

# **EE4601**

## **Communication Systems**

Week 4  
Ergodic Random Processes, Power Spectrum  
Linear Systems

# Ergodic Random Processes

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An **ergodic** random process is one where time averages are equal to ensemble averages. Hence, for all  $g(\mathbf{X})$  and  $\mathbf{X}$

$$\begin{aligned} E[g(\mathbf{X})] &= \int_{-\infty}^{\infty} g(\mathbf{X}) p_{\mathbf{X}(t)}(\mathbf{x}) d\mathbf{x} \\ &= \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T g[\mathbf{X}(t)] dt \\ &= \langle g[\mathbf{X}(t)] \rangle \end{aligned}$$

For a random process to be ergodic, it must be strictly stationary. However, not all strictly stationary random processes are ergodic.

A random process is **ergodic in the mean** if

$$\langle X(t) \rangle = \mu_X$$

and **ergodic in the autocorrelation** if

$$\langle X(t)X(t+\tau) \rangle = \phi_{XX}(\tau)$$

## Example (cont'd)

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Recall the random process

$$X(t) = A \cos(2\pi f_c t + \Theta)$$

where  $A$  and  $f_c$  are constants, and  $\Theta$  is assumed to be a uniformly distributed random phase having the pdf

$$p_{\Theta}(\theta) = \begin{cases} 1/(2\pi) , & 0 \leq \theta \leq 2\pi \\ 0 , & \text{elsewhere} \end{cases}$$

The time average mean of  $X(t)$  is

$$\langle X(t) \rangle = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T A \cos(2\pi f_c t + \theta) dt = 0$$

In this example  $\mu_X(t) = E[X(t)] = \langle X(t) \rangle = 0$ , so the random process  $X(t)$  is ergodic in the mean.

N.B. Make sure you understand the difference between the *time average* and *ensemble average*.

## Example (cont'd)

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The time average autocorrelation of  $X(t)$  is

$$\begin{aligned} \langle X(t)X(t+\tau) \rangle &= \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T A^2 \cos(2\pi f_c t + 2\pi f_c \tau + \theta) \cos(2\pi f_c t + \theta) dt \\ &= \lim_{T \rightarrow \infty} \frac{A^2}{4T} \int_{-T}^T [\cos(2\pi f_c \tau) + \cos(4\pi f_c t + 2\pi f_c \tau + 2\theta)] dt \\ &= \frac{A^2}{2} \cos(2\pi f_c \tau) \end{aligned}$$

In this example  $\phi_X(\tau) = E[X(t)X(t+\tau)] = \langle X(t)X(t+\tau) \rangle$ , so the random process  $X(t)$  is ergodic in the autocorrelation.

It follows that the random process  $X(t)$  in this example is *ergodic in the mean and autocorrelation*.

# Example

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Consider the random process shown below.

	$X_1(t) = a$	$P_1 = 1/4$
	$X_2(t) = 0$	$P_2 = 1/2$
	$X_3(t) = -a$	$P_3 = 1/4$

## Example (cont'd)

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For this example, the *ensemble* and *time average* means are, respectively,

$$\begin{aligned}\mu_X &= E[X(t)] = 0 \\ \langle X(t) \rangle &= \begin{cases} a & \text{with probability } 1/4 \\ 0 & \text{with probability } 1/2 \\ -a & \text{with probability } 1/4 \end{cases}\end{aligned}$$

Hence,  $X(t)$  is *not ergodic in the mean*.

The *ensemble* and *time average* autocorrelations are

$$\begin{aligned}\phi_{XX}(\tau) &= E[X(t)X(t+\tau)] = a^2(1/4) + 0(1/2) + (-a)^2(1/4) = a^2/2 \\ \langle X(t)X(t+\tau) \rangle &= \begin{cases} a^2 & \text{with probability } 1/2 \\ 0 & \text{with probability } 1/2 \end{cases}\end{aligned}$$

Hence,  $X(t)$  is *not ergodic in the autocorrelation*.

## Example (cont'd)

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Note that

$$\begin{aligned} \mathbb{E}[\langle X(t) \rangle] &= \mu_X \\ \mathbb{E}[\langle X(t)X(t+\tau) \rangle] &= \phi_{XX}(\tau) \end{aligned}$$

Because of this property  $\langle X(t) \rangle$  and  $\langle X(t)X(t+\tau) \rangle$  are said to provide *unbiased estimates* of  $\mu_X$  and  $\phi_{XX}(\tau)$ , respectively.

# Power Spectral Density

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The power spectral density (psd) of a wide sense stationary random process  $X(t)$  is the Fourier transform of its autocorrelation function, i.e.,

$$\begin{aligned}\Phi_{XX}(f) &= \int_{-\infty}^{\infty} \phi_{XX}(\tau) e^{-j2\pi f\tau} d\tau \\ \phi_{XX}(\tau) &= \int_{-\infty}^{\infty} \Phi_{XX}(f) e^{j2\pi f\tau} df .\end{aligned}$$

We have seen that  $\phi_{XX}(\tau)$  is real and even. Therefore,  $\Phi_{XX}(-f) = \Phi_{XX}(f)$  meaning that  $\Phi_{XX}(f)$  is also real and even.

The total power (ac + dc),  $P$ , in a random process  $X(t)$  is

$$P = E[X^2(t)] = \phi_{XX}(0) = \int_{-\infty}^{\infty} \Phi_{XX}(f) df$$

a famous result known as **Parseval's theorem**.



# Example

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$$X(t) = A \cos(2\pi f_c t + \Theta)$$

where  $A$  and  $f_c$  are constants and

$$p_{\Theta}(\theta) = \begin{cases} \frac{1}{2\pi}, & -\pi \leq \theta \leq \pi \\ 0, & \text{elsewhere} \end{cases}$$

We have seen before that

$$\phi_{XX}(\tau) = \frac{A^2}{2} \cos(2\pi f_c \tau)$$

Hence,

$$\begin{aligned} \Phi_{XX}(f) &= \frac{A^2}{2} \mathcal{F}[\cos(2\pi f_c \tau)] \\ &= \frac{A^2}{4} (\delta(f - f_c) + \delta(f + f_c)) \end{aligned}$$

# Properties of $\Phi_{XX}(f)$

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1.  $\Phi_{XX}(0) = \int_{-\infty}^{\infty} \phi_{XX}(\tau) d\tau$
2.  $\int_{0-}^{0+} \Phi_{XX}(f) df = \text{dc power}$
3.  $\phi_{XX}(0) = \int_{-\infty}^{\infty} \Phi_{XX}(f) df = \text{total power}$
4.  $\Phi_{XX}(f) \geq 0$  for all  $f$ . Power is never negative.
5.  $\Phi_{XX}(f) = \Phi_{XX}(-f)$  (even function) if  $X(t)$  is a real random process.
6.  $\Phi_{XX}(f)$  is always real.

# Discrete-time Random Processes

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Consider a discrete-time real-valued random process  $X_n$ , that consists of an ensemble of discrete-time sample sequences  $\{x_n\}$ .

The ensemble mean of  $X_n$  is

$$\mu_{X_n} = E[X_n] = \int_{-\infty}^{\infty} x_n f_{X_n}(x_n) dx_n$$

The ensemble autocorrelation of  $X_n$  is

$$\phi_{XX}(n, k) = E[X_n X_k] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} X_n X_k f_{X_n, X_k}(x_n, x_k) dx_n dx_k$$

For a wide-sense stationary discrete-time real-valued random process, we have

$$\begin{aligned}\mu_{X_n} &= \mu_X, \quad \forall n \\ \phi_{XX}(n, k) &= \phi_{XX}(n - k)\end{aligned}$$

From Parseval's theorem, the total power in the process  $X_n$  is

$$P = E[X_n^2] = \phi_{XX}(0)$$

# Power Spectrum of Discrete-time RP

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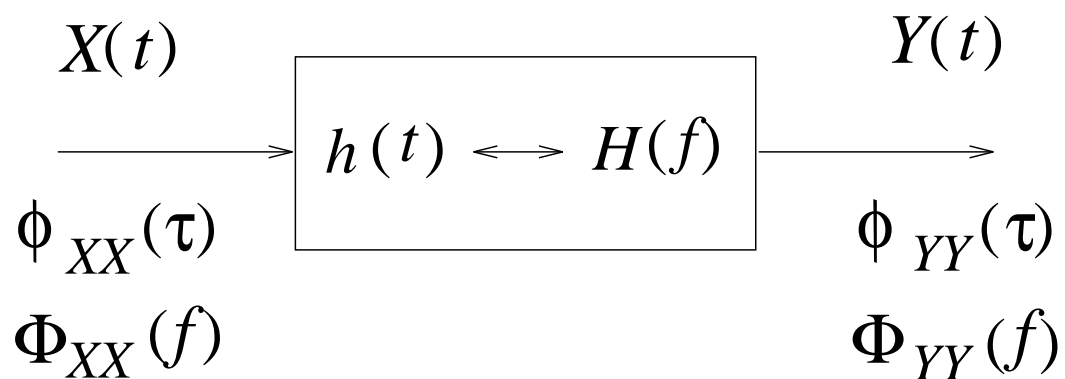
The power spectrum of the real-valued wide-sense stationary discrete-time random process  $X_n$  is the discrete-time Fourier transform of its autocorrelation function, i.e.,

$$\begin{aligned}\Phi_{XX}(f) &= \sum_{n=-\infty}^{\infty} \phi_{XX}(n) e^{-j2\pi f n} \\ \phi_{XX}(n) &= \int_{-1/2}^{1/2} \Phi_{XX}(f) e^{j2\pi f n} df\end{aligned}$$

Observe that the power spectrum  $\Phi_{XX}(f)$  is periodic in frequency  $f$  with a period of unity. In other words  $\Phi_{XX}(f) = \Phi_{XX}(f + k)$ , for  $k = \pm 1, \pm 2, \dots$ . This is a characteristic of any discrete-time sequence. For example, one obtained by sampling a continuous-time random process  $X_n = x(nT_s)$ , where  $T_s$  is the sample period.

# Linear Systems

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# Linear Systems

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Suppose that the input to the linear system (filter)  $h(t)$  is a wide sense stationary random process  $X(t)$ , with mean  $\mu_X$  and autocorrelation  $\phi_{XX}(\tau)$ .

The input and output waveforms are related by the convolution integral

$$Y(t) = \int_{-\infty}^{\infty} h(\tau)X(t - \tau)d\tau \ .$$

Hence,

$$Y(f) = H(f)X(f) \ .$$

The output mean is

$$\mu_Y = \int_{-\infty}^{\infty} h(\tau)E[X(t - \tau)]d\tau = \mu_X \int_{-\infty}^{\infty} h(\tau)d\tau = \mu_X H(0) \ .$$

The mean value of the filter output (dc output) is just the mean value of the filter input (dc input) multiplied by the dc gain of the filter.

# Linear Systems

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The output autocorrelation is

$$\begin{aligned}\phi_{YY}(\tau) &= \text{E}[Y(t)Y(t+\tau)] \\ &= \text{E}\left[\int_{-\infty}^{\infty} h(\beta)X(t-\beta)d\beta \int_{-\infty}^{\infty} h(\alpha)X(t+\tau-\alpha)d\alpha\right] \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} h(\alpha)h(\beta)\text{E}[X(t-\beta)X(t+\tau-\alpha)]d\beta d\alpha \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} h(\alpha)h(\beta)\phi_{XX}(\tau-\alpha+\beta)d\beta d\alpha \\ &= \int_{-\infty}^{\infty} h(\alpha) \int_{-\infty}^{\infty} h(\beta)\phi_{XX}(\tau+\beta-\alpha)d\alpha d\beta \\ &= \left\{\int_{-\infty}^{\infty} h(\beta)\phi_{XX}(\tau+\beta)d\beta\right\} * h(\tau) \\ &= h(-\tau) * \phi_{XX}(\tau) * h(\tau) \ .\end{aligned}$$

Taking transforms, the output psd is

$$\begin{aligned}\Phi_{YY}(f) &= H^*(f)\Phi_{XX}(f)H(f) \\ &= |H(f)|^2 \Phi_{XX}(f) \ .\end{aligned}$$

# Cross-correlation and Cross-covariance

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If  $X(t)$  and  $Y(t)$  are each wide sense stationary and jointly wide sense stationary, then

$$\begin{aligned}\phi_{XY}(t, t + \tau) &= \mathbb{E}[X(t)Y(t + \tau)] = \phi_{XY}(\tau) \\ \boldsymbol{\mu}_{XY}(t, t + \tau) &= \boldsymbol{\mu}_{XY}(\tau) = \phi_{XY}(\tau) - \mu_x \mu_y\end{aligned}$$

The crosscorrelation function  $\phi_{XY}(\tau)$  has the following properties.

1.  $\phi_{XY}(\tau) = \phi_{YX}(-\tau)$
2.  $|\phi_{XY}(\tau)| \leq \frac{1}{2}[\phi_{XX}(0) + \phi_{YY}(0)]$
3.  $|\phi_{XY}(\tau)|^2 \leq \phi_{XX}(0)\phi_{YY}(0)$  if  $X(t)$  and  $Y(t)$  have zero mean.



# Example

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Consider the linear system shown in the previous example. The crosscorrelation between the input process  $X(t)$  and the output process  $Y(t)$  is

$$\begin{aligned}\phi_{YX}(\tau) &= \text{E}[Y(t)X(t+\tau)] \\ &= \text{E}\left[\int_{-\infty}^{\infty} h(\alpha)X(t-\alpha)d\alpha X(t+\tau)\right] \\ &= \int_{-\infty}^{\infty} h(\alpha)\text{E}[X(t-\alpha)X(t+\tau)]d\alpha \\ &= \int_{-\infty}^{\infty} h(\alpha)\phi_{XX}(\tau+\alpha)d\alpha \\ &= h(-\tau) * \phi_{XX}(\tau)\end{aligned}$$

The cross power spectral density is

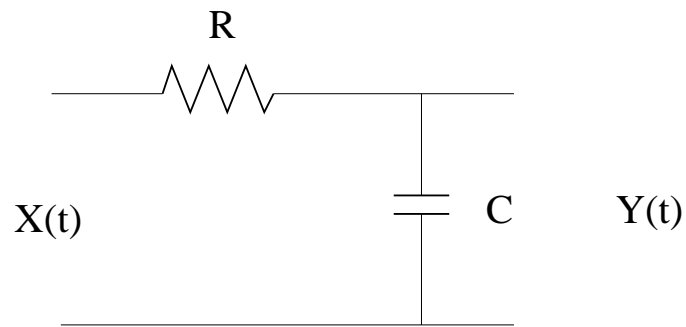
$$\Phi_{YX}(f) = H^*(f)\Phi_{XX}(f)$$

Note also that

$$\phi_{YX}(-\tau) = \phi_{XY}(\tau)$$

# Example

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# Example

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The transfer function of the filter is

$$H(f) = \frac{1}{1 + j2\pi fRC}$$

Suppose  $X(t)$  has autocorrelation function  $\phi_{XX}(\tau) = e^{-\alpha|\tau|}$ . What is  $\phi_{YY}(\tau)$ ?

We have

$$\Phi_{YY}(f) = |H(f)|^2 \Phi_{XX}(f)$$

where

$$\begin{aligned} |H(f)|^2 &= \frac{1}{1 + (2\pi fRC)^2} \\ \Phi_{XX}(f) &= \frac{2\alpha}{\alpha^2 + (2\pi f)^2} \end{aligned}$$

Hence,

$$\Phi_{YY}(f) = \frac{1}{1 + (2\pi fRC)^2} \cdot \frac{2\alpha}{\alpha^2 + (2\pi f)^2}$$

# Example

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Do you remember *partial fractions*? Now you need them!

We write

$$\Phi_{YY}(f) = \frac{A}{\alpha^2 + (2\pi f)^2} + \frac{B}{1 + (2\pi f RC)^2}$$

and solve for  $A$  and  $B$ . We have

$$A(1 + (2\pi f RC)^2) + B(\alpha^2 + (2\pi f)^2) = 2\alpha$$

Clearly,

$$\begin{aligned} A + B\alpha^2 &= 2\alpha \\ A(2\pi f RC)^2 + B(2\pi f)^2 &= 0 \end{aligned}$$

From the second equation

$$A = -\frac{B}{(RC)^2} = -B\beta^2$$

where  $\beta = 1/(RC)$ .

# Example

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Then using the first equation

$$B = \frac{2\alpha}{\alpha^2 - \beta^2}$$

Also,

$$A = -B\beta^2 = -\frac{2\alpha\beta^2}{\alpha^2 - \beta^2}$$

Finally,

$$\Phi_{YY}(f) = \frac{\beta^2}{\beta^2 - \alpha^2} \cdot \frac{2\alpha}{\alpha^2 + (2\pi f)^2} + \frac{\alpha\beta}{\alpha^2 - \beta^2} \cdot \frac{2\beta}{\beta^2 + (2\pi f)^2}$$

Now take inverse Fourier transforms to get

$$\phi_{YY}(\tau) = \frac{\beta^2}{\beta^2 - \alpha^2} \cdot e^{-\alpha|\tau|} + \frac{\alpha\beta}{\alpha^2 - \beta^2} \cdot e^{-\beta|\tau|}$$

# Discrete-time Random Processes

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Consider a wide-sense stationary discrete-time random process  $X_n$  that is input to a discrete-time linear time-invariant filter having impulse response  $h_n$ . The frequency response function of the filter is the discrete time Fourier transform

$$H(f) = \sum_{n=-\infty}^{\infty} h_n e^{-j2\pi f n}$$

The output of the filter is the convolution sum

$$Y_k = \sum_{n=-\infty}^{\infty} h_n X_{k-n}$$

It follows that the output mean is

$$\begin{aligned} \mu_Y = E[Y_k] &= \sum_{n=-\infty}^{\infty} h_n E[X_{k-n}] \\ &= \mu_X \sum_{n=-\infty}^{\infty} h_n \\ &= \mu_X H(0) \end{aligned}$$

# Discrete-time Random Processes

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The autocorrelation function of the output process is

$$\begin{aligned}\phi_{YY}(k) &= E[Y_n Y_{n+k}] \\ &= \sum_{i=-\infty}^{\infty} \sum_{j=-\infty}^{\infty} h_i h_j E[X_{n-i} h_j X_{n+k-j}] \\ &= \sum_{i=-\infty}^{\infty} \sum_{j=-\infty}^{\infty} h_i h_j \phi_{XX}(k - j + i)\end{aligned}$$

By taking the discrete-time Fourier transform of  $\phi_{YY}(k)$  and using the above relationship, we can obtain

$$\Phi_{YY}(f) = \Phi_{XX}(f) |H(f)|^2$$

Again, note in this case that  $\Phi_{YY}(f)$  is periodic in  $f$  with a period of unity.