#### Homework Assignment No. 3 - Solutions

## Problem 1 - (10 points)

Assume an LPLL has F(s) = 1 and the PLL parameters are  $K_d = 0.8$  V/radians,  $K_o = 100$  MHz/V, and the oscillation frequency,  $f_{osc} = 500$ MHz. Sketch the control voltage at the output of the phase detector if the input frequency jumps from 500MHz to 650MHz.

#### **Solution**

Find the transfer function from the input frequency,  $f_{in}$ , to the output of the phase detector,  $v_d$ .

$$V_{d} = K_{d}(\theta_{1}-\theta_{2}) = K_{d}\theta_{1} - \frac{K_{d}K_{o}}{s}V_{d}$$

$$V_{d}\left(1 + \frac{K_{d}K_{o}}{s}\right) = K_{d}\theta_{1} = K_{d}\left(\frac{\omega_{1}}{s}\right)$$

$$\therefore \qquad \frac{V_{d}}{\omega_{1}} = \frac{K_{d}}{s+K_{d}K_{o}} \rightarrow \qquad V_{d}(s) = \frac{K_{d}}{s+K_{d}K_{o}}\omega_{1}(s) = \frac{K_{d}}{s+K_{d}K_{o}}\frac{\Delta\omega_{1}}{s} = \frac{k_{1}}{s} + \frac{k_{2}}{s+K_{d}K_{o}}$$

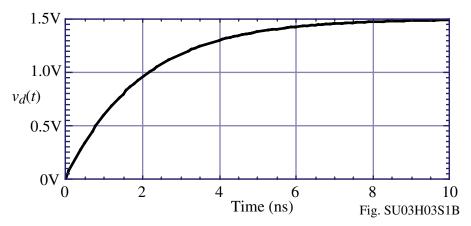
$$K_{d}\Delta\omega_{1} \qquad K_{d}\Delta\omega_{1}$$

By partial fraction expansion we can show that  $k_1 = -k_2 = \frac{K_d \Delta \omega_1}{K_d K_o} = \frac{K_d \Delta \omega_1}{K_v} = 1.5 \text{V}$ 

Note the units of  $\frac{K_d \Delta \omega_1}{K_v}$  are  $\frac{(V/rad)(rad/sec)}{1/sec} = V$ and  $K_v = (2\pi \cdot 100 \text{MHz/V})(0.8 \text{V/rad.}) = 502.65 \times 10^6 \text{ (1/sec.)}$ 

$$\therefore \qquad v_d(t) = \frac{K_d \Delta \omega_1}{K_v} (1 - e^{-K_v t}) = 1.5(1 - e^{-502.65 \times 10^6 t})$$

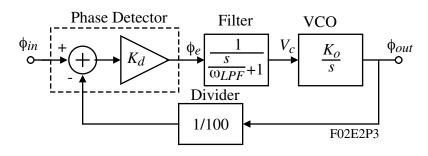
A plot of  $v_d(t)$  is shown below.



 $\omega_1$   $v_d$ 

## Problem 2 – (10 points)

A Type I PLL incorporates a VCO with  $K_o = 100$  MHz/V, a phase detector with  $K_d = 1$ V/rad, and a first-order, lowpass filter with  $\omega_{LPF} = 2\pi \times 10^6$  radians/s shown below. A divider of 100 has been placed in the feedback path to implement a frequency synthesizer. (a.) Find the value of the natural damping frequency,  $\omega_n$ , and the damping factor,  $\zeta$ , for the transfer function  $\phi_{out}(s)/\phi_{in}(s)$ , for this PLL. (b.) If a step input of  $\Delta \phi_{in}$  is applied at t = 0, what is the steady-state phase error at the output of the phase detector,  $\phi_e$ ? The steady-state error is evaluated by multiplying the desired phase by *s* and letting  $s \rightarrow 0$ .



<u>Solution</u>

$$(a.) \ \phi_{out} = \frac{K_o}{s} \left( \frac{1}{\frac{s}{\omega_{LPF}} + 1} \right) K_d \left( \phi_{in} - \frac{\phi_{out}}{N} \right) \rightarrow \phi_{out} \left[ 1 + \frac{K_o}{sN} \left( \frac{K_d}{1 + \frac{s}{\omega_{LPF}}} \right) \right] = \frac{K_o}{s} \left( \frac{K_d}{\frac{s}{\omega_{LPF}} + 1} \right) \phi_{in}$$
$$\therefore \qquad \frac{\phi_{out}(s)}{\phi_{in}(s)} = \frac{K_o K_d}{s \left( 1 + \frac{s}{\omega_{LPF}} \right) + \frac{K_o K_d}{N}} = \frac{K_o K_d \omega_{LPF}}{s^2 + \omega_{LPF} s + \frac{K_o K_d \omega_{LPF}}{N}} = \frac{\omega_n^2}{s^2 + 2\zeta \omega_n s + \omega_n^2}$$

Thus, 
$$\omega_n^2 = \frac{K_o K_d \omega_{LPF}}{N} = \frac{2\pi x 10^6 \cdot 2\pi x 10^8}{100} = 4\pi^2 x 10^{12} \rightarrow \omega_n = 2\pi x 10^6$$
  
 $\zeta = \frac{\omega_{LPF}}{2\omega_n} = \frac{\omega_{LPF}}{2\sqrt{\frac{K_o K_d \omega_{LPF}}{N}}} = \frac{1}{2} \sqrt{\frac{N\omega_{LPF}}{K_o K_d}} = \frac{1}{2} \sqrt{\frac{100 \cdot 2\pi x 10^6}{1 \cdot 2\pi x 10^8}} = 0.5$   
 $\therefore \qquad \omega_n = 2\pi x 10^6 \text{ and } \zeta = 0.5$ 

(b.) First we must solve for  $\phi_e(s)$  which is found as

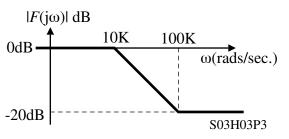
$$\phi_{e}(s) = \frac{s\left(1 + \frac{s}{\omega_{LPF}}\right)}{K_{o}}\phi_{out}(s) = \frac{s\left(1 + \frac{s}{\omega_{LPF}}\right)}{K_{o}}\frac{K_{o}K_{d}\omega_{LPF}}{s^{2} + \omega_{LPF}s + \frac{K_{o}K_{d}\omega_{LPF}}{N}}\phi_{in}(s)$$
If  $\phi_{in}(s) = \frac{\Delta\phi_{in}}{s}$ , then we can write  $s\phi_{e}(s) = \frac{K_{d}(s^{2} + \omega_{LPF}s)\Delta\phi_{in}}{s^{2} + \omega_{LPF}s + \frac{K_{o}K_{d}\omega_{LPF}}{N}}$ 
Therefore, we see that the steady-state error is  $\phi(t=\infty) = 0$ .

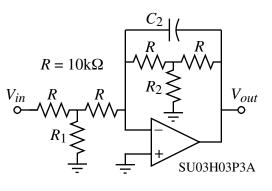
 $v_c$ 

SU03H03S2A

## Problem 3 – (10 points)

Modify the active filter shown of Problem 4 of Homework 2 to design the lag-lead loop filter shown below. The capacitors can be no larger than 10pF. Give the values of  $R_1$ ,  $R_2$ ,  $C_1$  and  $C_2$ .





#### <u>Solution</u>

The transfer function corresponding to the above Bode plot is,

$$F(s) = \frac{\frac{s}{10^5} + 1}{\frac{1}{10^4} + 1}$$

The modification of the filter is  $v_d$ shown where from Prob. 4 of  $\circ$ Homework 2,

$$R_{Ti} = \frac{2RR_i + R^2}{R_i}$$

The transfer function of this filter is found as,

$$F(s) = \frac{V_c(s)}{V_d(s)} = \left(\frac{R_{T2}}{R_{T1}}\right) \frac{sR_{T1}C_1 + 1}{sR_{T2}C_2 + 1} \Rightarrow R_{T2} = R_{T1} = R_T, R_TC_1 = 10^{-5} \text{ and } R_TC_2 = 10^{-4}$$

 $C_2$ 

R

Loop Filter

We see if  $R_{T2} = R_{T1}$ , then  $C_2 = 10C_1$ . Choosing  $C_2 = 10$ pF gives  $C_1 = 1$ pF. This gives

 $C_1$ 

 $R_{T1}$ 

$$R_T = \frac{10^{-4}}{C_2} = \frac{10^{-4}}{10^{-11}} = 10^7$$
$$R_T = \frac{2RR_i + R^2}{R_i} = 2R + \frac{R^2}{R_1} = 20x10^3 + \frac{100x10^6}{R_1} = 10^7 \Rightarrow R_1 = \frac{100x10^6}{10^7 - 20x10^3} = 10.02\Omega$$

Therefore,  $R_1 = R_2 = \underline{10.02\Omega}$ ,  $C_1 = \underline{1pF}$  and  $C_2 = \underline{10pF}$ 

The realization is completed by replacing each of the  $R_T$  resistors with the following equivalent:

$$\begin{array}{c} & R_{T1} \\ \bullet & & 10k\Omega & 10k\Omega \\ \bullet & & & 10.02\Omega \\ & & & \\ SU03H03S3B & & \\ \hline \end{array}$$

### Problem 4 – (10 points)

Using the filter of Problem 3, find the value of  $\omega_n$  and  $\zeta$  of the PLL if  $K_d = 1$ V/radians,  $K_o = 2$ Mradians/V·sec. What is the steady state phase error in degrees if a frequency ramp of 10<sup>9</sup> radians/sec.<sup>2</sup> is applied to the PLL?

# <u>Solution</u>

Using the definition give in the notes for the time constants of the passive lag-lead filter we get,

$$F(s) = \frac{\frac{s}{10^5} + 1}{\frac{1}{10^4} + 1} = \frac{s\tau_2 + 1}{s(\tau_1 + \tau_2) + 1} \implies \tau_2 = 10^{-5} \text{ sec. and } \tau_1 = 9x10^{-5} \text{ sec.}$$
  
$$\therefore \qquad \omega_n = \sqrt{\frac{K_o K_d}{\tau_1 + \tau_2}} = \sqrt{\frac{2x10^6}{10^{-4}}} = \sqrt{2} x10^5 = \underline{141.4x10^3 \text{ radians/sec.}}$$
  
$$\zeta = \frac{\omega_n}{2} \left(\tau_2 + \frac{1}{K_o K_d}\right) = \frac{\sqrt{2}x10^5}{2} \left(10^{-5} + \frac{1}{2x10^6}\right) = \frac{1}{\sqrt{2}} \left(1 + \frac{1}{20}\right) = \underline{0.742}$$

Assuming the PLL has a high loop gain, then the steady-state phase error can be found as

$$\theta_e(\infty) = \frac{\Delta \omega}{\omega_n^2} = \frac{10^9}{2 \times 10^{10}} = \frac{1}{20} \text{ radians } = \underline{2.86^\circ}$$

## Problem 5 – (10 points)

Solve for the crossover frequency of the PLL of Problems 3 and 4 and find the phase margin. Use SPICE to find the open-loop frequency response of the PLL and from your plot determine the crossover frequency and phase margin and compare with your calculated values.

## <u>Solution</u>

The crossover frequency can be found as,

$$\omega_c = \omega_n \sqrt{2\xi^2 + \sqrt{4\xi^4 + 1}} = \sqrt{2} \times 10^5 \sqrt{2 \cdot 0.742^2 + \sqrt{4 \cdot 0.742^4 + 1}}$$
$$= \sqrt{2} \times 10^5 (1.6089) = 2.275 \times 10^5 \text{ radians/sec.} = 36.208 \text{kHz}$$

The open loop transfer function is given as

$$LG(s) = \frac{K_v}{s} \left( \frac{1 + s\tau_1}{1 + s\tau_2} \right) = \frac{\sqrt{2}x 10^5}{s} \left( \frac{1 + s10^{-5}}{1 + s10^{-4}} \right)$$

The phase margin can be written as,

$$PM = 180^{\circ} - 90^{\circ} + \tan^{-1} \left( \frac{\omega_c}{10^5} \right) - \tan^{-1} \left( \frac{\omega_c}{10^4} \right) = 90^{\circ} + 66.27^{\circ} - 87.48^{\circ} = \underline{68.79^{\circ}}$$

#### SPICE Results:

```
Problem H3P5-Open Loop Response of an LPLL with Lead-Lag Filter
VS 1 0 AC 1.0
R1 1 0 10K
* Loop bandwidth = Kv = 2xE+6
                                     Tau1=1E-4
                                                  Tau2=1E-5
ELPLL 2 0 LAPLACE \{V(1)\}=
+{(2E+6/(S+0.001))*((1+1E-5*S)/(1+1E-4*S))}
* Note: The 0.001 added to "S" in the denominator is to prevent
* blowup of the problem at low frequencies.
R2 2 0 10K
*Steady state AC analysis
.AC DEC 20 10 100K
.PRINT AC VDB(2) VP(2)
.PROBE
.END
              100
                                           Phase + 180^{\circ}
               80
            dB or Degrees
              60
                     |F(j\omega)|
                                    Phase
              40
                                   Margin
                                    ≈ 69°
              20
               0
             -20
                                                     10<sup>4</sup>
                                                                 10<sup>5</sup>
                            100
                                       1000
                 10
```

Frequency (Hz)

 $\omega_{\rm C} \approx 36 \rm kHz$ 

The simulation results agree well with the calculated results.

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