## ECE3050 Mason's Flow Graph Formula

Amplifier analysis using superposition is often facilitated by the use of signal flow graphs. A signal flow graph, or flow graph for short, is a graphical representation of a set of linear equations which can be used to write by inspection the solution to the set of equations. For example, consider the set of equations

$$x_2 = Ax_1 + Bx_2 + Cx_5 \tag{1}$$

$$x_3 = Dx_1 + Ex_2 \tag{2}$$

$$x_4 = Fx_3 + Gx_5 \tag{3}$$

$$x_5 = H x_4 \tag{4}$$

$$x_6 = I x_3 \tag{5}$$

where  $x_1$  through  $x_6$  are variables and A through I are constants. These equations can be represented graphically as shown in Fig. 1. The graph has a node for each variable with branches connecting the nodes labeled with the constants A through I. The node labeled  $x_1$ is called a source node because it has only outgoing branches. The node labeled  $x_6$  is called a sink node because it has only incoming branches. The path from  $x_1$  to  $x_2$  to  $x_3$  to  $x_6$  is called a forward path because it originates at a source node and terminates at a non-source node and along which no node is encountered twice. The path gain for this forward path is AEI. The path from  $x_2$  to  $x_3$  to  $x_4$  to  $x_5$  and back to  $x_2$  is called a feedback path because it originates and terminates on the same node and along which no node is encountered more than once. The loop gain for this feedback path is EFHC.



Figure 1: Example signal flow graph.

Mason's formula can be used to calculate the transmission gain from a source node to any non-source node in a flow graph. The formula is

$$T = \frac{1}{\Delta} \sum_{k} P_k \Delta_k \tag{6}$$

where  $P_k$  is the gain of the kth forward path,  $\Delta$  is the graph determinant, and  $\Delta_k$  is the determinant with the kth forward path erased. The determinant is given by

$$\Delta = 1 - (\text{sum of all loop gains}) + \begin{pmatrix} \text{sum of the gain products of all possible} \\ \text{combinations of two non-touching loops} \end{pmatrix} - \begin{pmatrix} \text{sum of the gain products of all possible} \\ \text{combinations of three non-touching loops} \end{pmatrix} + \begin{pmatrix} \text{sum of the gain products of all possible} \\ \text{combinations of four non-touching loops} \end{pmatrix} - \cdots$$
(7)

For the flow graph in Fig. 1, the objective is to solve for the gain from node  $x_1$  to node  $x_6$ . There are two forward paths from  $x_1$  to  $x_6$  and three loops. Two of the loops do not touch each other. Thus the product of these two loop gains appears in the expression for  $\Delta$ . The path gains and the determinant are given by

$$P_1 = AEI \tag{8}$$

$$P_2 = DI \tag{9}$$

$$\Delta = 1 - (B + CEFH + GH) + B \times GH \tag{10}$$

Path  $P_1$  touches two loops while path  $P_2$  touches one loop. The determinants with each path erased are given by

$$\Delta_1 = 1 - GH \tag{11}$$

$$\Delta_2 = 1 - (B + GH) + B \times GH \tag{12}$$

Thus the overall gain from  $x_1$  to  $x_6$  is given by

$$\frac{x_6}{x_1} = \frac{AEI \times (1 - GH) + DI \times [1 - (B + GH) + B \times GH]}{1 - (B + CEFH + GH) + B \times GH}$$
(13)