

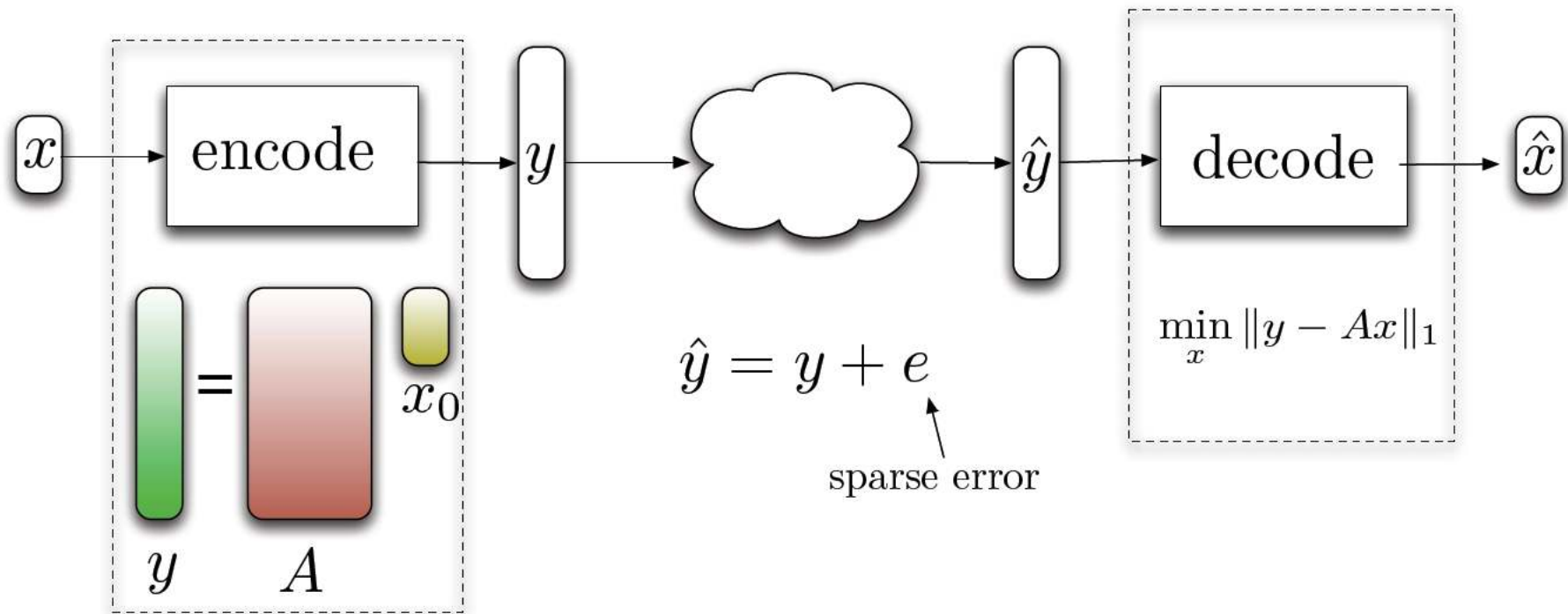
**Channel Protection:  
Random Channel Meets Sparse Channels**  
[a “blind deconvolution” scheme]

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*joint work with* **William Mantzel** *and* **Justin Romberg**

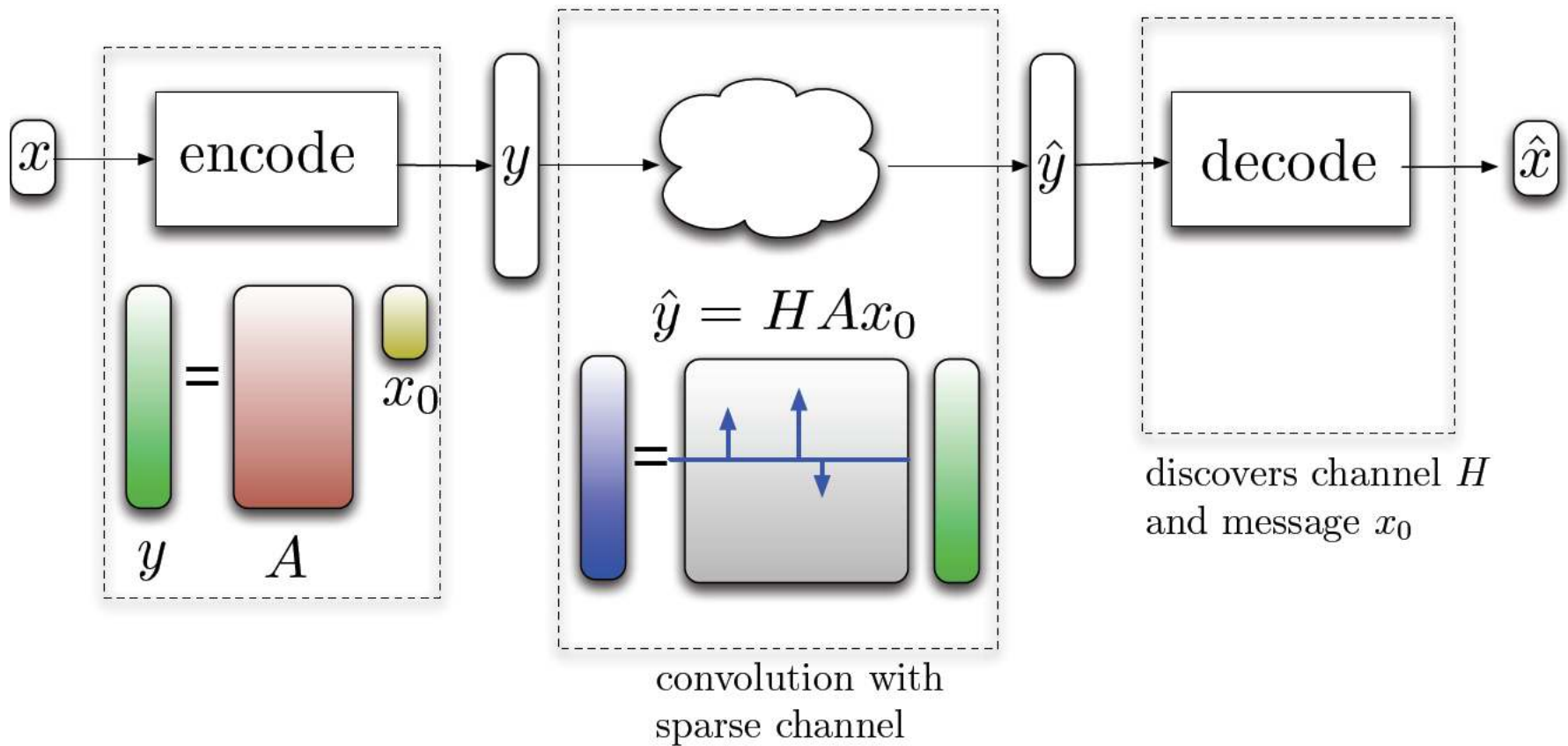
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# Random Coding Example [Candes & Tao '04]



- Structure:  $A$  is a *tall random* ( $m \times n$ ) matrix,  $e$  is *sparse*
- It can recover the signal  $x$  exactly if
$$|\text{supp}(e)| < \text{Const} \cdot (m-n)/\log(m)$$
- Also stable against small disturbances [Candes & Randall '07]

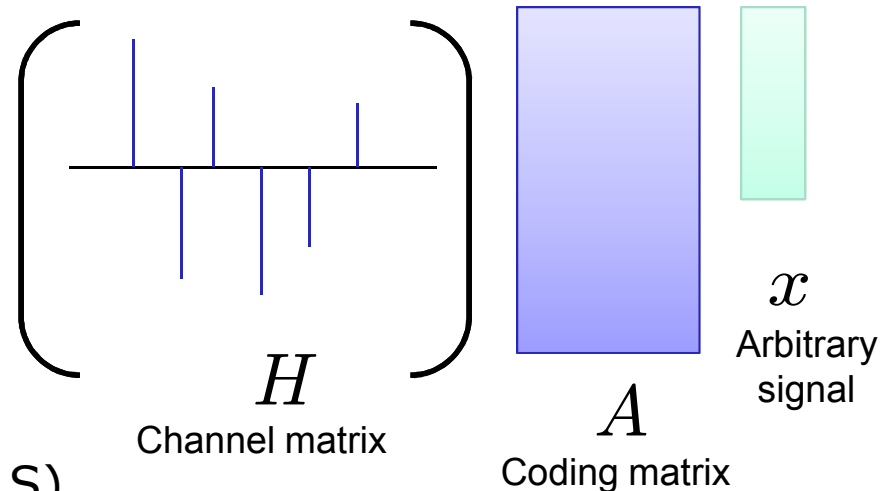
# Random Coding and Blind Deconvolution



# Problem Formulation

- Problem setup:

$$y = h * Ax \longrightarrow$$



- $x$  – unknown message
  - $A$  –  $m \times n$  matrix
  - $h$  – channel impulse response  
(length of channel  $L$ ; sparsity  $S$ )
- Message is encoded with a tall random matrix before transmission:  $Ax$
  - Signal received via a channel with impulse response  $h$
  - Goal: Estimate  $x$  without knowledge of  $h$

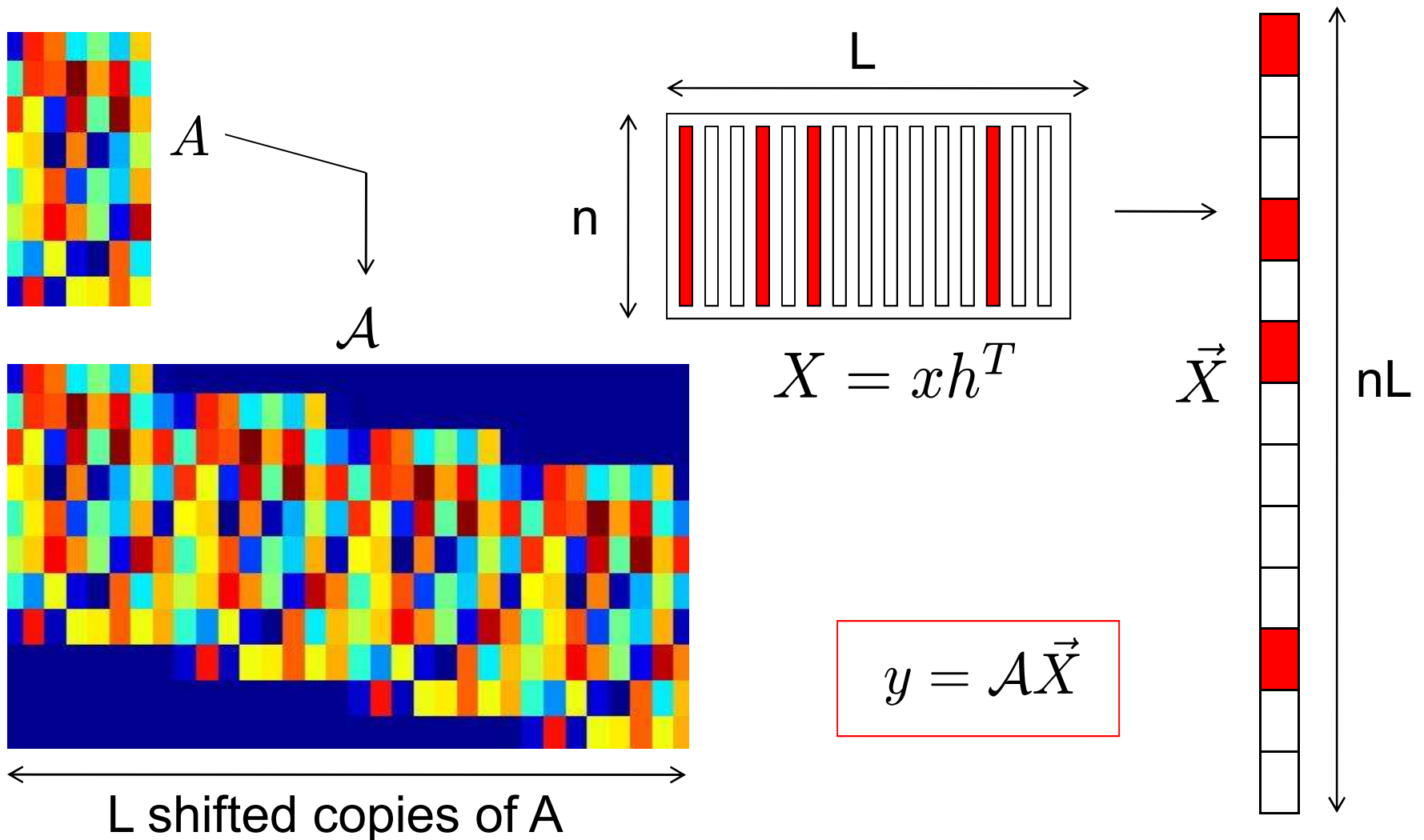
## Random Coding for Blind Deconvolution, why?

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- “Channel protection”:  $y = h * Ax$
- Random coding may provide robustness against (*sparse*) *convolutive* channels (now we have a structure, aha!)
- Structure: Transmitted signal lies in a *smaller subspace: range(A)*, channel impulse response is *sparse*
- The recovery performance improves as we increase redundancy
- Goal: Estimate  $x$  without knowledge of  $h$  with minimum redundancy in the coding
- The problem of estimating  $x$  and  $h$  simultaneously can be nonconvex

# Deconvolution

- Problem variables can be described as rank one matrix

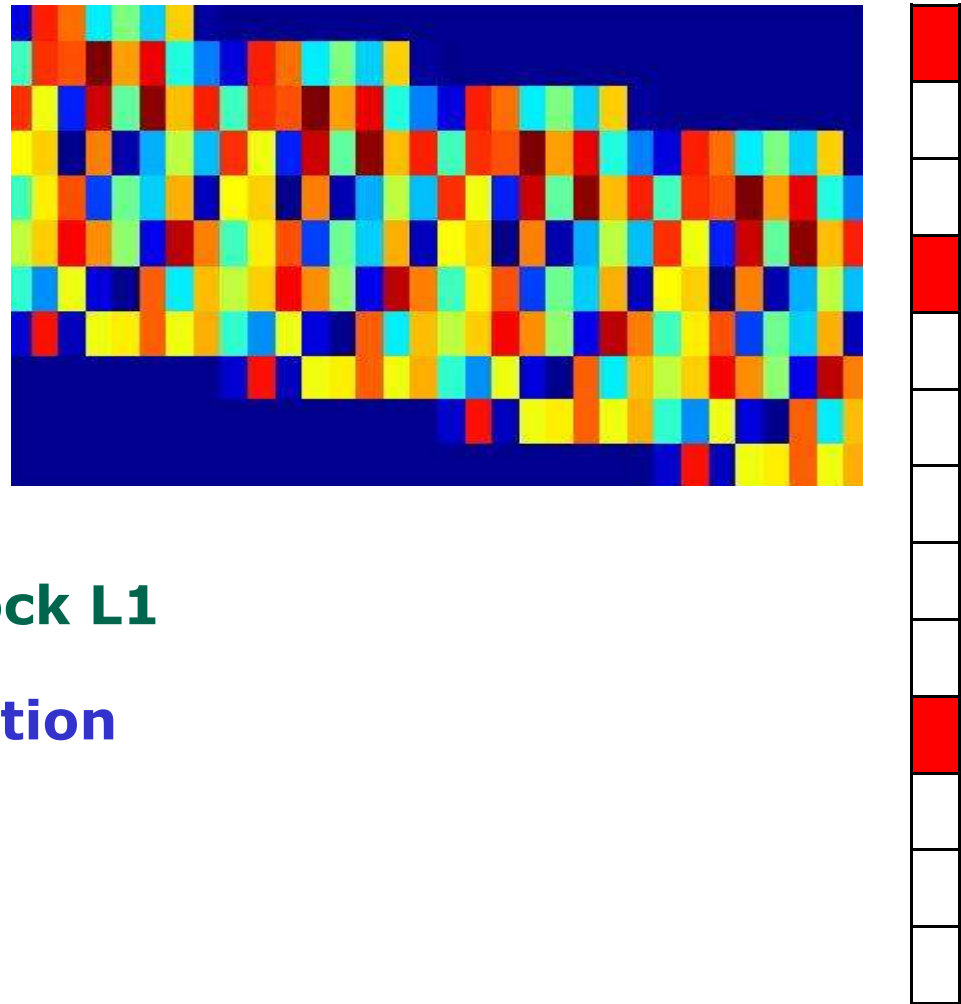


# Proposed Methods for Deconvolution

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- Solve the following inverse problem

$$y = \mathcal{A}\vec{X}$$

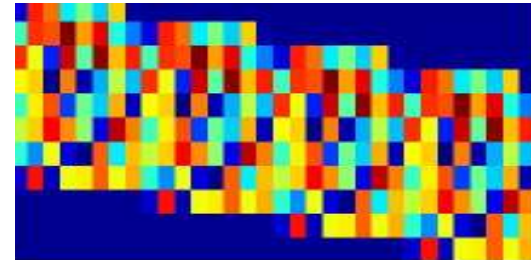


- **Block L1**
- **Rank constrained block L1**
- **Alternating minimization**
- **Rank minimization**

# Block L1

- Naïve approach

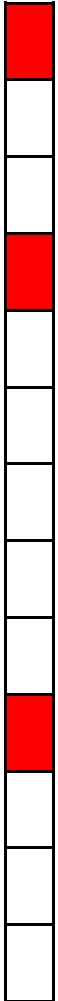
$$\text{minimize } \|\vec{X}\|_1 \text{ subject to } y = \mathcal{A}\vec{X}$$



- However, sparsity pattern is not arbitrary (*block sparse*)
- The block-L1 approach improves performance (slightly)  
[Baraniuk et al., Stojnic et al., Blumensath et al. 2008]

$$\text{minimize } \sum_k \|\vec{X}_k\|_2 \text{ subject to } y = \mathcal{A}\vec{X}$$

- This requires  $m = O(nS \log(nL))$  for perfect recovery
- However, there are only  $(n+S)$  degrees of freedom!
- We want to break through to get  $m = O(n+S)$   
(modulo log factor)



# Rank Constrained Block-L1

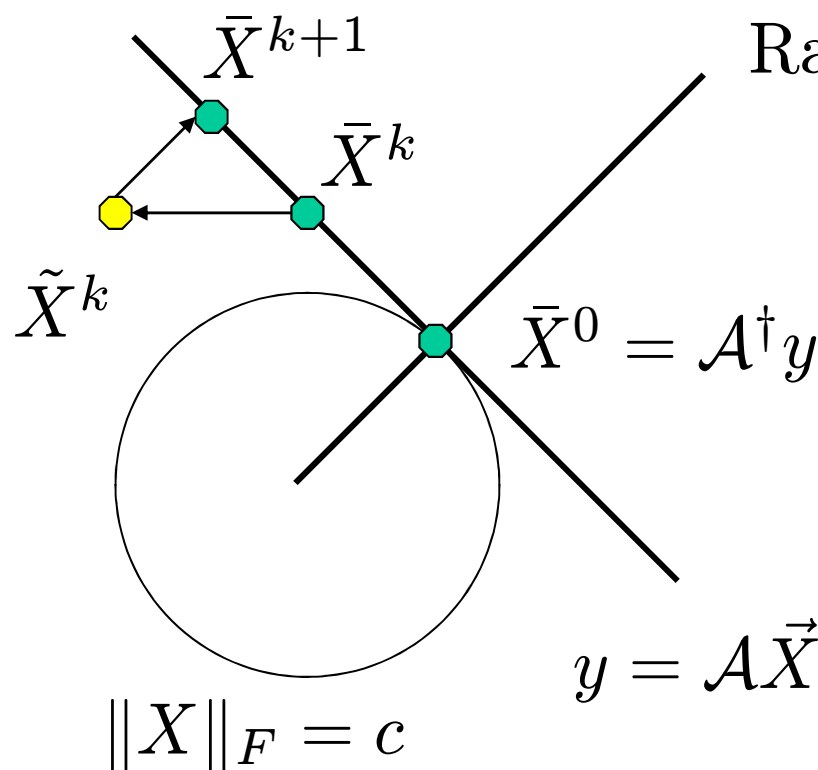
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- Enforce the rank-1 constraint on block L1 (nonconvex)
- Gradient descent with rank-constraint and affine projection
- Traverse the affine subspace of measurement constraints
  - Project  $X$  to the nearest rank-1 matrix
  - Minimize 2→1 norm:  $\sum \|X_k\|_2$
  - Project back to the affine subspace
- When  $X = fg^T$  (rank 1), this minimizes  $\|f\|_2 \|g\|_1$
- Enforces sparsity on the number of active columns
- Rank-1 projection at every step
- Gradient descent: The update direction for each nonzero column:

$$\Delta X_k = -\frac{X_k}{\|X_k\|_2}$$

# Rank Constrained Block-L1

- Find closest rank one matrix to the solution (SVD)
- Minimize  $2 \rightarrow 1$  norm (can be combined with SVD as soft thresholding)
- Project onto the affine space defined by the measurements



$$U\Sigma V^T = \bar{X}^k$$

$$\tilde{X}^k = \sigma_1 u_1 \tilde{v}_1^T$$

$$\bar{X}^{k+1} = P_{\mathcal{A}\vec{X}=y} \tilde{X}^k$$

Soft threshold:

$$\tilde{v}_1 = S_\epsilon(v_1)$$

# Alternating Minimization (AM)

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- Solve the joint optimization problem

$$\text{minimize } \frac{1}{2} \|h * Ax - y\|_2^2 + \tau \|h\|_1$$

- Hard to solve simultaneously
- Solve *alternately* for  $x$  and  $h$

- BPDN for  $h$  (using previous estimate of  $x$ )

$$\text{minimize } \frac{1}{2} \|M_{Ax}h - y\|_2^2 + \tau \|h\|_1$$

- Least squares for  $x$  (using previous estimate of  $h$ )

$$\text{minimize } \|M_{h*A}x - y\|_2$$

- Iterate until convergence!

# Discussion About Analysis of AM

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- What do we know\* about the setup

$$\text{minimize } \frac{1}{2} \|h * Ax - y\|_2^2 + \tau \|h\|_1$$

- What if we know the signal perfectly:

$$\text{minimize } \frac{1}{2} \|Gh - y\|_2^2 + \tau \|h\|_1$$

recovers the signal exactly if  $m \geq S \log^5 L$

- What if we know the channel perfectly:

$$\text{minimize } \|HAx - y\|_2$$

for a generic  $h$  with  $S$  taps, matrix  $HA$  has rank  $n$  if  
 $m > \text{Const} \cdot (n+S) \log(m)$

This follows from quantitative uncertainty principle!

\* Do not ask what happens if do not know  $x$  and  $h$

# Rank Minimization

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- Find minimum rank matrix satisfying the measurements

$$\text{minimize } \text{rank}(X) \text{ subject to } \mathcal{A}\vec{X} = y$$

- Convex relaxation -- Nuclear norm minimization [Fazel 2002, Recht et al. 2007, ... ]

$$\text{minimize } \|X\|_* \text{ subject to } \mathcal{A}\vec{X} = y$$

- Equivalent semidefinite program

$$\text{minimize } \frac{1}{2}(\text{Tr}(W_1) + \text{Tr}(W_2))$$

$$\text{subject to } \begin{bmatrix} W_1 & X \\ X^T & W_2 \end{bmatrix} \succeq 0$$

$$\mathcal{A}\vec{X} = y$$

# Rank Minimization

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- SDP formulation minimizes rank; indifferent to sparsity
- Equivalently minimizes  $\|h\|_2^2 + \|x\|_2^2$
- Additional constraints:

Norm of  $h$

$$\text{Tr}(W_2) = 1$$

i.e.  $\|h\|_2 = 1$

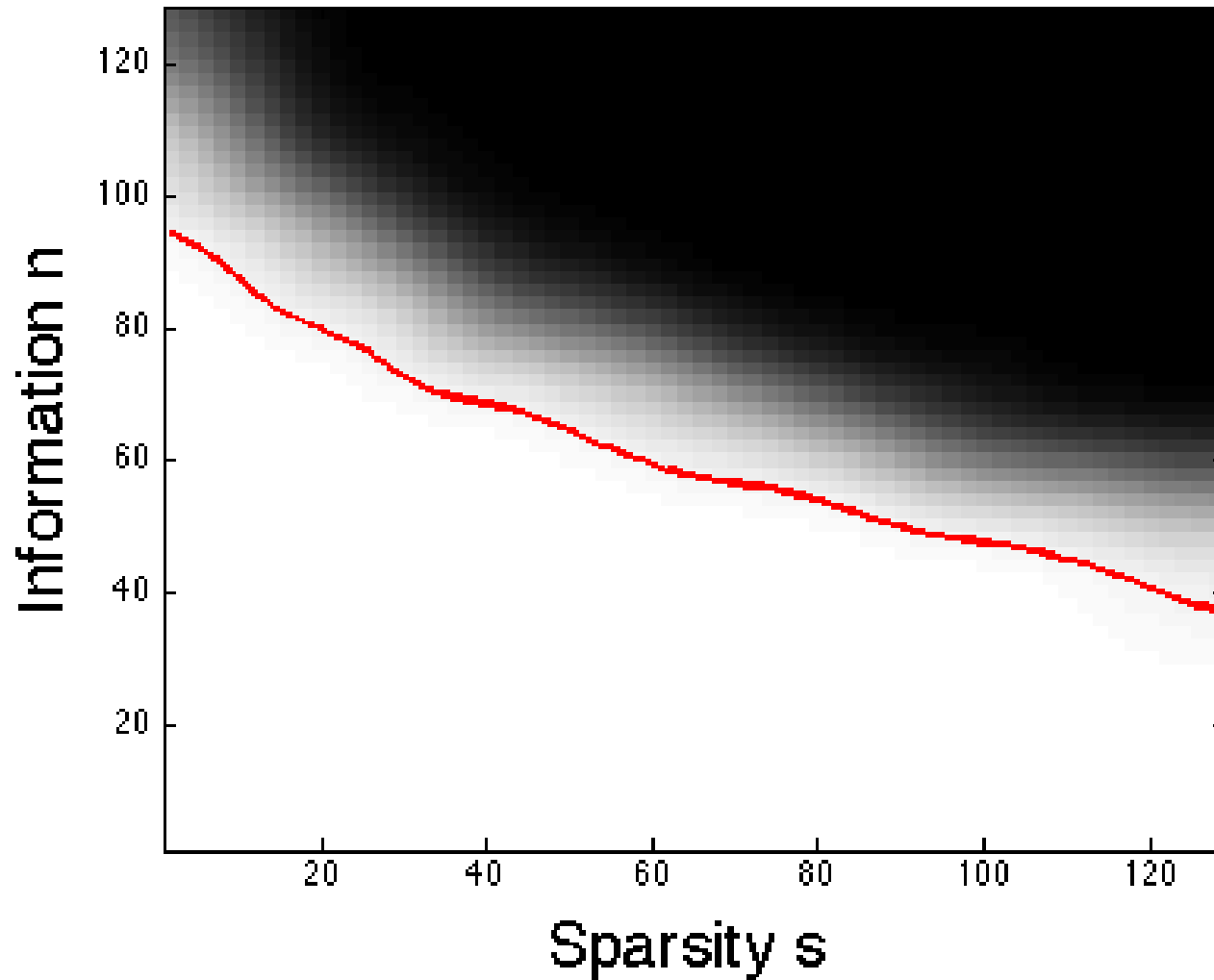
Sparsity of the matrix

$$\mathbf{1}^T |W_2| \mathbf{1} \leq k$$

i.e.  $\|h\|_2 \leq k$

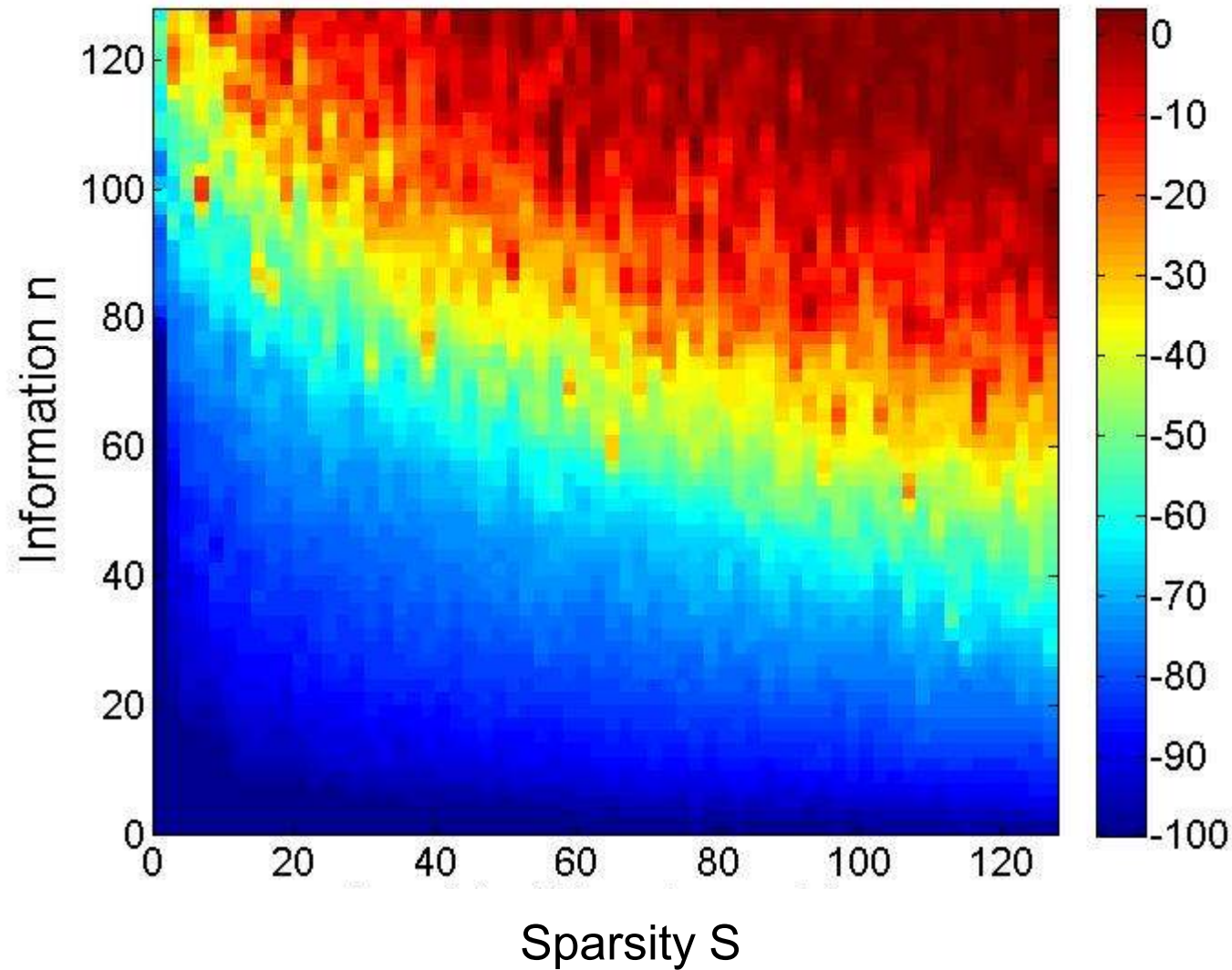
## Results: Rank constrained Gradient Descent ( $m=256, L=128$ )

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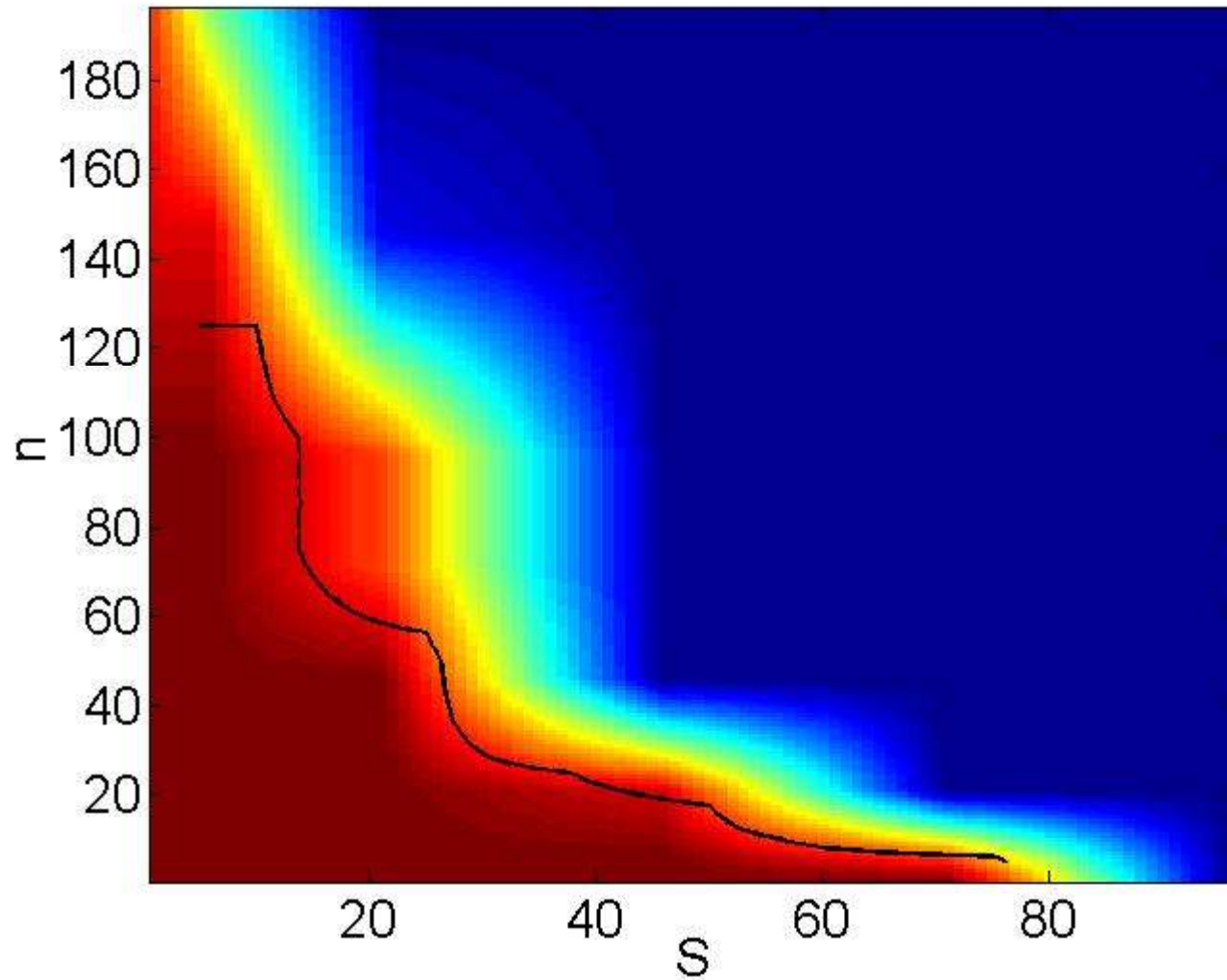
## Results: Rank constrained Gradient Descent ( $m=256, L=128$ )

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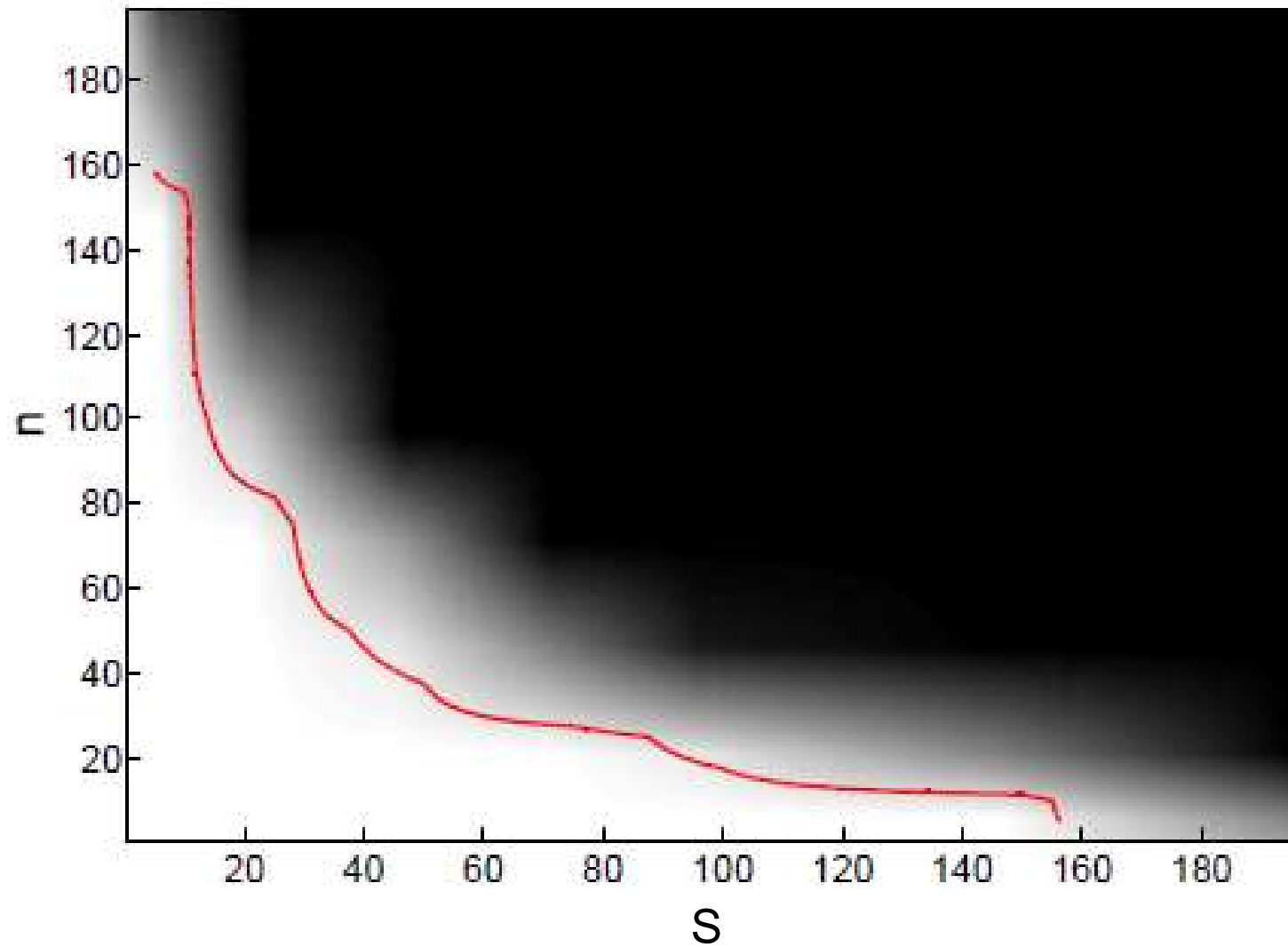
## Results: Alternating minimization ( $m=256$ , $L=128$ , Linear convolution model)

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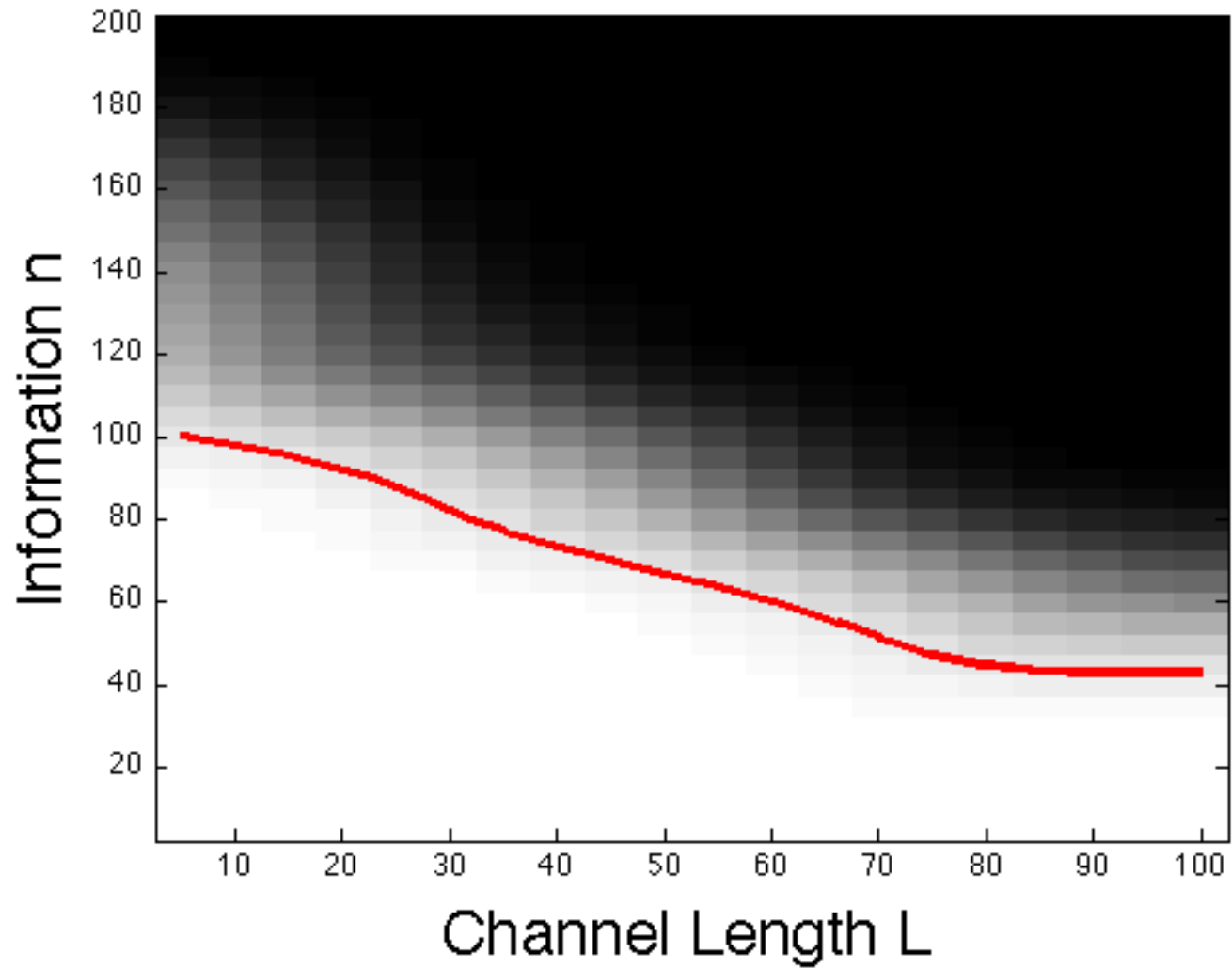
## Results: Alternating minimization ( $m=256$ , circular convolution model)

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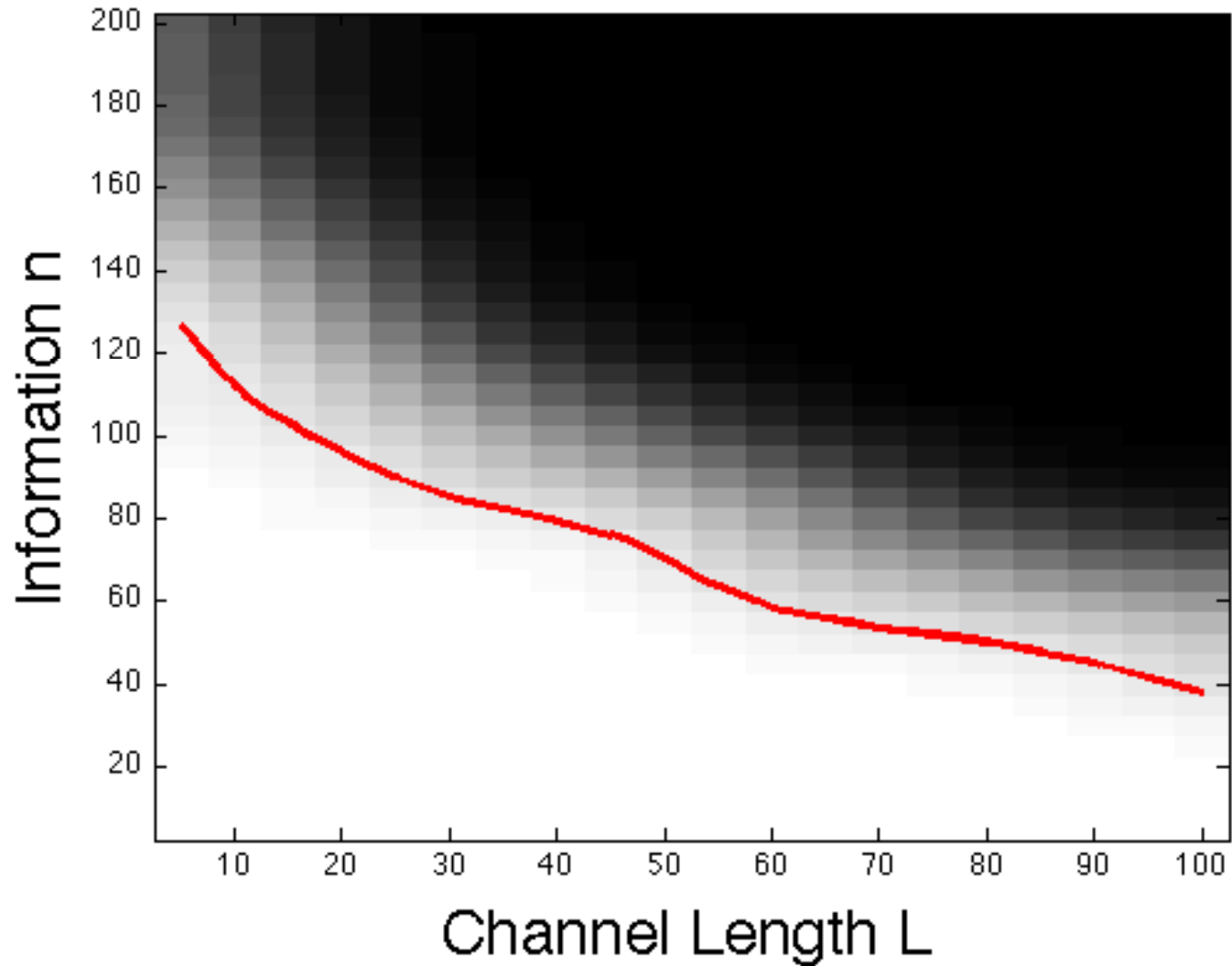
## Results: SDP ( $m=300$ )

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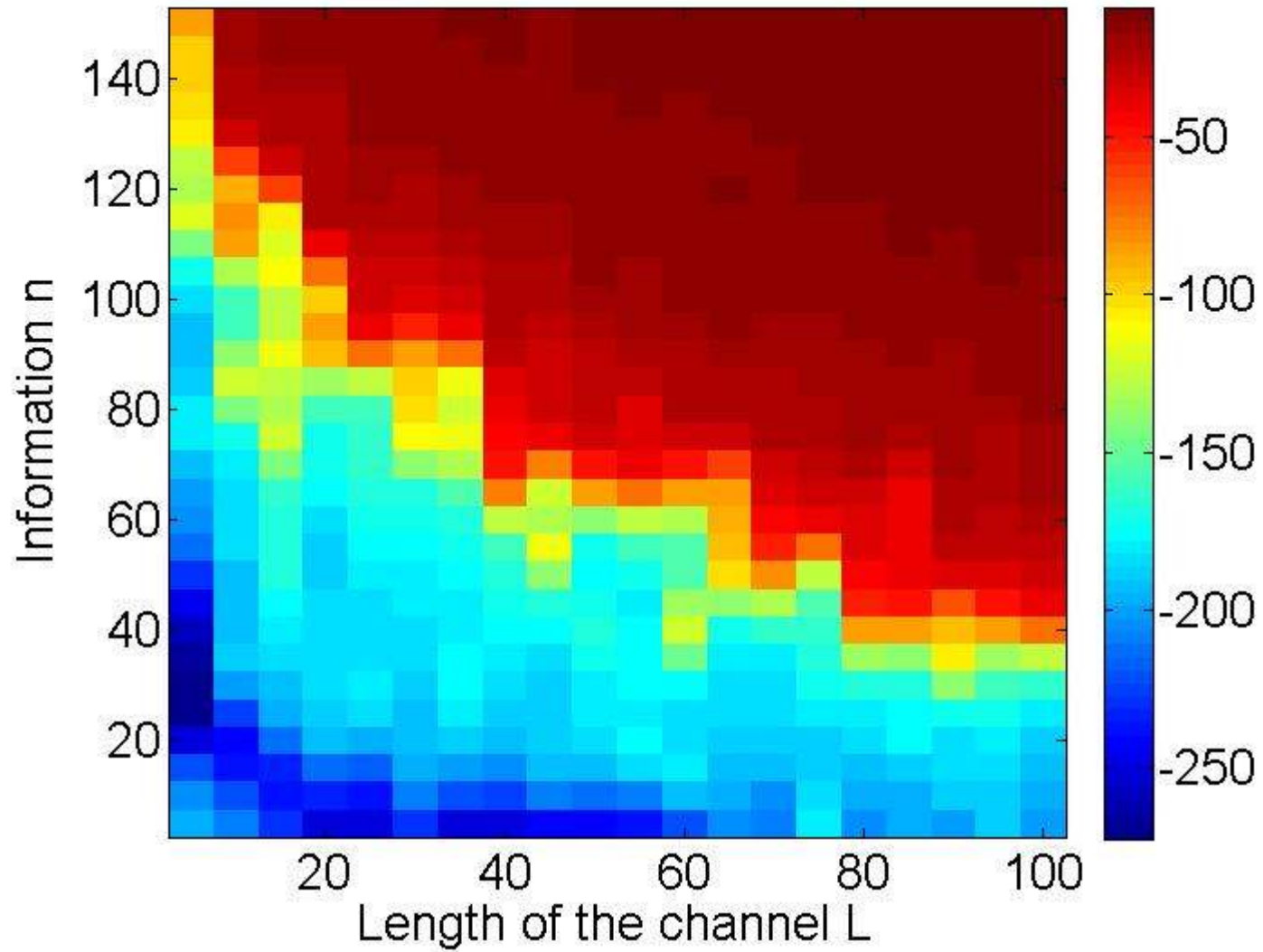
## Results: SDP ( $m=300$ , sparsity = 25%)

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## Results: SDP ( $m=256$ )

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# Summary

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- Random encoding ensures blind deconvolution
- Our proposed algorithms recover the encoded signal from the received signal, without knowledge of the channel.
- Required redundancy scales with length of message and sparsity (and length) of channel
- Nonconvex problems require some more work for global guarantees
- Relax the measurement constraints in the presence of noise

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# Thankyou !

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Papers:

- *Channel protection: Random coding meets sparse channels, ITW 2009*
- *Random coding and blind deconvolution, Allerton 2009*

Questions

