - \frac{R_4}{R_2 + R_4}\right]}{1 + R_b \times \left[G_m \times R_c + \frac{R_4}{R_2 + R_4}\right] \times \frac{1}{R_2}}$$

This is of the form

$$\frac{v_2}{i_1} = \frac{A}{1+Ab}$$

where

$$A = -R_b \times \left[ G_m \times R_c - \frac{R_4}{R_2 + R_4} \right]$$
  
= -(R\_1 || R\_2) ×  $\left[ G_m \times R_2 || R_4 - \frac{R_4}{R_2 + R_4} \right]$   
= -5.971 kΩ  
 $b = -\frac{1}{R_2} = -0.1429 \,\mathrm{mS}$ 

Note that the product Ab is dimensionless and positive. The latter must be true for the feedback to be negative. Numerical evaluation yields

$$\frac{v_2}{i_1} = \frac{A}{\Delta} = -3.22 \,\mathrm{k}\Omega$$

The voltage gain is given by

$$\frac{v_2}{v_1} = \frac{v_2}{i_1} \times \frac{i_1}{v_1} = \frac{A}{\Delta} \times \frac{1}{R_1} = -1.074$$

The resistances  $R_a$ ,  $R_A$ , and  $R_B$  are given by

$$R_a = \frac{v_g}{i_1} = \frac{R_b}{\Delta} = 1.13 \,\mathrm{k\Omega}$$
$$R_A = R_1 + \left(\frac{1}{R_a} - \frac{1}{R_1}\right)^{-1} = 4.82 \,\mathrm{kS}$$
$$R_B = \frac{v_2}{i_t} = \frac{R_c}{\Delta} = 2.22 \,\mathrm{k\Omega}$$

Ω

## Shunt-Shunt Example 3

A shunt-shunt feedback BJT amplifier is shown in Fig. 14. The input variable is the  $v_1$  and the output variable is the voltage  $v_2$ . The feedback resistor is  $R_2$ . The summing at the input is shunt because the input through  $R_1$  and the feedback through  $R_2$  connect in shunt to the same node, i.e. the  $v_{b1}$  node. The output sampling is shunt because  $R_2$  connects to the output node. Solve for the voltage gain  $v_2/v_1$ , the input resistance  $R_A$ , and the output resistance  $R_B$ . Assume  $\beta = 100$ ,  $r_{\pi} = 2.5 \,\mathrm{k\Omega}$ ,  $g_m = \beta/r_{\pi}$ ,  $\alpha = \beta/(1+\beta)$ ,  $r_e = \alpha/g_m$ ,  $r_0 = \infty$ ,  $r_x = 0$ ,  $V_T = 25 \,\mathrm{mV}$ . The resistor values are  $R_1 = 1 \,\mathrm{k\Omega}$ ,  $R_2 = 20 \,\mathrm{k\Omega}$ ,  $R_3 = 500 \,\Omega$ ,  $R_4 = 1 \,\mathrm{k\Omega}$ , and  $R_5 = 5 \,\mathrm{k\Omega}$ .

The circuit with feedback removed is shown in Fig. 15. A test current source  $i_t$  is added in shunt with the output to solve for the output resistance  $R_B$ . In the circuit, the source is replaced by a Norton equivalent circuit consisting of a current

$$i_1 = \frac{v_1}{R_1}$$



Figure 14: Amplifier circuit.



Figure 15: Circuit with feedback removed.

in parallel with the resistor  $R_1$ . This is necessary for the feedback analysis to conform to convention for shunt summing. The circuit seen looking into  $R_2$  from the collector of  $Q_3$  is replaced with a Thevenin equivalent circuit made with respect with  $v_{b1}$ .

For the circuit with feedback removed, we can write

$$i_{e} = i_{1} + \frac{v_{2}}{R_{2}} \qquad v_{b1} = i_{e}R_{b} \qquad R_{b} = R_{1}||R_{2}||r_{\pi} \qquad i_{c1} = g_{m}v_{b1} \qquad v_{b2} = -i_{c1}R_{c} \qquad R_{c} = R_{3}||r_{\pi}||R_{2}||r_{\pi} \qquad i_{c3} = g_{m}v_{b3} \qquad v_{2} = (-i_{c3} + i_{t})R_{e} + v_{b1}\frac{R_{5}}{R_{2} + R_{5}} \qquad R_{e} = R_{2}||R_{5}||R_{2}||R_{5}$$

The equations can be solved algebraically or by a flow graph. The flow graph for the equations is shown in Fig. 16. The determinant is

$$\Delta = 1 - R_b \times \left( g_m \times -R_c \times g_m \times -R_d \times g_m \times -R_e + \frac{R_5}{R_2 + R_5} \right) \times \frac{1}{R_2}$$
$$= 1 + R_b \times \left( g_m \times R_c \times g_m \times R_d \times g_m \times R_e - \frac{R_5}{R_2 + R_5} \right) \times \frac{1}{R_2}$$
$$= 354.7$$

$$i1 \leftarrow \frac{1}{Rb} = \frac{ic1}{Rb} + \frac{ic1}{gm} + \frac{ic2}{Rc} + \frac{ic2}{Rc} + \frac{ic3}{Rc} +$$

Figure 16: Signal-flow graph for the equations.

The transresistance gain is

$$\frac{v_2}{i_1} = \frac{R_b \times \left(g_m \times -R_c \times g_m \times -R_d \times g_m \times -R_e + \frac{R_2}{R_2 + R_5}\right)}{\Delta}$$
$$= \frac{-R_b \times \left(g_m \times R_c \times g_m \times R_d \times g_m \times R_e - \frac{R_2}{R_2 + R_5}\right)}{1 + R_b \times \left(g_m \times R_c \times g_m \times R_d \times g_m \times R_e - \frac{R_2}{R_2 + R_5}\right) \times \frac{1}{R_2}}$$
$$= \frac{-R_b \times \left(g_m \times R_c \times g_m \times R_d \times g_m \times R_e - \frac{R_2}{R_2 + R_5}\right)}{1 + \left[-R_b \times \left(g_m \times R_c \times g_m \times R_d \times g_m \times R_e - \frac{R_2}{R_2 + R_5}\right)\right] \times \frac{-1}{R_2}}$$

This is of the form

$$\frac{i_{e2}}{v_1} = \frac{A}{1+Ab}$$

where A and b are given by

$$A = -R_b \times \left( g_m \times R_c \times g_m \times R_d \times g_m \times R_e - \frac{R_5}{R_2 + R_5} \right)$$
  
$$= -R_1 \|R_2\| r_\pi \times \left( g_m \times R_3 \|r_\pi \times g_m \times R_4\| r_\pi \times g_m \times R_2 \|R_5 - \frac{R_5}{R_2 + R_5} \right)$$
  
$$= -7.073 \,\mathrm{M}\Omega$$

$$b = \frac{-1}{R_2} = -50\,\mu\mathrm{S}$$

Notice that the product Ab is dimensionless and positive. The latter must be true for the feedback to be negative.

Numerical evaluation of the transresistance gain yields

$$\frac{v_2}{i_1} = \frac{A}{\Delta} = -19.94\,\mathrm{k}\Omega$$

The resistances  $R_a$  and  $R_A$  are

$$\begin{split} R_{a} &= \frac{v_{b1}}{i_{1}} = \frac{R_{c}}{\Delta} = 1.945\,\Omega \\ R_{A} &= R_{1} + \left(\frac{1}{R_{a}} - \frac{1}{R_{1}}\right)^{-1} = 1.002\,\mathrm{k}\Omega \end{split}$$

The resistance  $R_B$  is

$$R_B = \frac{v_2}{i_t} = \frac{R_e}{\Delta} = 11.28\,\Omega$$

The voltage gain is

$$\frac{v_2}{v_{b1}} = \frac{v_2}{i_1} \times \left(\frac{v_{b1}}{i_1}\right)^{-1} = \left(\frac{A}{\Delta}\right) \times \frac{1}{R_A} = -19.91$$

## Shunt-Shunt Example 4

A shunt-shunt feedback BJT amplifier is shown in Fig. 17. The input variable is the  $v_1$  and the output variable is the voltage  $v_2$ . The feedback resistor is  $R_2$ . The summing at the input is shunt because the input through  $R_1$  and the feedback through  $R_2$  connect in shunt to the same node, i.e. the  $v_{e1}$  node. The output sampling is shunt because  $R_2$  connects to the output node. Solve for the voltage gain  $v_2/v_1$ , the input resistance  $R_A$ , and the output resistance  $R_B$ . For  $Q_1$  and  $Q_2$ , assume  $\beta = 100$ ,  $r_{\pi} = 2.5 \text{ k}\Omega$ ,  $g_m = \beta/r_{\pi}$ ,  $\alpha = \beta/(1+\beta)$ ,  $r_e = \alpha/g_m$ ,  $r_0 = \infty$ ,  $r_x = 0$ ,  $V_T = 25 \text{ mV}$ . For  $J_3$ , assume  $g_{m3} = 0.001 \text{ S}$  and  $r_{03} = \infty$ . The resistor values are  $R_1 = 1 \text{ k}\Omega$ ,  $R_2 = 100 \text{ k}\Omega$ ,  $R_3 = 10 \Omega$ ,  $R_4 = 30 \text{ k}\Omega$ , and  $R_5 = 10 \text{ k}\Omega$ .



Figure 17: Amplifier circuit.

The circuit with feedback removed is shown in Fig. 18. A test current source  $i_t$  is added in shunt with the output to solve for the output resistance  $R_B$ . In the circuit, the source is replaced by a Norton equivalent circuit consisting of a current

$$i_1 = \frac{v_1}{R_1}$$

in parallel with the resistor  $R_1$ . This is necessary for the feedback analysis to conform to convention for shunt summing. The circuit seen looking into  $R_2$  from the collector of  $Q_3$  is replaced with a Thévenin equivalent circuit made with respect with  $v_{e1}$ .



Figure 18: Circuit with feedback removed.

For the circuit with feedback removed, we can write

$$i_{e} = i_{1} + \frac{v_{2}}{R_{2}} \qquad v_{e1} = i_{e}R_{b} \qquad R_{b} = R_{1}||R_{2}||r_{e1} \qquad i_{c1} = g_{m1}v_{e1} \qquad v_{tg3} = i_{c1}R_{3}$$
$$i_{d3} = g_{m3}v_{tg3} \qquad v_{tb2} = -i_{d3}R_{4} \qquad i_{e2} = -G_{1}v_{tb2} \qquad G_{1} = \frac{1}{r'_{e2} + R_{2}||R_{5}} \qquad r'_{e2} = \frac{1}{R_{4}} + r_{e2}$$
$$v_{2} = (-i_{e2} + i_{t})R_{c} + v_{e1}\frac{R_{5}}{R_{2} + R_{5}} \qquad R_{c} = R_{2}||R_{5}$$

The equations can be solved algebraically or by a flow graph. The flow graph for the equations is shown in Fig. 19. The determinant is

$$\Delta = 1 - R_b \times \left( g_{m1} \times R_3 \times g_{m2} \times -R_4 \times -G_1 \times -R_c + \frac{R_5}{R_2 + R_5} \right) \times \frac{1}{R_2}$$
  
= 1 + R\_b \times \left( g\_{m1} \times R\_3 \times g\_{m2} \times R\_4 \times G\_1 \times R\_c - \frac{R\_5}{R\_2 + R\_5} \right) \times \frac{1}{R\_2}  
= 113.0



Figure 19: Signal-flow graph for the equations.

The transresistance gain is

$$\frac{v_2}{i_1} = \frac{R_b \times \left(g_{m1} \times R_3 \times g_{m2} \times -R_4 \times -G_1 \times -R_c + \frac{R_2}{R_2 + R_5}\right)}{\Delta}$$

$$= \frac{-R_b \times \left(g_{m1} \times R_3 \times g_{m2} \times R_4 \times G_1 \times R_c - \frac{R_2}{R_2 + R_5}\right)}{1 + R_b \times \left(g_{m1} \times R_3 \times g_{m2} \times R_4 \times G_1 \times R_c - \frac{R_2}{R_2 + R_5}\right) \times \frac{1}{R_2}}$$

$$= \frac{-R_b \times \left(g_{m1} \times R_3 \times g_{m2} \times R_4 \times G_1 \times R_c - \frac{R_2}{R_2 + R_5}\right)}{1 + \left[-R_b \times \left(g_{m1} \times R_3 \times g_{m2} \times R_4 \times G_1 \times R_c - \frac{R_2}{R_2 + R_5} - \frac{R_2}{R_2 + R_5}\right)\right] \times \frac{-1}{R_2}}$$

This is of the form

$$\frac{i_{e2}}{v_1} = \frac{A}{1+Ab}$$

where A and b are given by

$$A = -R_b \times \left( g_{m1} \times R_3 \times g_{m2} \times R_4 \times G_1 \times R_c - \frac{R_2}{R_2 + R_5} \right)$$
  
=  $-R_1 \|R_2\|_{r_{e1}} \times \left( g_{m1} \times R_3 \times g_{m2} \times R_4 \times \frac{1}{r'_{e2} + R_2} \|R_5 - \frac{R_5}{R_2 + R_5} \right)$   
=  $-11.2 \,\mathrm{M\Omega}$ 

$$b = \frac{-1}{R_2} = -10\,\mu\text{S}$$

Notice that the product Ab is dimensionless and positive. The latter must be true for the feedback to be negative.

Numerical evaluation of the transresistance gain yields

$$\frac{v_2}{i_1} = \frac{A}{\Delta} = -99.11 \,\mathrm{k}\Omega$$

The resistances  $R_a$  and  $R_A$  are

$$R_a = \frac{v_{e1}}{i_1} = \frac{R_b}{\Delta} = 0.214 \,\Omega$$
$$R_A = R_1 + \left(\frac{1}{R_a} - \frac{1}{R_1}\right)^{-1} = 1 \,\mathrm{k}\Omega$$

ъ

The resistance  $R_B$  is

$$R_B = \frac{v_2}{i_t} = \frac{R_c}{\Delta} = 80.49\,\Omega$$

The voltage gain is

$$\frac{v_2}{v_{e1}} = \frac{v_2}{i_1} \times \left(\frac{v_{e1}}{i_1}\right)^{-1} = \left(\frac{A}{\Delta}\right) \times \frac{1}{R_A} = -99.09$$

## Series-Series Example 1

Figure 20(a) shows the ac signal circuit of a series-series feedback amplifier. The input variable is  $v_1$  and the output variable is  $i_{d2}$ . The input signal is applied to the gate of  $M_1$  and the feedback signal is applied to the source of  $M_1$ . Fig. 20(b) shows the circuit with feedback removed. A test voltage source  $v_t$  is added in series with the output to calculate the output resistance  $R_b$ . The feedback at the source of  $M_1$  is modeled by a Thévenin equivalent circuit. The feedback factor or feedback ratio b is the coefficient of  $i_{d2}$  in this source, i.e.  $b = R_5$ . The circuit values are  $g_m = 0.001 \text{ S}$ ,  $r_s = g_m^{-1} = 1 \text{ k}\Omega$ ,  $r_0 = \infty$ ,  $R_1 = 50 \text{ k}\Omega$ ,  $R_2 = 10 \text{ k}\Omega$ ,  $R_3 = 1 \text{ k}\Omega$ ,  $R_4 = 9 \text{ k}\Omega$ , and  $R_5 = 1 \text{ k}\Omega$ .



Figure 20: (a) Amplifier circuit. (b) Circuit with feedback removed.

The following equations can be written for the circuit with feedback removed:

$$i_{d1} = G_{m1}v_a \qquad G_{m1} = \frac{1}{r_{s1} + R_5} \qquad v_a = v_1 - v_{ts1} \qquad v_{ts1} = i_{d2}R_5$$
$$i_{d2} = G_{m2}v_b \qquad G_{m2} = \frac{1}{r_{s2} + R_3} \qquad v_b = v_t - v_{tg2} \qquad v_{tg2} = -i_{d1}R_2$$

The voltage  $v_a$  is the error voltage. The negative feedback tends to reduce  $v_a$ , making  $|v_a| \to 0$  as the amount of feedback becomes infinite. When this is the case, setting  $v_a = 0$  yields the transconductance gain  $i_{d2}/v_1 = b^{-1} = R_5^{-1}$ . Although the equations can be solved algebraically, the signal-flow graph simplifies the solution.

Figure 21 shows the signal-flow graph for the equations. The determinant of the graph is given by

$$\Delta = 1 - G_{m1} \times (-R_2) \times (-1) \times G_{m2} \times R_5 \times (-1)$$



Figure 21: Flow graph for the equations.

The transconductance gain  $i_{d2}/v_1$  is calculated with  $v_t = 0$ . It is given by

$$\frac{i_{d2}}{v_1} = \frac{G_{m1} \times (-R_2) \times (-1) \times G_{m2}}{\Delta}$$
$$= \frac{\frac{1}{r_{s1} + R_5} \times R_2 \times \frac{1}{r_{s1} + R_5}}{1 + \frac{1}{r_{s1} + R_5} \times R_2 \times \frac{1}{r_{s1} + R_5} \times R_5}$$

This is of the form

where

$$\frac{i_{d2}}{v_1} = \frac{A}{1+Ab}$$

$$A = G_{m1} \times (-R_2) \times (-1) \times G_{m2} = \frac{1}{r_{s1} + R_5} \times R_2 \times \frac{1}{r_{s2} + R_3} = 2.5 \times 10^{-3} \,\mathrm{S}$$
$$b = R_5 = 1000 \,\Omega$$

Note that bA is dimensionless. Numerical evaluation yields

$$\frac{i_{d2}}{v_1} = \frac{2.5 \times 10^{-3}}{1 + 1000 \times 2.5 \times 10^{-3}} = 7.124 \times 10^{-4} \,\mathrm{S}$$

The resistance  $R_b$  is calculated with  $v_1 = 0$ . It is given by

$$R_{b} = \left(\frac{i_{d2}}{v_{t}}\right)^{-1} = \left(\frac{G_{m2}}{\Delta}\right)^{-1} = (1 + bA)(r_{s2} + R_{3}) = 7\,\mathrm{k}\Omega$$

Note that the feedback tends to increase  $R_b$ . The resistance  $R_B$  is calculated as follows:

$$R_B = (R_b - R_3) ||R_3 = 857.1 \,\Omega$$

Because the gate current of  $M_1$  is zero, the input resistance is  $R_A = R_1 = 50 \text{ k}\Omega$ .

## Series-Series Example 2

A series-series feedback BJT amplifier is shown in Fig. 22. The input variable is the voltage  $v_1$  and the output variable is the voltage  $v_2$ . The feedback is from  $i_{e2}$  to the emitter of  $Q_1$ . Because the feedback does not connect to the input node, the input summing is series. The output sampling is series because the feedback is proportional to the current that flows in series with the output rather than the output voltage. Solve for the transconductance gain  $i_{c3}/v_1$ , the voltage gain  $v_2/v_1$ , the input resistance  $R_A$ , and the output resistance  $R_B$ . Assume  $\beta = 100$ ,  $I_{C1} = 0.6 \text{ mA}$ ,  $I_{C2} = 1 \text{ mA}$ ,  $I_{C3} = 4 \text{ mA}$ ,  $\alpha = \beta/(1+\beta)$ ,  $g_m = I_C/V_T$ ,  $r_e = \alpha V_T/I_C$ ,  $r_0 = \infty$ ,  $r_x = 0$ ,  $V_T = 25 \text{ mV}$ ,  $R_1 = 100 \Omega$ ,  $R_2 = 9 \text{ k}\Omega$ ,  $R_3 = 5 \text{ k}\Omega$ ,  $R_4 = 600 \Omega$ ,  $R_5 = 640 \Omega$ , and  $R_6 = 100 \Omega$ . The circuit with feedback removed is shown in Fig. 23.



Figure 22: Amplifier circuit.

The circuit looking out of the emitter of  $Q_1$  is a Thévenin equivalent made with respect to the current  $i_{e3}$ . The output current is proportional to this current, i.e.  $i_{c3} = \alpha i_{e3}$ . Because  $r_0 = \infty$  for  $Q_3$ , the feedback does not affect the output resistance seen looking down through  $R_4$  because it is infinite. For a finite  $r_0$ , a test voltage source can be added in series with  $R_4$  to solve for this resistance. It would be found that a finite  $r_0$  for  $Q_3$  considerably complicates the circuit equations and the flow graph.



Figure 23: Circuit with feedback removed.

For the circuit with feedback removed, we can write

$$\begin{aligned} v_e &= v_1 - i_{e3} \frac{R_6 R_1}{R_6 + R_5 + R_1} & i_{e1} = G_1 v_e & G_1 = \frac{1}{r_{e1} + R_1 \| (R_5 + R_6)} & i_{c1} = \alpha i_{e1} \\ i_{b1} &= \frac{i_{c1}}{\beta} & v_{tb2} = -i_{c1} R_2 & i_{e2} = G_2 v_{tb2} & G_2 = \frac{1}{r'_{e2}} & r'_{e2} = \frac{R_2}{1 + \beta} + r_e \\ i_{c2} &= \alpha i_{e2} & v_{tb3} = -i_{c2} R_3 & i_{e3} = G_3 v_{tb3} - k_1 i_{e1} & G_3 = \frac{1}{r'_{e3} + R_6 \| (R_1 + R_5)} \\ k_1 &= \frac{R_1}{R_1 + R_5 + r'_{e3} \| R_6} \frac{R_6}{R_6 + r'_{e3}} & i_{c3} = \alpha i_{e3} & v_2 = -i_{c2} R_4 \end{aligned}$$

The equations can be solved algebraically or by a flow graph. The flow graph for the equations is shown in Fig. 24. The determinant is

$$\Delta = 1 - \left\{ G_1 \times \left[ (\alpha \times -R_2 \times G_2 \times \alpha \times -R_3 \times G_3) - k_1 \right] \times \frac{-R_6 R_1}{R_6 + R_5 + R_1} \right\}$$
$$= 1 + G_1 \times (\alpha \times R_2 \times G_2 \times \alpha \times R_a - k_1) \times \frac{R_6 R_1}{R_6 + R_5 + R_1}$$
$$= 251.5$$



Figure 24: Signal-flow graph for the circuit.

The transconductance gain is

$$\begin{aligned} \frac{i_{c3}}{v_1} &= \frac{G_1 \times (\alpha \times -R_2 \times G_2 \times \alpha \times -R_3 \times G_3 - k_1) \times \alpha}{\Delta} \\ &= \frac{G_1 \times (\alpha \times R_2 \times G_2 \times \alpha \times R_3 \times G_3 - k_1) \times \alpha}{1 + [G_1 \times (\alpha \times R_2 \times G_2 \times \alpha \times R_a - k_1)] \times \frac{R_6 R_1}{R_6 + R_5 + R_1}} \\ &= \frac{G_1 \times [(\alpha \times R_2 \times G_2 \times \alpha \times R_3 \times G_3) - k_1] \times \alpha}{1 + [G_1 \times (\alpha \times R_2 \times G_2 \times \alpha \times R_a - k_1) \times \alpha] \times \frac{R_6 R_1}{R_6 + R_5 + R_1} \times \frac{1}{\alpha}} \end{aligned}$$

This is of the form

$$\frac{i_{c3}}{v_1} = \frac{A}{1+Ab}$$

where A and b are given by

$$A = G_1 \times \left[ (\alpha \times R_2 \times G_2 \times \alpha \times R_3 \times G_3) - k_1 \right] \times \alpha$$
  
=  $\frac{1}{r_{e_1} + R_1 \| (R_5 + R_6)} \times \left[ \left( \alpha \times R_2 \times \frac{1}{r'_{e_2}} \times \alpha \times R_3 \times \frac{1}{r'_{e_3} + R_6 \| (R_1 + R_5)} \times \alpha \right) - \frac{R_1}{R_1 + R_5 + r'_{e_3} \| R_6} \frac{R_6}{R_6 + r'_{e_3}} \right] \times \alpha$   
= 20.83 S

$$b = \frac{R_6 R_1}{R_6 + R_5 + R_1} \times \frac{1}{\alpha} = 12.02\,\Omega$$

Notice that the product Ab is dimensionless and positive. The latter must be true for the feedback to be negative.

Numerical evaluation of the transconductance gain yields

$$\frac{i_{c3}}{v_1} = \frac{A}{\Delta} = 0.083$$

The voltage gain is given by

$$\frac{v_2}{v_1} = \frac{i_{c3}}{v_1} \times \frac{v_2}{i_{c3}} = \frac{A}{\Delta} \times -R_4 = -49.7$$

The resistances  $R_A$  and  $R_B$  are given by

$$R_{A} = \left(\frac{i_{b1}}{v_{1}}\right)^{-1} = \left(\frac{G_{1}\alpha/\beta}{\Delta}\right)^{-1} = \frac{\Delta \times (1+\beta)}{G_{1}} = \Delta \times (1+\beta) \times [r_{e1} + R_{1} \| (R_{5} + R_{6})] = 3.285 \,\mathrm{M}\Omega$$
$$R_{B} = R_{4} = 600 \,\Omega$$

### Series-Series Example 3

A series-series feedback BJT amplifier is shown in Fig. 25(a). The input variable is the voltage  $v_1$  and the output variable is the voltage  $v_2$ . The feedback is from  $i_{e2}$  to  $i_{c2}$  to the emitter of  $Q_1$ . Because the feedback does not connect to the input node, the input summing is series. Because the feedback does not sample the output voltage, the sampling is series. That is, the feedback network samples the current in series with the output. Solve for the transconductance gain  $i_{e2}/v_1$ , the voltage gain  $v_2/v_1$ , the input resistance  $R_A$ , and the output resistance  $R_B$ . Assume  $\beta = 100$ ,  $r_{\pi} = 2.5 \,\mathrm{k\Omega}$ ,  $\alpha = \beta/(1+\beta)$ ,  $r_e = \alpha/g_m$ ,  $r_0 = \infty$ ,  $r_x = 0$ ,  $V_T = 25 \,\mathrm{mV}$ ,  $R_1 = 100 \,\Omega$ ,  $R_2 = 1 \,\mathrm{k\Omega}$ ,  $R_3 = 20 \,\mathrm{k\Omega}$ , and  $R_4 = 10 \,\mathrm{k\Omega}$ .



Figure 25: (a) Amplifier circuit. (b) Circuit with feedback removed.

The circuit with feedback removed is shown in Fig. 25(b). The circuit seen looking out of the emitter of  $Q_1$  is replaced with a Thévenin equivalent circuit made with respect with  $i_{c2}$ . The output current  $i_{e2}$  is proportional to this current, i.e.  $i_{e2} = \alpha i_{c2}$ . A test voltage source  $v_t$  is added in series with the output to solve for the output resistance. The resistance seen by the test source is labeled  $R_b$ .

For the circuit with feedback removed, we can write

$$v_e = v_1 - i_{c2}R_2$$
  $i_{e1} = G_1 v_e$   $G_1 = \frac{1}{r_e + R_1 + R_2}$   $i_{c1} = \alpha i_{e1}$   $i_{b1} = \frac{i_{c1}}{\beta}$ 

$$v_{tb2} = -i_{c1}R_3 \qquad i_{e2} = G_2 \left( v_t - v_{tb2} \right) \qquad G_2 = \frac{1}{r'_{e2} + R_4} \qquad r'_{e2} = \frac{R_3}{1 + \beta} + r_e \qquad i_{c2} = \alpha i_{e2}$$

The equations can be solved algebraically or by a flow graph. The flow graph for the equations is shown in Fig. 26. The determinant is

$$\Delta = 1 - (G_1 \times \alpha \times -R_3 \times -G_2 \times \alpha \times -R_2)$$
  
= 1 + G\_1 \times \alpha \times R\_2 \times G\_2 \times \alpha \times R\_2  
= 1.181

v1 
$$\bullet$$
 ie1  $\alpha$   $\uparrow$   $\frac{1}{\beta}$  vtb2 ie2 G2  
G1 ic1 -R2 -G2  $\downarrow$   $\alpha$   
ic2 -R2

Figure 26: Signal-flow graph for the equations.

The transconductance gain is

$$\begin{aligned} \frac{i_{e2}}{v_1} &= \frac{G_1 \times \alpha \times -R_3 \times -G_2}{\Delta} \\ &= \frac{(G_1 \times \alpha \times R_3 \times G_2)}{1 + (G_1 \times \alpha \times R_3 \times G_2) \times \alpha \times R_2} \end{aligned}$$

This is of the form

$$\frac{i_{e2}}{v_1} = \frac{A}{1+Ab}$$

where A and b are given by

$$A = G_1 \times \alpha \times R_3 \times G_2$$
  
= 
$$\frac{1}{r_{e1} + R_1 + R_2} \times \alpha \times R_3 \times \frac{1}{r'_{e2} + R_4}$$
  
= 
$$0.9117 \text{ mS}$$
  
$$b = \alpha R_2 = 1.98 \text{ k}\Omega$$

Notice that the product Ab is dimensionless and positive. The latter must be true for the feedback to be negative.

Numerical evaluation of the transconductance gain yields

$$\frac{i_{e2}}{v_1} = \frac{A}{\Delta} = 0.325 \,\mathrm{mS}$$

The voltage gain is given by

$$\frac{v_2}{v_1} = \frac{i_{e2}}{v_1} \times \frac{v_2}{i_{e2}} = \frac{A}{\Delta} \times -R_4 = -3.25$$

The resistances  $R_A$  and  $R_B$  are given by

$$R_A = \left(\frac{i_{b1}}{v_1}\right)^{-1} = \left(\frac{G_1 \alpha/\beta}{\Delta}\right)^{-1} = \Delta \times (1+\beta) \left(r_e + R_1 + R_2\right) = 602 \,\mathrm{k\Omega}$$
$$R_b = \left(\frac{i_{e2}}{v_t}\right)^{-1} = \left(\frac{G_{m2}}{\Delta}\right)^{-1} = \Delta \times (R_4 + r'_{e2}) = 28.68 \,\mathrm{k\Omega}$$
$$R_B = (R_b - R_4) \,\|R_4 = 6.513 \,\mathrm{k\Omega}$$

### Series-Series Example 4

A series-series feedback BJT amplifier is shown in Fig. 27(a). The input variable is the voltage  $v_1$  and the output variable is the current  $i_{c2}$ . The feedback is from  $i_{c2}$  to  $i_{e2}$  to the gate of  $J_1$ . The input summing is series because the feedback does not connect to the same node that the source connects. The output sampling is series because the feedback is proportional to the output current  $i_{c2}$ . Solve for the transconductance gain  $i_{c2}/v_1$ , the voltage gain  $v_2/v_1$ , the input resistance  $R_A$ , and the output resistance  $R_B$ . For  $J_1$ , assume that  $g_{m1} = 0.001 \text{ S}, r_{s1} = g_{m1}^{-1} = 1000 \Omega$ , and  $r_{01} = \infty$ . For  $Q_2$ , assume  $\beta_2 = 100, r_{\pi 2} = 2.5 \text{ k}\Omega, \alpha_2 = \beta_2/(1 + \beta_2), r_{e2} = \alpha_2/g_{m2}, r_{02} = \infty, r_{x2} = 0, V_T = 25 \text{ mV}$ . The resistor values are  $R_1 = 1 \text{ k}\Omega, R_2 = 10 \text{ k}\Omega, R_3 = 1 \text{ k}\Omega, R_4 = 10 \text{ k}\Omega, R_5 = 1 \text{ k}\Omega$ , and  $R_6 = 10 \text{ k}\Omega$ .



Figure 27: (a) Amplifier circuit. (b) Circuit with feedback removed.

The circuit with feedback removed is shown in Fig. 27(b). The circuit seen looking out of the emitter of  $Q_1$  is replaced with a Thévenin equivalent circuit made with respect with  $i_{e2}$ . The output current is proportional to this current, i.e.  $i_{c2} = \alpha_2 i_{e2}$ . Because  $r_{02} = \infty$ , the feedback does not affect the output resistance seen looking down through  $R_6$  because it is infinite. For a finite  $r_{02}$ , a test voltage source can be added in series with  $R_6$  to solve for this resistance. It would be found that a finite  $r_{02}$  considerably complicates the circuit equations and the flow graph.

For the circuit with feedback removed, we can write

4

$$i_{d1} = g_{m1}v_e \qquad v_e = i_{e2}\frac{R_5R_3}{R_3 + R_4 + R_5} - v_1 \qquad v_{tb2} = -i_{d1}R_2 \qquad i_{e2} = G_1v_{tb2}$$
$$G_1 = \frac{1}{r'_{e2} + R_5 \| (R_3 + R_4)} \qquad r'_{e2} = \frac{R_2}{1 + \beta_2} + r_{e2} \qquad i_{c2} = \alpha_2 i_{e2}$$

The equations can be solved algebraically or by a flow graph. The flow graph for the equations is shown in Fig. 28. The determinant is

$$\Delta = 1 - \left(g_{m1} \times -R_2 \times G_1 \times \frac{R_5 R_3}{R_3 + R_4 + R_5}\right)$$
  
= 1 + g\_{m1} \times R\_2 \times G\_1 \times \frac{R\_5 R\_3}{R\_3 + R\_4 + R\_5}  
= 1.801

v1 
$$\rightarrow$$
 1 ve gm1  $-R2$  G1 ie2  $\alpha 2$   
id1 vtb2  $\frac{R5 R3}{R3+R4+R5}$ 

Figure 28: Signal-flow graph for the equations.

The transconductance gain is

$$\frac{i_{e2}}{v_1} = \frac{-1 \times g_{m1} \times -R_2 \times G_1 \times \alpha_2}{\Delta}$$
$$= \frac{g_{m1} \times R_2 \times G_1 \times \alpha_2}{1 + g_{m1} \times R_2 \times G_1 \times \frac{R_5 R_3}{R_3 + R_4 + R_5}}$$
$$= \frac{(g_{m1} \times R_2 \times G_1 \times \alpha_2)}{1 + (g_{m1} \times R_2 \times G_1 \times \alpha_2) \times \frac{R_5 R_3}{R_3 + R_4 + R_5} \times \frac{1}{\alpha_2}}$$

This is of the form

$$\frac{i_{e2}}{v_1} = \frac{A}{1+Ab}$$

where A and b are given by

$$A = g_{m1} \times R_2 \times G_1 \times \alpha_2$$
  
=  $g_{m1} \times R_2 \times \frac{1}{r'_{e2} + R_5 \| (R_3 + R_4)} \times \alpha_2$   
= 9.516 mS  
 $b = \frac{R_5 R_3}{R_3 + R_4 + R_5} \times \frac{1}{\alpha_2} = 84.17 \,\Omega$ 

Notice that the product Ab is dimensionless and positive. The latter must be true for the feedback to be negative.

Numerical evaluation of the transconductance gain yields

$$\frac{i_{c2}}{v_1} = \frac{A}{\Delta} = 5.284 \,\mathrm{mS}$$

The voltage gain is given by

$$\frac{v_2}{v_1} = \frac{i_{c2}}{v_1} \times \frac{v_2}{i_{c2}} = \frac{A}{\Delta} \times -R_6 = -52.84$$

The resistances  $R_A$  and  $R_B$  are given by

$$R_{A} = R_{1} \left\| \left( \frac{-i_{d1}}{v_{1}} \right)^{-1} = R_{1} \left\| \left( \frac{g_{m1}}{\Delta} \right)^{-1} = R_{1} \right\| \left( \frac{\Delta}{g_{m1}} \right) = 643 \,\Omega$$
$$R_{B} = R_{6} = 10 \,\mathrm{k}\Omega$$

# Series-Series Example 5

A series-series feedback BJT amplifier is shown in Fig. 29. The input variable is the current  $i_1$  and the output variable is the current  $i_{e2}$ . The feedback path is the path from  $i_{e2}$  to  $i_{c2}$  to  $i_{e3}$  to  $i_{c3}$  to the emitter of  $Q_1$ . The input summing is series because the feedback does not connect to the input node. The output

sampling is series because the feedback is proportional to the output current  $i_{e2}$  and not the output voltage  $v_2$ . Solve for the current gain gain  $i_{e2}/i_1$ , the transresistance gain  $v_2/i_1$ , the input resistance  $R_A$ , and the output resistance  $R_B$ . Assume  $\beta = 100$ ,  $r_{\pi} = 2.5 \text{ k}\Omega$ ,  $g_m = \beta/r_{\pi}$ ,  $\alpha = \beta/(1+\beta)$ ,  $r_e = \alpha/g_m$ ,  $r_0 = \infty$ ,  $r_x = 0$ ,  $V_T = 25 \text{ mV}$ . The resistor values are  $R_1 = 1 \text{ k}\Omega$ ,  $R_2 = 100 \Omega$ ,  $R_3 = 10 \text{ k}\Omega$ ,  $R_4 = 100 \Omega$ ,  $R_5 = 1 \text{ k}\Omega$ , and  $R_6 = 10 \text{ k}\Omega$ .



Figure 29: Amplifier circuit.

The circuit with feedback removed is shown in Fig. 30. The source is replaced with a Thevenin equivalent circuit consisting of a voltage

$$v_1 = i_1 R_1$$

in series with the resistor  $R_1$ . This is necessary for the feedback analysis to conform to convention for series summing at the input. The circuit seen looking out of the emitter of  $Q_1$  is replaced with a Thévenin equivalent circuit made with respect with  $i_{c3}$ . The latter is proportional to the output current  $i_{e2}$ . The relation is

$$\frac{i_{c3}}{i_{e2}} = \frac{i_{c3}}{i_{e3}} \times \frac{i_{e3}}{i_{c2}} \times \frac{i_{c2}}{i_{e2}} = \alpha \times \frac{R_3}{R_3 + R_4 + r_{e3}} \times \alpha$$

Note that  $r_{e3}$  in this equation is the small-signal resistance seen looking into the emitter of  $Q_3$ .



Figure 30: Circuit with feedback removed.

For the circuit with feedback removed, we can write

$$v_{e} = v_{1} - i_{c3}R_{2} \qquad i_{e1} = G_{1}v_{e} \qquad G_{1} = \frac{1}{r'_{e1} + R_{2}} \qquad r'_{e1} = \frac{R_{1}}{1 + \beta} + r_{e} \qquad i_{c1} = \alpha i_{e1} \qquad i_{b1} = \frac{i_{c1}}{\beta}$$

$$v_{tb2} = -i_{c1}R_{6} \qquad i_{e2} = G_{2}(v_{t} - v_{tb2}) \qquad G_{2} = \frac{1}{r'_{e2} + R_{5}} \qquad r'_{e2} = \frac{R_{6}}{1 + \beta} + r_{e}$$

$$i_{c2} = \alpha i_{e2} \qquad i_{e3} = i_{c2}\frac{R_{3}}{R_{3} + R_{4} + r_{e}} \qquad i_{c3} = \alpha i_{e3}$$

$$v_{1} \bullet \underbrace{1 \qquad ve \qquad ie1 \qquad ic1 \qquad vtb2 \qquad ie2 \quad G_{2}}_{ic3} \bullet vt$$

$$v_{1} \bullet \underbrace{-R_{2} \qquad G_{1} \qquad \alpha \qquad \frac{1}{\beta} \qquad -R_{6} \qquad -G_{2}}_{ib1} \qquad \alpha \qquad ic2$$

$$r_{1} \bullet \underbrace{R_{3}}_{R_{3} + R_{4} + r_{e}} \qquad i_{c2}$$

Figure 31: Signal-flow graph for the equations.

The equations can be solved algebraically or by a flow graph. The flow graph for the equations is shown in Fig. 31. The determinant is

$$\Delta = 1 - G_1 \times \alpha \times -R_6 \times -G_2 \times \alpha \times \frac{R_3}{R_3 + R_4 + r_e} \times \alpha \times R_2$$
  
= 1 + G<sub>1</sub> × \alpha × R\_6 × G<sub>2</sub> × \alpha × \frac{R\_3}{R\_3 + R\_4 + r\_e} × \alpha × R\_2  
= 7.335

The transconductance gain is

$$\begin{array}{ll} \displaystyle \frac{i_{e2}}{v_1} & = & \displaystyle \frac{1 \times G_1 \times \alpha \times -R_6 \times -G_2}{\Delta} \\ \\ \displaystyle & = & \displaystyle \frac{G_1 \times \alpha \times R_6 \times G_2}{1 + G_1 \times \alpha \times R_6 \times G_2 \times \alpha \times \frac{R_3}{R_3 + R_4 + r_e} \times \alpha \times R_2} \end{array}$$

This is of the form

$$\frac{i_{e2}}{v_1} = \frac{A}{1+Ab}$$

where A and b are given by

$$A = G_1 \times \alpha \times R_6 \times G_2$$
  
=  $\frac{1}{r'_{e1} + R_2} \times \alpha \times R_6 \times \frac{1}{r'_{e2} + R_5}$   
= 65.43 mS  
$$b = \alpha \times \frac{R_3}{R_3 + R_4 + r_e} \times \alpha \times R_2 = 96.82 \Omega$$

Notice that the product Ab is dimensionless and positive. The latter must be true for the feedback to be negative.

Numerical evaluation of the transconductance gain yields

$$\frac{i_{e2}}{v_1} = \frac{A}{\Delta} = 8.92 \,\mathrm{mS}$$

The current gain is given by

$$\frac{i_{e2}}{i_1} = \frac{i_{e2}}{v_1} \times \frac{v_1}{i_1} = \frac{A}{\Delta} \times R_1 = 8.92$$

The transresistance gain is

$$R_m = \frac{v_2}{i_1} = \frac{i_{e2}}{i_1} \times \frac{v_2}{i_{e2}} = \frac{A}{\Delta} \times R_1 \times -R_5 = -8.92 \,\mathrm{k}\Omega$$

The resistances  $R_a$  and  $R_A$ 

$$R_{a} = \left(\frac{i_{b1}}{v_{1}}\right)^{-1} = \left(\frac{G_{1}\alpha/\beta}{\Delta}\right)^{-1} = \Delta \times [R_{1} + r_{\pi} + (1+\beta)R_{2}] = 113.3 \,\mathrm{k\Omega}$$
$$R_{A} = \frac{v_{b1}}{i_{1}} = (R_{a} - R_{1}) \,\|R_{1} = 991.2 \,\Omega$$

The voltage gain is

$$\frac{v_2}{v_{b1}} = \frac{v_2}{i_1} \times \left(\frac{v_{b1}}{i_1}\right)^{-1} = \left(\frac{A}{\Delta} \times R_1\right) \times \frac{1}{R_A} = -990$$

The resistances  $R_b$  and  $R_B$  are

$$R_b = \left(\frac{i_{e2}}{v_t}\right)^{-1} = \left(\frac{G_2}{\Delta}\right)^{-1} = \Delta \times (r'_{e2} + R_5) = 10.98 \,\mathrm{k\Omega}$$
$$R_B = (R_b - R_5) \,\|R_5 = 889.5 \,\Omega$$

### Shunt-Series Example 1

Figure 32(a) shows the ac signal circuit of a shunt-series feedback amplifier. The input variable is  $v_1$  and the output variable is  $i_{d2}$ . The input signal and the feedback signal are applied to the source of  $M_1$ . A test voltage source  $v_t$  is added in series with the output to calculate the output resistance  $R_b$ . For the analysis to follow convention, the input source consisting of  $v_1$  in series with  $R_1$  must be converted into a Norton equivalent. This circuit is the current

$$i_1 = \frac{v_1}{R_1}$$

in parallel with the resistor  $R_1$ . Fig. 32(b) shows the circuit with feedback removed and the source replaced with the Norton equivalent. A test source  $v_t$  is added in series with the output to calculate the resistance  $R_b$ . The feedback at the source of  $M_1$  is modeled by a Norton equivalent circuit  $i_{d2}$  in parallel with the resistor  $R_4$ . The feedback is from the output current  $i_{d2}$  to the source of  $M_1$ . The circuit values are  $g_m = 0.001$  S,  $r_s = g_m^{-1} = 1 \text{ k}\Omega$ ,  $r_0 = \infty$ ,  $R_1 = 10 \text{ k}\Omega$ ,  $R_2 = 20 \text{ k}\Omega$ ,  $R_3 = 1 \text{ k}\Omega$ ,  $R_4 = 1 \text{ k}\Omega$ , and  $R_5 = 1 \text{ k}\Omega$ .

The following equations can be written for the circuit with feedback removed:

$$v_{s1} = i_a R_c \qquad i_a = i_1 + i_{d2} \qquad R_c = R_1 ||R_4||r_{s1} \qquad i_{d1} = -g_{m1} v_{s1}$$
$$i_{d2} = G_{m2} v_b \qquad G_{m2} = \frac{1}{r_{s2} + R_3} \qquad v_b = v_t - v_{tg2} \qquad v_{tg2} = -i_{d1} R_2$$

The current  $i_a$  is the error current. The negative feedback tends to reduce  $i_a$ , making  $|i_a| \rightarrow 0$  as the amount of feedback becomes infinite. When this is the case, setting  $i_a = 0$  yields the current gain  $i_{d2}/i_1 = -1$ .

Although the equations can be solved algebraically, the signal-flow graph simplifies the solution. Fig. 33 shows the flow graph for the equations. The determinant of the graph is given by

$$\Delta = 1 - R_c \times (-g_{m1}) \times (-R_2) \times (-1) \times G_{m2} \times 1$$

The current gain is calculated with  $v_t = 0$ . It is given by

$$\frac{i_{d2}}{i_1} = \frac{R_c \times (-g_{m1}) \times (-R_2) \times (-1) \times G_{m2}}{\Delta}$$
$$= -\frac{R_1 \|R_4\| r_{s1} \times g_{m1} \times R_2 \times \frac{1}{r_{s2} + R_3}}{1 + R_c \times g_{m1} \times R_2 \times \frac{1}{r_{s2} + R_3} \times 1}$$



Figure 32: (a) Amplifier circuit. (b) Circuit with feedback removed.



Figure 33: Flow graph for the equations.

This is of the form

$$\frac{i_{d2}}{i_1} = \frac{A}{1+Al}$$

where

$$A = R_c \times (-g_{m1}) \times (-R_2) \times (-1) \times G_{m2} = -(R_1 || R_4 || r_{s1}) \times g_{m1} \times R_2 \times \frac{1}{r_{s2} + R_3} = -0.3333$$
$$b = -1$$

Note that Ab is dimensionless. Numerical evaluation yields

$$\frac{i_{d2}}{i_1} = \frac{2.5 \times 10^{-3}}{1 + 1000 \times 2.5 \times 10^{-3}} = -0.7692$$

The voltage gain is given by

$$\frac{v_2}{v_1} = \frac{i_{d2}}{i_1} \times \frac{i_1}{v_1} \times \frac{v_2}{i_{d2}} = \frac{i_{d2}}{i_1} \times \frac{1}{R_1} \times (-R_3) = 0.7692$$

The resistance  $R_a$  is calculated with  $v_t = 0$ . It is given by

$$R_a = \frac{v_{s1}}{i_1} = \frac{R_c}{\Delta} = \frac{R_1 ||R_4||r_{s1}}{1 + 1 \times R_c \times g_{m1} \times R_2 \times \frac{1}{r_{s2} + R_3}} = 76.92\,\Omega$$

Note that the feedback tends to decrease  $R_a$ . The resistance  $R_A$  is calculated as follows:

$$R_A = R_1 + \left(R_a^{-1} - R_1^{-1}\right)^{-1} = 1.083 \,\mathrm{k\Omega}$$

The resistance  $R_b$  is calculated with  $i_1 = 0$ . It is given by

$$R_{b} = \left(\frac{i_{d2}}{v_{t}}\right)^{-1} = \left(\frac{G_{m2}}{\Delta}\right)^{-1} = (1+Ab)\left(r_{s2} + R_{3}\right) = 8.667\,\mathrm{k}\Omega$$

Note that the feedback tends to increase  $R_b$ . The resistance  $R_B$  is calculated as follows:

$$R_B = (R_b - R_3) ||R_3 = 884.6 \,\Omega$$

#### Shunt-Series Example 2

A shunt-series feedback BJT amplifier is shown in Fig. 34(a). The input variable is the voltage  $v_1$  and the output variable is the current  $i_{e2}$ . The feedback is from  $i_{e2}$  to  $i_{c2}$  to the source of  $M_1$ . The input summing is shunt because the feedback connects to the same node that the source connects. The output sampling is series because the feedback is proportional to the output current  $i_{e2}$ . Solve for the voltage gain  $v_2/v_1$ , the input resistance  $R_A$ , and the output resistance  $R_B$ . For  $M_1$ , assume that  $g_{m1} = 0.001$  S,  $r_{s1} = g_{m1}^{-1} = 1000 \Omega$ , and  $r_{01} = \infty$ . For  $Q_2$ , assume  $\beta_2 = 100$ ,  $r_{\pi 2} = 2.5 \text{ k}\Omega$ ,  $\alpha_2 = \beta_2/(1 + \beta_2)$ ,  $r_{e2} = \alpha_2/g_{m2}$ ,  $r_{02} = \infty$ ,  $r_{x2} = 0$ ,  $V_T = 25 \text{ mV}$ . The resistor values are  $R_1 = 10 \text{ k}\Omega$ ,  $R_2 = 100 \text{ k}\Omega$ ,  $R_3 = 100 \text{ k}\Omega$ ,  $R_4 = 10 \text{ k}\Omega$ , and  $R_5 = 1 \text{ k}\Omega$ . The circuit with feedback removed is shown in Fig. 34(b). The source is replaced with a Norton equivalent circuit. The current  $i_1$  is given by

$$i_1 = \frac{v_1}{R_1}$$

The circuit seen looking into  $R_2$  from the  $v_{s1}$  node is replaced with a Norton equivalent circuit made with respect with  $i_{c2}$ . The output current is proportional to this current, i.e.  $i_{c2} = \alpha_2 i_{e2}$ . A test voltage source  $v_t$  is added in series with  $i_{e2}$  to calculate the resistance  $R_b$ .

For the circuit with feedback removed, we can write

$$v_{s1} = i_a R_c \qquad i_a = i_1 - \frac{R_4}{R_2 + R_4} i_{c2} \qquad R_c = R_1 \| (R_2 + R_4) \| r_{s1} \qquad i_{d1} = g_{m1} v_{s1} \qquad v_{tb2} = i_{d1} R_3$$



Figure 34: (a) Shunt-series amplifier. (b) Amplifier with feedback removed.

$$i_{e2} = G_1 v_{tb2} - \frac{v_t}{R_d} \qquad G_1 = \frac{1}{r'_{e2} + R_5} \qquad r'_{e2} = \frac{R_3}{1 + \beta_2} + r_{e2} \qquad R_d = R_5 + r'_{e2} \qquad i_{c2} = \alpha_2 i_{e2}$$

The equations can be solved algebraically or by a flow graph. The flow graph for the equations is shown in Fig. 35. The determinant is

$$\Delta = 1 - \left(1 \times R_c \times g_{m1} \times R_3 \times G_1 \times \alpha_2 \times \frac{-R_4}{R_2 + R_4}\right)$$
$$= 1 + R_c \times g_{m1} \times R_3 \times G_1 \times \alpha_2 \times \frac{R_4}{R_2 + R_4}$$
$$= 5.025$$



Figure 35: Signal-flow graph for the equations.

The current gain is

$$\begin{split} \frac{i_{e2}}{i_1} &= \frac{R_c \times g_{m1} \times R_3 \times G_1}{\Delta} \\ &= \frac{R_c \times g_{m1} \times R_3 \times G_1}{1 + R_c \times g_{m1} \times R_3 \times G_1 \times \alpha_2 \times \frac{R_4}{R_2 + R_4}} \\ &= \frac{\left(R_1 \| \left(R_2 + R_4\right) \| r_{s1} \times g_{m1} \times R_3 \times \frac{1}{r'_{e2} + R_4}\right)}{1 + \left(R_1 \| \left(R_2 + R_4\right) \| r_{s1} \times g_{m1} \times R_3 \times \frac{1}{r'_{e2} + R_4}\right) \times \alpha_2 \times \frac{R_4}{R_2 + R_4} \end{split}$$

This is of the form

$$\frac{i_{e2}}{i_1} = \frac{A}{1+Ab}$$

where A and b are given by

$$A = R_c \times g_{m1} \times R_3 \times G_1$$
  
=  $R_1 \| (R_2 + R_4) \| r_{s1} \times g_{m1} \times R_3 \times \frac{1}{r'_{e2} + R_4}$   
= 44.75  
 $b = \alpha_2 \times \frac{R_4}{R_2 + R_4} = 0.09$ 

Notice that the product Ab is dimensionless and positive. The latter must be true for the feedback to be negative.

Numerical evaluation of the current gain yields

$$\frac{i_{e2}}{i_1} = \frac{A}{\Delta} = 8.90$$

The resistances  $R_a$  and  $R_A$  are

$$R_a = \frac{v_{s1}}{i_1} = \frac{R_c}{\Delta} = 179.3 \,\Omega$$
$$R_A = R_1 + \left(R_a^{-1} - R_1^{-1}\right)^{-1} = 10.13 \,\mathrm{k}\Omega$$

The resistance  $R_b$  and  $R_B$  are

$$R_b = \left(\frac{-i_{e2}}{v_t}\right)^{-1} = \left(\frac{1}{\Delta}\frac{1}{R_d}\right)^{-1} = \Delta R_d = 10.12 \,\mathrm{k\Omega}$$
$$R_B = (R_b - R_5) \,\|R_5 = 901.3 \,\Omega$$

The voltage gain is given by

$$\frac{v_2}{v_1} = \frac{i_{e2}}{i_1} \times \frac{v_2}{i_{e2}} \times \frac{i_1}{v_1} = \frac{A}{\Delta} \times R_2 \times \frac{1}{R_1} = 89.0$$

## Shunt-Series Example 3

A shunt-series feedback BJT amplifier is shown in Fig. 36(a). The input variable is the voltage  $v_1$  and the output variable is the current  $i_{c2}$ . The feedback is from  $i_{c2}$  to  $i_{c2}$  to  $i_{c3}$  to the emitter of  $Q_1$ . The input summing is shunt because the feedback connects to the same node that the source connects. The output sampling is series because the feedback is proportional to the output current  $i_{c2}$ . Solve for the voltage gain  $v_2/v_1$ , the input resistance  $R_A$ , and the output resistance  $R_B$ . Assume  $\beta = 100$ ,  $r_{\pi} = 2.5 \text{ k}\Omega$ ,  $\alpha = \beta/(1+\beta)$ ,  $r_e = \alpha/g_m$ ,  $r_0 = \infty$ ,  $r_x = 0$ ,  $V_T = 25 \text{ mV}$ . The resistor values are  $R_1 = R_3 = 1 \text{ k}\Omega$  and  $R_2 = R_4 = R_5 = 10 \text{ k}\Omega$ .

The circuit with feedback removed is shown in Fig. 36(b). The source is replaced with a Norton equivalent circuit consisting of the current

$$i_1 = \frac{v_1}{R_1}$$

in parallel with the resistor  $R_1$ . The feedback is modeled by a Norton equivalent circuit consisting of the current  $i_{c3}$ . Because  $r_{03} = \infty$ , the output resistance of this source is an open circuit. The output current is proportional to this current. Because  $r_{02} = \infty$ , the feedback does not affect the output resistance seen looking down through  $R_5$  because it is infinite. For a finite  $r_{02}$ , a test voltage source can be added in series with  $R_5$  to solve for this resistance. It would be found that a finite  $r_{02}$  considerably complicates the circuit equations and the flow graph.



Figure 36: (a) Amplifier circuit. (b) Circuit with feedback removed.

For the circuit with feedback removed, we can write

$$i_{a} = i_{1} - i_{c3} \qquad v_{e1} = i_{a}R_{b} \qquad R_{b} = R_{1}||R_{2}||r_{e1} \qquad i_{c1} = -g_{m1}v_{e1} \qquad i_{c2} = -\beta_{2}i_{c1} \qquad i_{e2} = \frac{i_{e2}}{\alpha_{2}}$$
$$v_{tb3} = i_{e2}R_{4} \qquad i_{e3} = G_{1}v_{tb3} \qquad G_{1} = \frac{1}{r'_{e3} + R_{3}} \qquad r'_{e3} = \frac{R_{4}}{1 + \beta_{3}} + r_{e3} \qquad i_{c3} = \alpha_{3}i_{e3}$$

The equations can be solved algebraically or by a flow graph. The flow graph for the equations is shown in Fig. 37. The determinant is

$$\Delta = 1 - \left(R_b \times -g_{m1} \times -\beta_1 \times \frac{1}{\alpha_2} \times R_4 \times G_1 \times \alpha_3 \times -1\right)$$
  
= 1 + R\_b \times g\_{m1} \times \beta\_1 \times \frac{1}{\alpha\_2} \times R\_4 \times G\_1 \times \alpha\_3  
= 858.7  
  
i1 -1 \beta\_1 \times \frac{1}{\alpha\_2} \times R\_4 \times G\_1 \times \times R\_4 \times G\_1 \times R\_4 \times C\_1 \times C\_2 \times C\_1 \times C\_1

Figure 37: Signal-flow graph for the equations.

The transconductance gain is

$$\frac{i_{c2}}{i_1} = \frac{1 \times R_b \times -g_{m1} \times -\beta_2}{\Delta}$$

$$= \frac{R_b \times g_{m1} \times \beta_2}{1 + R_b \times g_{m1} \times \beta_2 \times \frac{1}{\alpha_2} \times R_4 \times G_1 \times \alpha_3}$$

$$= \frac{(R_b \times g_{m1} \times \beta_2)}{1 + (R_b \times g_{m1} \times \beta_2) \times \left(\frac{1}{\alpha_2} \times R_4 \times G_1 \times \alpha_3\right)}$$

This is of the form

$$\frac{i_{c2}}{i_1} = \frac{A}{1+Ab}$$

where A and b are given by

$$A = R_b \times g_{m1} \times \beta_2$$
  
=  $R_1 ||R_2||r_{e1} \times g_{m1} \times \beta_2$   
= 96.39  
$$b = \frac{1}{\alpha_2} \times R_4 \times G_1 \times \alpha_3 = \frac{1}{\alpha_2} \times R_4 \times \frac{1}{r'_{e3} + R_3} \times \alpha_3 = 8.899$$

Notice that the product Ab is dimensionless and positive. The latter must be true for the feedback to be negative.

Numerical evaluation of the transconductance gain yields

$$\frac{i_{c2}}{i_1} = \frac{A}{\Delta} = 0.112$$

The voltage gain is given by

$$\frac{v_2}{v_1} = \frac{i_1}{v_1} \times \frac{i_{c2}}{i_1} \times \frac{v_2}{i_{c2}} = \frac{1}{R_1} \times \frac{A}{\Delta} \times -R_5 = -1.122$$

The resistances  $R_a$ ,  $R_A$ , and  $R_B$  are given by

$$R_a = \frac{R_b}{\Delta} = 0.028\,\Omega \qquad R_A = R_1 + \left(R_a^{-1} - R_1^{-1}\right)^{-1} = 1\,\mathrm{k}\Omega \qquad R_B = R_5 = 10\,\mathrm{k}\Omega$$

### Shunt-Series Example 4

Figure 38(a) shows the ac signal circuit of a shunt-series feedback amplifier. The input variable is  $v_1$  and the output variable is  $i_{d2}$ . The input signal and the feedback signal are applied to the gate of  $M_1$ . For the analysis to follow convention, the input source consisting of  $v_1$  in series with  $R_1$  must be converted into a Norton equivalent. The feedback is from the output current  $i_{d2}$  to the source of  $M_2$  and to the gate of  $M_1$ . The circuit values are  $g_m = 0.001$  S,  $r_s = g_m^{-1} = 1 \text{ k}\Omega$ ,  $r_0 = \infty$ ,  $R_1 = 1 \text{ k}\Omega$ ,  $R_2 = 100 \text{ k}\Omega$ ,  $R_3 = 10 \text{ k}\Omega$ ,  $R_4 = 1 \text{ k}\Omega$ ,  $R_5 = 1 \text{ k}\Omega$ , and  $R_6 = 100 \Omega$ .

The circuit with feedback removed is shown in Fig. 38(b). The source is replaced with a Norton equivalent circuit consisting of the current

$$i_1 = \frac{v_1}{R_1}$$

in parallel with the resistor  $R_1$ . The feedback is modeled by a Norton equivalent circuit consisting of the current  $k_1i_{d2}$ . The output current is proportional to this current. Because  $r_{02} = \infty$ , the feedback does not affect the output resistance seen looking up from signal ground into the lower terminal of  $R_3$  because it is infinite. For a finite  $r_{02}$ , a test voltage source can be added in series with  $R_3$  to solve for this resistance. It would be found that a finite  $r_{02}$  considerably complicates the circuit equations and the flow graph.



Figure 38: (a) Amplifier circuit. (b) Circuit with feedback removed.

The following equations can be written for the circuit with feedback removed:

$$\begin{aligned} i_a &= i_1 + k_1 i_{d2} \qquad k_1 = \frac{R_5}{R_5 + R_6} \qquad v_{g1} = i_a R_c \qquad R_c = R_1 \| R_b \qquad R_b = R_5 + R_6 \\ i_{d1} &= g_{m1} v_{g1} \qquad i_{d2} = G_1 \left( v_{tg2} - v_{ts2} \right) \qquad v_{tg2} = -i_{d1} R_2 \qquad v_{ts2} = k_2 v_{g1} \\ k_2 &= \frac{R_5}{R_5 + R_6} \qquad G_1 = \frac{1}{r_{s2} + R_{ts2}} \qquad R_{ts2} = R_4 + R_5 \| R_6 \end{aligned}$$

The current  $i_a$  is the error current. The negative feedback tends to reduce  $i_a$ , making  $|i_a| \rightarrow 0$  as the amount of feedback becomes infinite. When this is the case, setting  $i_a = 0$  yields the current gain  $i_{d2}/i_1 = -1/k_1$ .

Although the equations can be solved algebraically, the signal-flow graph simplifies the solution. Fig. 39 shows the flow graph for the equations. The determinant of the graph is given by

$$\Delta = 1 - (R_c \times g_{m1} \times -R_2 \times G_1 \times k_1)$$
$$= 1 + R_c \times g_{m1} \times R_2 \times G_1 \times k_1$$



Figure 39: Signal-flow graph for the equations.

The current gain is given by

$$\begin{aligned} \frac{i_{d2}}{i_1} &= \frac{R_c \times g_{m1} \times -R_2 \times G_1}{\Delta} \\ &= \frac{-\left(R_c \times g_{m1} \times R_2 \times \frac{1}{r_{s2} + R_4 + R_5 \|R_6}\right)}{1 + \left[-\left(R_c \times g_{m1} \times R_2 \times \frac{1}{r_{s2} + R_4 + R_5 \|R_6}\right)\right] \times (-k_1)} \\ &= \frac{i_{d2}}{i_1} = \frac{A}{1 + Ab} \end{aligned}$$

This is of the form

$$\frac{d2}{d_1} = \frac{11}{1+Ab}$$

where

$$A = -\left(R_c \times g_{m1} \times R_2 \times \frac{1}{r_{s2} + R_4 + R_5 \|R_6}\right) = -25.02$$
$$b = -k_1 = -0.909$$

Note that Ab is dimensionless. Numerical evaluation yields

$$\frac{i_{d2}}{i_1} = \frac{-25.02}{1 + (-25.02) \times (-0.909)} = -1.054$$

The voltage gain is given by

$$\frac{v_2}{v_1} = \frac{i_{d2}}{i_1} \times \frac{i_1}{v_1} \times \frac{v_2}{i_{d2}} = \frac{i_{d2}}{i_1} \times \frac{1}{R_1} \times -R_3 = -10.54$$

The resistance  $R_a$  is

$$R_a = \frac{v_{s1}}{i_1} = \frac{R_c}{\Delta} = \frac{R_1 \| (R_5 + R_6)}{\Delta} = 22.03 \,\Omega$$

Note that the feedback tends to decrease  $R_a$ . The resistance  $R_A$  is

$$R_A = R_1 + \left(R_a^{-1} - R_1^{-1}\right)^{-1} = 1.023 \,\mathrm{k}\Omega$$

The resistance  $R_B$  is

$$R_B = R_3 = 10 \,\mathrm{k}\Omega$$

This is not a function of the feedback because  $r_{02}$  has been assumed to be infinite.

## Shunt-Series Example 5

Figure 40(a) shows the ac signal circuit of a shunt-series feedback amplifier. The input variable is  $v_1$  and the output variable is  $i_{d2}$ . The input signal and the feedback signal are applied to the base  $Q_1$ . For the analysis to follow convention, the input source consisting of  $v_1$  in series with  $R_1$  must be converted into a Norton equivalent. The feedback is from the output current  $i_{c2}$  to the current  $i_{e2}$  to the current  $i_{e3}$  to the current  $i_{e3}$ . The resistor values are  $R_1 = 1 \,\mathrm{k}\Omega$ ,  $R_2 = 10 \,\mathrm{k}\Omega$ ,  $R_3 = 10 \,\mathrm{k}\Omega$ , and  $R_4 = 10 \,\mathrm{k}\Omega$ . Assume  $\beta = 100$ ,  $r_{\pi} = 2.5 \,\mathrm{k}\Omega$ ,  $\alpha = \beta/(1+\beta)$ ,  $r_e = \alpha/g_m$ ,  $r_0 = \infty$ ,  $r_x = 0$ ,  $V_T = 25 \,\mathrm{mV}$ .



Figure 40: (a) Amplifier circuit. (b) Circuit with the source replaced with a Norton equivalent.

The circuit with feedback removed is shown in Fig. 40(b). The source is replaced with a Norton equivalent circuit consisting of the current

$$i_1 = \frac{v_1}{R_1}$$

in parallel with the resistor  $R_1$ . The feedback is modeled by a Norton equivalent circuit consisting of the current  $i_{c3}$ . The output current is proportional to this current. Because  $r_{02} = \infty$ , the feedback does not affect the output resistance seen looking up from signal ground into the lower terminal of  $R_4$  because it is

infinite. For a finite  $r_{02}$ , a test voltage source can be added in series with  $R_4$  to solve for this resistance. It would be found that a finite  $r_{02}$  considerably complicates the circuit equations and the flow graph.

The following equations can be written for the circuit with feedback removed:

$$i_{a} = i_{1} + i_{c3} \qquad v_{b1} = i_{a}R_{b} \qquad R_{b} = R_{1} ||r_{\pi 1} \qquad i_{c1} = g_{m1}v_{b1} \qquad v_{tb2} = -i_{c1}R_{3} \qquad i_{e2} = G_{1}v_{tb2}$$

$$G_{1} = \frac{1}{r'_{e2} + R_{2} + r_{e3}} \qquad r'_{e2} = \frac{R_{3}}{1 + \beta_{2}} + r_{e2} \qquad i_{c2} = \alpha_{2}i_{e2} \qquad i_{e3} = i_{e2} \qquad i_{c3} = \alpha_{3}i_{e3}$$

The current  $i_a$  is the error current. The negative feedback tends to reduce  $i_a$ , making  $|i_a| \rightarrow 0$  as the amount of feedback becomes infinite. When this is the case, setting  $i_a = 0$  yields the current gain  $i_{d2}/i_1 = -1/k_1$ .

Although the equations can be solved algebraically, the signal-flow graph simplifies the solution. Fig. 41 shows the flow graph for the equations. The determinant of the graph is given by

$$\Delta = 1 - (R_b \times g_{m1} \times -R_3 \times G_1 \times 1 \times \alpha_3 \times 1)$$
  
= 1 + R\_b \times g\_{m1} \times R\_3 \times G\_1 \times \alpha\_3  
= 28.88  
$$\frac{1}{10} \frac{\text{ic1}}{10} \frac{\text{vb1}}{10} \frac{\text{ic1}}{10} \frac{\text{vtb2}}{10} \frac{\text{ic2}}{10} \frac{\text{ic2}}{10}$$

ie3

α3

The current gain is given by

i1•--

ic3

$$\frac{i_{d2}}{i_1} = \frac{1 \times R_b \times g_{m1} \times -R_3 \times G_1 \times \alpha_2}{\Delta}$$
$$= \frac{-(R_b \times g_{m1} \times R_3 \times G_1 \times \alpha_2)}{1 + [-(R_b \times g_{m1} \times R_3 \times G_1 \times \alpha_2)] \times \left(-\frac{\alpha_3}{\alpha_2}\right)}$$

This is of the form

$$\frac{i_{d2}}{i_1} = \frac{A}{1+Ab}$$

where

$$A = -(R_b \times g_{m1} \times R_3 \times G_1 \times \alpha_2) = -27.88$$
$$b = -\frac{\alpha_3}{\alpha_2} = -1$$

Note that Ab is dimensionless and the product is positive. The latter is a result of the feedback being negative. Numerical evaluation yields

$$\frac{i_{d2}}{i_1} = \frac{-27.88}{1 + (-27.88) \times (-1)} = -0.965$$

The voltage gain is given by

$$\frac{v_2}{v_1} = \frac{i_{d2}}{i_1} \times \frac{i_1}{v_1} \times \frac{v_2}{i_{d2}} = \frac{i_{d2}}{i_1} \times \frac{1}{R_1} \times -R_4 = 9.654$$

The resistance  $R_a$  is

$$R_a = \frac{v_{s1}}{i_1} = \frac{R_b}{\Delta} = \frac{R_1 || r_{\pi 1}}{\Delta} = 24.74 \,\Omega$$

Note that the feedback tends to decrease  $R_a$ . The resistance  $R_A$  is

$$R_A = R_1 + \left(R_a^{-1} - R_1^{-1}\right)^{-1} = 1.025 \,\mathrm{k}\Omega$$

The resistance  $R_B$  is

$$R_B = R_4 = 10 \,\mathrm{k}\Omega$$

This is not a function of the feedback because  $r_{02}$  has been assumed to be infinite.